An $N=2$ worldsheet approach to D-branes in bihermitian geometries: II. The general case

This article has been downloaded from IOPscience. Please scroll down to see the full text article.
JHEP09(2009)105
(http://iopscience.iop.org/1126-6708/2009/09/105)
The Table of Contents and more related content is available

Download details:
IP Address: 80.92.225.132
The article was downloaded on 01/04/2010 at 13:41

Please note that terms and conditions apply.

# An $N=2$ worldsheet approach to D-branes in bihermitian geometries: II. The general case 

Alexander Sevrin, ${ }^{a}$ Wieland Staessens ${ }^{a, 1}$ and Alexander Wijns ${ }^{b, c}$<br>${ }^{a}$ Theoretische Natuurkunde, Vrije Universiteit Brussel and The International Solvay Institutes, Pleinlaan 2, B-1050 Brussels, Belgium<br>${ }^{b}$ NORDITA,<br>Roslagstullsbacken 23, SE-106 91 Stockholm, Sweden<br>${ }^{c}$ Science Institute, University of Iceland, Dunhaga 3, 107 Reykjavik, Iceland<br>E-mail: Alexandre.Sevrin@vub.ac.be, Wieland.Staessens@vub.ac.be, awijns@nordita.org


#### Abstract

We complete the investigation of $N=(2,2)$ supersymmetric nonlinear $\sigma$ models in the presence of a boundary. We study the full bihermitian geometry parameterized by chiral, twisted chiral and semi-chiral superfields and identify the D-brane configurations preserving an $N=2$ worldsheet supersymmetry. Combining twisted with semi-chiral superfields leads to a clearly defined notion of lagrangian and coisotropic branes generalizing lagrangian and coisotropic A-branes on Kähler manifolds to manifolds which are not necessarily Kähler (but still bihermitian). Adding chiral fields complicates the picture and results in hybrid configurations interpolating between lagrangian/coisotropic branes and branes wrapping around a holomorphic cycle. Even here the branes can be viewed as coisotropic submanifolds albeit in a generalized sense. All supersymmetric D-brane configurations are characterized in the context of generalized complex geometry. Duality transformations interchanging the various types of superfields while preserving all supersymmetries are explicitly constructed and provide for a powerful technique to construct various highly non-trivial D-brane configurations. Several explicit examples are given.


Keywords: Superspaces, D-branes, Sigma Models

ArXiv EPRINT: 0908.2756

[^0]
## Contents

1 Introduction ..... 1
$2 \mathrm{~N}=2$ superspace ..... 2
2.1 $N=(2,2)$ supersymmetry in the absence of boundaries ..... 2
2.2 Boundaries and $N=2$ superspace ..... 10
3 Boundary conditions ..... 12
3.1 Unconstrained $N=2$ fields and lagrangian and coisotropic branes ..... 12
3.1.1 Generalities ..... 12
3.1.2 Lagrangian branes ..... 13
3.1.3 Maximally coisotropic branes ..... 14
3.1.4 Coisotropic branes ..... 15
3.2 Chiral $N=2$ fields ..... 16
3.3 The general case ..... 17
3.3.1 Generalized maximally coisotropic branes ..... 17
3.3.2 Generalized lagrangian branes ..... 18
3.4 Embedding in generalized complex geometry ..... 19
3.4.1 Generalized complex submanifols of bihermitian manifolds ..... 19
4 Duality transformations ..... 23
4.1 Dualities without an isometry ..... 23
4.1.1 The four dual semi-chiral formulations ..... 24
4.1.2 The duality between twisted chiral and twisted complex linear fields ..... 25
4.1.3 The duality between chiral and complex linear fields ..... 25
4.2 Dualities with an isometry ..... 25
4.2.1 The duality between a pair of chiral and twisted chiral fields and a semi-chiral multiplet ..... 26
4.2.2 The duality between a chiral and a twisted chiral field ..... 30
5 Examples ..... 33
5.1 The WZW model on $S^{3} \times S^{1}$ and its dual formulation ..... 33
5.2 From D1-branes on $T^{2} \times D$ to D2-branes on $S^{3} \times S^{1}$ ..... 36
5.3 From D3-branes on $T^{2} \times D$ to D2-branes on $S^{3} \times S^{1}$ ..... 37
5.4 From D3-branes on $T^{2} \times D$ to D4-branes on $S^{3} \times S^{1}$ ..... 38
6 Conclusions and discussion ..... 39
A Conventions, notations and identities ..... 42
B $\quad N=1$ non-linear $\sigma$-models ..... 44
C Some geometry ..... 45
C. 1 Generalized complex geometry ..... 45
C.1.1 Example: Kähler structure ..... 46
C. 2 Generalized complex submanifolds ..... 47
C.2.1 Example 1: complex manifolds ..... 48
C.2.2 Example 2: symplectic manifolds ..... 48
C. 3 Poisson structures ..... 49
D Auxiliary fields and boundary conditions ..... 51

## 1 Introduction

The discovery of moduli stabilization [1] led to the recognition that there is a landscape of (metastable) string vacua. This resulted in a highly increased interest in string theory in backgrounds with fluxes. While many results were obtained within the framework of effective field theories (gauged supergravity), a direct stringy approach is desirable. The pure spinor formalism [2] succeeds in doing so, however here developing work remains to be done. On the other hand we do have an alternative description for a subclass of these backgrounds. Indeed non-linear $\sigma$-models in two dimensions with an $N=(2,2)$ supersymmetry - the so-called RNS models - provide a worldsheet description of type II superstrings in backgrounds including general NSNS-fluxes (no RR-fluxes and a constant dilaton however) [3]-[12]. The requirement of $N=(2,2)$ supersymmetry imposes severe restrictions on the allowed geometries. Imposing conformal invariance at the quantum level (the vanishing of the $\beta$-functions) gives further conditions allowing an analysis which potentially surpasses a supergravity one as higher order $\alpha^{\prime}$ corrections are - in principle - calculable.

A manifestly supersymmetric formulation of these models clarifies the geometric structure and greatly facilitates (quantum) calculations. Such a formulation is now known: any $N=(2,2)$ non-linear $\sigma$-model can be parameterized in $N=(2,2)$ superspace in terms of chiral, twisted chiral and semi-chiral superfields [7].

When dealing with backgrounds which contain D-branes one has to consider non-linear $\sigma$-models with boundaries. The presence of boundaries breaks the $N=(2,2)$ worldsheet supersymmetry to an $N=2$ supersymmetry and further enriches the geometric structure. The present paper concludes the study of the classical geometry of these models in a manifestly supersymmetric formulation ( $N=2$ boundary superspace).

While a lot of pioneering work was done on supersymmetric D-brane configurations [13]-[20], the study of a manifestly $N=2$ supersymmetric worldsheet formulation of D-branes started only in [21] where $N=1$ and $N=2$ boundary superspace was set up. This was subsequently applied to the study of A- and B-branes on Kähler manifolds [22]. Contrary to expectations, A-type boundary conditions were indeed possible in $N=2$ superspace. This was then extended to models which include NSNS-fluxes where in first
instance the simplest case - mutually commuting complex structures (or put differently models described in terms of twisted chiral and chiral superfields) - was studied [23]. An interesting observation was that very involved brane configurations, e.g. coisotropic branes, could easily be constructed from simple brane configurations through supersymmetry preserving T-duality transformations.

In the present case we turn our attention to the most general $N=(2,2)$ non-linear $\sigma$ model. In such models the complex structures do not necessarily commute and a complete description needs, besides twisted chiral and chiral superfields, semi-chiral superfields as well. We identify the brane configurations compatible with worldsheet supersymmetry. The most transparant case is where only semi-chiral and twisted chiral superfields are present. Here one finds a very clear and explicit generalization of lagrangian and coisotropic branes on Kähler manifolds to the non-Kähler case. Having models described solely by chiral fields results in B-branes wrapping around holomorphic cycles of Kähler manifolds. The general case - where all three types of superfields are present - interpolates between the two previous cases. Even here the branes can be interpreted as generalized coisotropic submanifolds however in the context of a foliation by symplectic leaves of a Poisson manifold.

In the next section we review $N=(2,2)$ non-linear $\sigma$-models in $N=(2,2)$ superspace. We also introduce boundaries, reducing $N=(2,2)$ superspace to $N=2$ boundary superspace. We identify the three types of superfields in boundary superspace.

Section 3 classifies the boundary conditions compatible with $N=2$ supersymmetry and leads to the identification of the various D-brane configurations. Some of these results were already announced in [24]. The various configurations are interpreted in terms of generalized complex submanifolds of a generalized Kähler manifold.

Section 4 turns to duality transformations which interchange the various types of superfields. After briefly reviewing the duality transformations which do not need isometries we make a thorough study of duality transformations in the presence of isometries.

In section 5 we illustrate our results through several examples. In particular we focus on the non-linear $\sigma$-model with the Hopf surface $S^{3} \times S^{1}$ as target manifold (also known as the Wess-Zumino-Witten model on $\mathrm{SU}(2) \times \mathrm{U}(1))$ where we explicitly construct langrangian D2-branes and coisotropic D4-branes. In order to achieve this we start from the much simpler D1- and D3-brane configurations on $D \times T^{2}$ which we then dualize to the above mentioned D2- and D4-branes on $S^{3} \times S^{1}$.

We end with our conclusions and an outlook on future developments. The first appendix summarizes our conventions. In appendix B we briefly review $N=(1,1)$ and $N=1$ supersymmetric non-linear $\sigma$-models in superspace. Appendix C summarizes some useful notions of generalized complex geometry. In the last appendix we digress on the role of auxiliary fields in T-duality transformations.

## $2 \mathrm{~N}=2$ superspace

## 2.1 $\quad N=(2,2)$ supersymmetry in the absence of boundaries

An $N=(2,2)$ non-linear $\sigma$-model is determined by the following data:

- An even dimensional (target) manifold $\mathcal{M}$. We denote the local coordinates by $X^{a}$, $a \in\{1, \cdots, 2 n\}$.
- A metric $g_{a b}(X)$ on the manifold.
- A closed three-form $H_{a b c}(X)$ on the manifold. Locally we introduce a two-form potential $b_{a b}(X)$ and we write $H_{a b c}=-(3 / 2) \partial_{[a} b_{b c]}$. Obviously the two-form potential is only defined modulo a gauge transformation, $b_{a b} \simeq b_{a b}+\partial_{a} k_{b}-\partial_{b} k_{a}$.
- Two (integrable) complex structures $J_{ \pm b}^{a}(X), J_{ \pm c}^{a} J_{ \pm b}^{c}=-\delta_{b}^{a}$, which are such that the metric is hermitian with respect to both of them: $J_{ \pm a}^{c} J_{ \pm b}^{d} g_{c d}=g_{a b}$.
- The complex structures are covariantly constant though with different connections:

$$
\begin{equation*}
0=\nabla_{c}^{ \pm} J_{ \pm b}^{a} \equiv \partial_{c} J_{ \pm b}^{a}+\Gamma_{ \pm d c}^{a} J_{ \pm b}^{d}-\Gamma_{ \pm b c}^{d} J_{ \pm d}^{a}, \tag{2.1}
\end{equation*}
$$

with the connections $\Gamma_{ \pm}$given by,

$$
\Gamma_{ \pm b c}^{a} \equiv\left\{\begin{array}{l}
a  \tag{2.2}\\
b c
\end{array}\right\} \pm H^{a}{ }_{b c} .
$$

For obvious reasons this type of target manifold geometry is called a bihermitian geometry. Note that if $\left\{\mathcal{M}, g, H, J_{+}, J_{-}\right\}$defines a bihermitian geometry then so does $\left\{\mathcal{M}, g, H, J_{+},-J_{-}\right\}$. This is a local realization of mirror symmetry.

The hermiticity of the metric with respect to the two complex structures implies the existence of two two-forms,

$$
\begin{equation*}
\omega_{a b}^{ \pm}=-\omega_{b a}^{ \pm} \equiv-g_{a c} J_{ \pm b}^{c} \tag{2.3}
\end{equation*}
$$

In general they are not closed. Using eq. (2.1), one shows that,

$$
\begin{equation*}
\omega_{[a b, c]}^{ \pm}= \pm 2 J_{ \pm[a}^{d} H_{b c] d}= \pm(2 / 3) J_{ \pm a}^{d} J_{ \pm b}^{e} J_{ \pm c}^{f} H_{d e f}, \tag{2.4}
\end{equation*}
$$

where for the last step one uses the fact that the Nijenhuis tensors ${ }^{1}$ vanish. When the torsion vanishes, the two-forms are closed and this reduces to the usual Kähler geometry. Later in this section we will show that even when the torsion does not vanish one might have - under special circumstances - closed two-forms defined out of the metric $g$ and the complex structures $J_{ \pm}$.

From a local point of view, the equations above might be viewed as a set of differential and algebraic equations which should be solved. For a single complex structure, say $J_{+}$, this is indeed easily done. Going to complex coordinates $Z^{A}$ and $Z^{\bar{A}}, a \in\{1, \cdots, n\}$, where $J_{+}$assumes its canonical form, $J_{+}^{A}=i \delta_{B}^{A}, J_{+}^{\bar{A}}=-i \delta_{B}^{A}, J_{+}^{A} \bar{B}=J_{+}^{\bar{A}}=0$, one

[^1]immediately finds using eq. (2.1) that all conditions are solved provided metric and torsion potential are parameterized in terms of a (locally defined) one form $m_{A}$ :
\[

$$
\begin{align*}
g_{A \bar{B}} & =\frac{1}{2}\left(\partial_{A} m_{\bar{B}}+\partial_{\bar{B}} m_{A}\right), \\
b_{A B} & =-\frac{1}{2}\left(\partial_{A} m_{B}-\partial_{B} m_{A}\right), \quad b_{\bar{A} \bar{B}}=-\frac{1}{2}\left(\partial_{\bar{A}} m_{\bar{B}}-\partial_{\bar{B}} m_{\bar{A}}\right), \tag{2.5}
\end{align*}
$$
\]

and all other components zero. There is a residual freedom in defining the one-form $m_{A}$ : $m_{A} \simeq m_{A}+n_{A}+i \partial_{A} f$, where $n_{A}$ is holomorphic - $\partial_{\bar{B}} n_{A}=0-$ and $f$ is an arbitrary real function. The precise form of $b$ is obviously gauge dependent, only the torsion 3 -form $H_{A B \bar{C}}=\partial_{\bar{C}}\left(\partial_{A} m_{B}-\partial_{B} m_{A}\right) / 4$ has an invariant meaning.

Solving the conditions for both complex structures $J_{+}$and $J_{-}$simultaneously is more involved. Nonetheless - as the off-shell description of these models in $N=(2,2)$ superspace is known [7] (building on earlier work in [8]-[11]) - it can be done in terms of a single real potential. The construction starts from the observation that the terms in the algebra which do not close off-shell are all proportional to the commutator of the two complex structures $\left[J_{+}, J_{-}\right]$. As a consequence one expects that additional auxiliary fields will be needed in the direction of coker $\left[J_{+}, J_{-}\right]$while this will not be the case for $\operatorname{ker}\left[J_{+}, J_{-}\right]=\operatorname{ker}\left(J_{+}-J_{-}\right) \oplus \operatorname{ker}\left(J_{+}+J_{-}\right)$.

Decomposing the tangent space as $\operatorname{ker}\left(J_{+}-J_{-}\right) \oplus \operatorname{ker}\left(J_{+}+J_{-}\right) \oplus \operatorname{coker}\left[J_{+}, J_{-}\right]$one shows that the first subspace gets parameterized by chiral, the second by twisted chiral and the last one by semi-chiral $N=(2,2)$ superfields [7]. The three types of superfields are defined by the following constraints: ${ }^{2}$

Semi-chiral superfields: $l^{\tilde{\alpha}}, l^{\bar{\alpha}}, r^{\tilde{\mu}}, r^{\bar{\mu}}, \quad \tilde{\alpha}, \tilde{\tilde{\alpha}}, \tilde{\mu}, \overline{\tilde{\mu}} \in\left\{1, \cdots n_{s}\right\}$,

$$
\begin{equation*}
\overline{\mathbb{D}}_{+} l^{\tilde{\alpha}}=\mathbb{D}_{+} l^{\overline{\tilde{\alpha}}}=\overline{\mathbb{D}} \_r^{\tilde{\mu}}=\mathbb{D} \_r^{\overline{\tilde{\mu}}}=0 . \tag{2.6}
\end{equation*}
$$

Twisted chiral superfields: $w^{\mu}, w^{\bar{\mu}}, \quad \mu, \bar{\mu} \in\left\{1, \cdots n_{t}\right\}$,

$$
\begin{equation*}
\overline{\mathbb{D}}_{+} w^{\mu}=\mathbb{D}_{-} w^{\mu}=\mathbb{D}_{+} w^{\bar{\mu}}=\overline{\mathbb{D}}_{-} w^{\bar{\mu}}=0 . \tag{2.7}
\end{equation*}
$$

Chiral superfields: $z^{\alpha}, z^{\bar{\alpha}}, \quad \alpha, \bar{\alpha} \in\left\{1, \cdots n_{c}\right\}$,

$$
\begin{equation*}
\overline{\mathbb{D}}_{ \pm} z^{\alpha}=\mathbb{D}_{ \pm} z^{\bar{\alpha}}=0 . \tag{2.8}
\end{equation*}
$$

It is clear that chiral and twisted chiral $N=(2,2)$ superfields have the same number of components as $N=(1,1)$ superfields while semi-chiral $N=(2,2)$ superfields have twice as many, half of which are - from $N=(1,1)$ superspace point of view - auxiliary.

Note that given $\{\mathcal{M}, g, H\}$, the choice for $J_{+}$and $J_{-}$is not necessarily unique. Consider e.g. a hyper-Kähler manifold (so $H=0$, this discussion was given in [10]) where one has three complex structures $J_{i}, i \in\{1,2,3\}$, satisfying $J_{i} J_{j}=-\delta_{i j}+\varepsilon_{i j k} J_{k}$. If one chooses $J_{+}=J_{-}=\sin \theta \cos \phi J_{1}+\sin \theta \sin \phi J_{2}+\cos \theta J_{3}$ with $\phi \in[0,2 \pi], \theta \in[0, \pi]$, one

[^2]gets a description in terms of chiral fields only. Choosing $J_{+}=-J_{-}=\sin \theta \cos \phi J_{1}+$ $\sin \theta \sin \phi J_{2}+\cos \theta J_{3}$, gives a description in terms of twisted chiral fields. Finally, one could also put $J_{+}=J_{1}$ and $J_{-}=\cos \phi J_{2}+\sin \phi J_{3}$ in which case $\left\{J_{+}, J_{-}\right\}=0$ which implies $\operatorname{ker}\left[J_{+}, J_{-}\right]=\emptyset$. As a consequence the model is now formulated in terms of semichiral superfields.

The most general action involving these superfields and consistent with dimensions is given by,

$$
\begin{equation*}
\mathcal{S}=4 \int d^{2} \sigma d^{2} \theta d^{2} \hat{\theta} V(l, \bar{l}, r, \bar{r}, w, \bar{w}, z, \bar{z}) \tag{2.9}
\end{equation*}
$$

where the Lagrange density $V(l, \bar{l}, r, \bar{r}, w, \bar{w}, z, \bar{z})$ is an arbitrary real function of the semichiral, the twisted chiral and the chiral superfields. It is defined modulo a generalized Kähler transformation,

$$
\begin{equation*}
V \rightarrow V+F(l, w, z)+\bar{F}(\bar{l}, \bar{w}, \bar{z})+G(\bar{r}, w, \bar{z})+\bar{G}(r, \bar{w}, z) \tag{2.10}
\end{equation*}
$$

These generalized Kähler transformations are essential for the global consistency of the model, see e.g. [25]. Reducing the action in eq. (2.9) to $N=(1,1)$ superspace one finds that $\hat{D}_{-} l^{\tilde{\alpha}}$ and $\hat{D}_{+} r^{\tilde{\mu}}$ (and their complex conjugates) are auxiliary fields. Before doing so, let us introduce some notation. We write,

$$
M_{A B}=\left(\begin{array}{cc}
V_{a b} & V_{a \bar{b}}  \tag{2.11}\\
V_{\bar{a} b} & V_{\bar{a} \bar{b}}
\end{array}\right)
$$

where, $(A, a) \in\{(l, \tilde{\alpha}),(r, \tilde{\mu}),(w, \mu),(z, \alpha)\}$ and $(B, b) \in\{(l, \tilde{\beta}),(r, \tilde{\nu}),(w, \nu),(z, \beta)\}$. In this way e.g. we get that $M_{z r}$ is the $2 n_{c} \times 2 n_{s}$ matrix given by,

$$
M_{z r}=\left(\begin{array}{cc}
V_{\alpha \tilde{\nu}} & V_{\alpha \overline{\tilde{\nu}}}  \tag{2.12}\\
V_{\bar{\alpha} \tilde{\nu}} & V_{\bar{\alpha} \tilde{\nu}}
\end{array}\right) .
$$

Note that $M_{A B}^{T}=M_{B A}$. We also introduce the matrix $\mathbb{P}$,

$$
\mathbb{P} \equiv\left(\begin{array}{cc}
\mathbf{1} & 0  \tag{2.13}\\
0 & -\mathbf{1}
\end{array}\right)
$$

with 1 the unit matrix and using this we write,

$$
\begin{equation*}
C_{A B} \equiv \mathbb{P} M_{A B}-M_{A B} \mathbb{P}, \quad A_{A B} \equiv \mathbb{P} M_{A B}+M_{A B} \mathbb{P} \tag{2.14}
\end{equation*}
$$

Using this notation one obtains - after elimination of the auxiliary fields - the complex structures,

$$
\begin{align*}
J_{+} & =\left(\begin{array}{cccc}
i \mathbb{P} & 0 & 0 & 0 \\
i M_{l r}^{-1} C_{l l} & i M_{l r}^{-1} \mathbb{P} M_{l r} & i M_{l r}^{-1} C_{l w} & i M_{l r}^{-1} C_{l z} \\
0 & 0 & i \mathbb{P} & 0 \\
0 & 0 & 0 & i \mathbb{P}
\end{array}\right) \\
J_{-} & =\left(\begin{array}{cccc}
i M_{r l}^{-1} \mathbb{P} M_{r l} & i M_{r l}^{-1} C_{r r} & i M_{r l}^{-1} A_{r w} & i M_{r l}^{-1} C_{r z} \\
0 & i \mathbb{P} & 0 & 0 \\
0 & 0 & -i \mathbb{P} & 0 \\
0 & 0 & 0 & i \mathbb{P}
\end{array}\right) \tag{2.15}
\end{align*}
$$

where we labeled rows and columns in the order $l, \bar{l}, r, \bar{r}, w, \bar{w}, z, \bar{z}$. Note that neither of them is in the canonical (diagonal) form. One easily shows [10] that making a coordinate transformation which replaces $r^{\tilde{\mu}}$ and $r^{\tilde{\tilde{\mu}}}$ by $V_{\tilde{\alpha}}$ and $V_{\tilde{\tilde{\alpha}}}$ resp. while keeping the other coordinates as they are, diagonalizes $J_{+}$. Similarly, a coordinate transformation which goes from $l^{\tilde{\alpha}}$ and $l^{\overline{\tilde{\alpha}}}$ to $V_{\tilde{\mu}}$ and $V_{\tilde{\tilde{\mu}}}$ and keeping the other coordinates fixed diagonalizes $J_{-}$. This allows one to reinterpret the generalized Kähler potential as the generating functional for a canonical transformation bringing one from a coordinate system where $J_{+}$assumes its standard diagonal form to another coordinate system where $J_{-}$has its canonical form (and vice-versa) [7].

From the second order action one reads off the metric $g$ and the torsion potential $b$. We write both of them together $e=g+b$ with $e$ given by,

$$
e=\frac{1}{2} J_{+}^{T}\left(\begin{array}{cccc}
0 & M_{l r} & M_{l w} & M_{l z}  \tag{2.16}\\
-M_{r l} & 0 & 0 & 0 \\
0 & M_{w r} & M_{w w} & M_{w z} \\
0 & M_{z r} & M_{z w} & M_{z z}
\end{array}\right) J_{-}+\frac{1}{4}\left(\begin{array}{cccc}
0 & 0 & -M_{l w} & M_{l z} \\
0 & 0 & -M_{r w} & M_{r z} \\
-M_{w l} & -M_{w r} & -2 M_{w w} & 0 \\
M_{z l} & M_{z r} & 0 & 2 M_{z z}
\end{array}\right) .
$$

We will give a more elegant expression for the metric and torsion potential later in this section. However, when only semi-chiral fields are present, the expressions for the metric and torsion potential following from eq. (2.16) greatly simplify,

$$
\begin{align*}
g & =\frac{1}{4}\left(\begin{array}{cc}
0 & M_{l r} \\
-M_{r l} & 0
\end{array}\right)\left[J_{+}, J_{-}\right] \\
b & =\frac{1}{4}\left(\begin{array}{cc}
0 & M_{l r} \\
-M_{r l} & 0
\end{array}\right)\left\{J_{+}, J_{-}\right\} . \tag{2.17}
\end{align*}
$$

Similarly, if only twisted chiral and chiral fields are present, the metric and torsion potential following from eq. (2.16) are given by,

$$
\begin{equation*}
g_{\alpha \bar{\beta}}=+V_{\alpha \bar{\beta}}, \quad g_{\mu \bar{\nu}}=-V_{\mu \bar{\nu}}, \quad b_{\alpha \nu}=+\frac{1}{2} V_{\alpha \nu}, \quad b_{\alpha \bar{\nu}}=-\frac{1}{2} V_{\alpha \bar{\nu}} \tag{2.18}
\end{equation*}
$$

and complex conjugate. Note that as we are not yet considering boundaries, $b$ is only defined modulo a gauge transformation. The relevant gauge invariant object is the torsion 3 -form $H \sim d b$ whose explicit form is unfortunately in general rather involved.

We already noted the existence of the "local mirror transform", $\left\{\mathcal{M}, g, H, J_{+}, J_{-}\right\} \rightarrow$ $\left\{\mathcal{M}, g, H, J_{+},-J_{-}\right\}$. In superspace this is simply realized by,

$$
\begin{equation*}
V(l, \bar{l}, r, \bar{r}, w, \bar{w}, z, \bar{z}) \rightarrow-V(l, \bar{l}, \bar{r}, r, z, \bar{z}, w, \bar{w}) \tag{2.19}
\end{equation*}
$$

Moreover, let us remark that depending on the field content one can have several twoforms which - using the conditions which guarantee the existence of an $N=(2,2)$ bulk supersymmetry - can be shown to be closed and which are linear in the generalized Kähler potential.

- There are no chiral fields, so $\operatorname{ker}\left(J_{+}-J_{-}\right)=\emptyset$. Then,

$$
\begin{equation*}
\Omega_{a b}^{(-)} \equiv 2 g_{a c}\left(\left(J_{+}-J_{-}\right)^{-1}\right)^{c}{ }_{b}, \tag{2.20}
\end{equation*}
$$

is a closed form. It is linear in the generalized Kähler potential and it is explicitely given by,

$$
\Omega^{(-)}=-\frac{i}{2}\left(\begin{array}{ccc}
C_{l l} & A_{l r} & C_{l w}  \tag{2.21}\\
-A_{r l} & -C_{r r} & -A_{r w} \\
C_{w l} & A_{w r} & C_{w w}
\end{array}\right),
$$

where the matrices $C$ and $A$ were defined in eq. (2.14). We used a basis $(l, \bar{l}, r, \bar{r}, w, \bar{w})$. When only twisted chiral fields are present we have that $J \equiv J_{+}=-J_{-}$, the geometry becomes Kähler and $\Omega^{(-)}$reduces to the usual Kähler two-form, $\Omega_{a b}^{(-)}=-g_{a c} J^{c}{ }_{b}$. The two-form $\Omega^{(-)}$has generically no well defined holomorphicity properties with respect to either $J_{+}$or $J_{-}$. One finds,

$$
\begin{equation*}
\Omega_{a c}^{(-)} J_{ \pm b}^{c}=-\Omega_{b c}^{(-)} J_{\mp a}^{c} . \tag{2.22}
\end{equation*}
$$

Having the two-form $\Omega^{(-)}$and the complex structures $J_{ \pm}$allows one to neatly characterize the remainder of the geometry. One finds,

$$
\begin{align*}
g_{a b} & =+\frac{1}{2} \Omega_{a c}^{(-)}\left(J_{+}-J_{-}\right)^{c}{ }_{b}, \\
b_{a b} & =-\frac{1}{2} \Omega_{a c}^{(-)}\left(J_{+}+J_{-}\right)^{c}, \tag{2.23}
\end{align*}
$$

where $b$ is equivalent - modulo a gauge transformation - to the previously given expression (i.e. we still have $H=d b$ ).

- There are no twisted chiral fields, so $\operatorname{ker}\left(J_{+}+J_{-}\right)=\emptyset$. Then,

$$
\begin{equation*}
\Omega_{a b}^{(+)} \equiv 2 g_{a c}\left(\left(J_{+}+J_{-}\right)^{-1}\right)^{c}{ }_{b}, \tag{2.24}
\end{equation*}
$$

is a closed form. Again it is linear in the generalized Kähler potential,

$$
\Omega^{(+)}=\frac{i}{2}\left(\begin{array}{lll}
C_{l l} & C_{l r} & C_{l z}  \tag{2.25}\\
C_{r l} & C_{r r} & C_{r z} \\
C_{z l} & C_{z r} & C_{z z}
\end{array}\right),
$$

where we used a basis $(l, \bar{l}, r, \bar{r}, z, \bar{z})$. When no semi-chiral fields are present we get $J \equiv J_{+}=J_{-}$and the geometry becomes Kähler with $\Omega^{(+)}$being precisely the Kähler two-form. Here as well one finds that $\Omega^{(+)}$has no particular properties with respect to either $J_{+}$or $J_{-}$,

$$
\begin{equation*}
\Omega_{a c}^{(+)} J_{ \pm b}^{c}=\Omega_{b c}^{(+)} J_{\mp a}^{c} . \tag{2.26}
\end{equation*}
$$

As before we can express the metric and the torsion potential in terms of the closed two-form and the complex structures,

$$
\begin{align*}
g_{a b} & =+\frac{1}{2} \Omega_{a c}^{(+)}\left(J_{+}+J_{-}\right)^{c}{ }_{b}, \\
b_{a b} & =-\frac{1}{2} \Omega_{a c}^{(+)}\left(J_{+}-J_{-}\right)^{c}{ }_{b}, \tag{2.27}
\end{align*}
$$

where again it should be noted that $b$ is only defined modulo a gauge transformation.

- There are only semi-chiral fields, so $\operatorname{ker}\left[J_{+}, J_{-}\right]=\emptyset$. Then both $\Omega^{(-)}$and $\Omega^{(+)}$exist. On top of that we have that,

$$
\begin{equation*}
\Omega_{a b}^{( \pm)} \equiv 2 g_{a c}\left(\left[J_{+}, J_{-}\right]^{-1}\right)^{c}{ }_{b} \tag{2.28}
\end{equation*}
$$

is a closed two-form as well. In terms of the generalized Kähler potential it is given by,

$$
\Omega^{( \pm)}=\frac{1}{2}\left(\begin{array}{cc}
0 & M_{l r}  \tag{2.29}\\
-M_{r l} & 0
\end{array}\right),
$$

where we used a basis $(l, \bar{l}, r, \bar{r})$. In this case we find that $\Omega^{( \pm)}$is a $(2,0)+(0,2)$ two-form with respect to both $J_{+}$and $J_{-}$,

$$
\begin{equation*}
\Omega_{a c}^{( \pm)} J_{+b}^{c}=-\Omega_{b c}^{( \pm)} J_{+a}^{c}, \quad \Omega_{a c}^{( \pm)} J_{-b}^{c}=-\Omega_{b c}^{( \pm)} J_{-a}^{c} . \tag{2.30}
\end{equation*}
$$

The relation with $\Omega^{(-)}$and $\Omega^{(+)}$is explicitly given by,

$$
\begin{equation*}
\Omega^{(-)}=-\Omega^{( \pm)}\left(J_{+}+J_{-}\right), \quad \Omega^{(+)}=+\Omega^{( \pm)}\left(J_{+}-J_{-}\right) . \tag{2.31}
\end{equation*}
$$

Finally, let us return to the general case where semi-chiral, twisted chiral and chiral superfields are simultaneously present. The expressions in eqs. (2.23) and (2.27) suggest the following parameterization for $g$ and $b$,

$$
\begin{align*}
g_{a b} & =+\frac{1}{2} \Omega_{+a c} J_{+b}^{c}+\frac{1}{2} \Omega_{-a c} J_{-b}^{c}, \\
b_{a b} & =-\frac{1}{2} \Omega_{+a c} J_{+b}^{c}+\frac{1}{2} \Omega_{-a c} J_{-b}^{c}, \tag{2.32}
\end{align*}
$$

where $\Omega_{ \pm}$are two-tensors with a priory no particular (symmetry) properties. Through a suitable gauge choice for $b$ one can always turn either $\Omega_{+}$or $\Omega_{-}$into a closed two-form as can be verified for e.g. $\Omega_{+}$using the expressions for $g$ and $b$ given in eq. (2.5). Using those one finds that $\Omega_{+}$can be written as $\Omega_{+a b}=\partial_{a} k_{b}-\partial_{b} k_{a}$ with $k_{A}=-(i / 2) m_{A}$ and $k_{\bar{A}}=(i / 2) m_{\bar{A}}$. However the other $\Omega$ will in general not be a two-form. An explicit example of this is the case where only twisted chiral and chiral superfields are present. The oneform used in eq. (2.5) is then explicitly given by $m_{\alpha}=V_{\alpha}$ and $m_{\mu}=-V_{\mu}$ (and complex conjugate). Using this one easily verifies that $\Omega_{+}$is a closed two-form while $\Omega_{-}$is neither anti-symmetric nor symmetric.

Choosing a gauge for $b$ such that $\Omega_{+}$is a closed two-form, given by,

$$
\Omega_{+}=-\frac{i}{2}\left(\begin{array}{cccc}
C_{l l} & A_{l r} & C_{l w} & A_{l z}  \tag{2.33}\\
-A_{r l} & -C_{r r} & -A_{r w} & -C_{r z} \\
C_{w l} & A_{w r} & C_{w w} & A_{w z} \\
-A_{z l} & -C_{z r} & -A_{z w} & -C_{z z}
\end{array}\right)
$$

with respect to the basis $(l, \bar{l}, r, \bar{r}, w, \bar{w}, z, \bar{z})$, one finds that $\Omega_{-}$is generically neither antisymmetric nor symmetric and it can not be expressed in terms of linear derivatives of the potential. It is explicitly given by,

$$
\Omega_{-}=\frac{i}{2}\left(\begin{array}{cccc}
C_{l l} & A_{l r} & C_{l w} & A_{l z}  \tag{2.34}\\
-A_{r l} & -C_{r r} & -A_{r w} & -C_{r z} \\
C_{w l} & A_{w r} & C_{w w} & A_{w z} \\
C_{z l}+Z_{z l} & C_{z r}+Z_{z r} & A_{z w}+Z_{z w} & C_{z z}+Z_{z z}
\end{array}\right)
$$

where we have,

$$
\begin{align*}
Z_{z l} & =-2 M_{z l} M_{r l}^{-1} \mathbb{P} M_{r l}  \tag{2.35}\\
Z_{z r} & =+2 M_{z l} M_{r l}^{-1} \mathbb{P} C_{r r} \mathbb{P}  \tag{2.36}\\
Z_{z w} & =-2 M_{z l} M_{r l}^{-1} \mathbb{P} A_{r w} \mathbb{P}  \tag{2.37}\\
Z_{z z} & =+2 M_{z l} M_{r l}^{-1} \mathbb{P} C_{r z} \mathbb{P} \tag{2.38}
\end{align*}
$$

Locally we can write $2 \Omega_{+a b}=\partial_{a} B_{b}-\partial_{b} B_{a}$ where $B_{a}=i\left(V_{l},-V_{\bar{l}},-V_{r}, V_{\bar{r}}\right.$, $\left.V_{w},-V_{\bar{w}},-V_{z}, V_{\bar{z}}\right)$. When there are no chiral fields present, $\Omega_{ \pm}$reduces to $\pm \Omega^{(-)}$. We thus reproduce the situation defined in eq. (2.20) and subsequent relations.

However, using a different gauge choice for $b$ one makes $\Omega_{+}$non-linear in $V$ and $\Omega_{-}$a closed two-form,

$$
\Omega_{-}=\frac{i}{2}\left(\begin{array}{cccc}
C_{l l} & C_{l r} & C_{l w} & C_{l z}  \tag{2.39}\\
C_{r l} & C_{r r} & C_{r w} & C_{r z} \\
C_{w l} & C_{w r} & C_{w w} & C_{w z} \\
C_{z l} & C_{z r} & C_{z w} & C_{z z}
\end{array}\right)
$$

w.r.t. the basis $(l, \bar{l}, r, \bar{r}, w, \bar{w}, z, \bar{z})$. We get for $\Omega_{+}$now,

$$
\Omega_{+}=\frac{i}{2}\left(\begin{array}{cccc}
C_{l l} & C_{l r} & C_{l w} & C_{l z}  \tag{2.40}\\
C_{r l} & C_{r r} & C_{r w} & C_{r z} \\
-C_{w l}+W_{w l} & -A_{w r}+W_{w r} & -C_{w w}+W_{w w} & -C_{w z}+W_{w z} \\
C_{z l} & C_{z r} & C_{z w} & C_{z z}
\end{array}\right) \text {, }
$$

with,

$$
\begin{align*}
W_{w l} & =-2 M_{w r} M_{l r}^{-1} \mathbb{P} C_{l l} \mathbb{P},  \tag{2.41}\\
W_{w r} & =+2 M_{w r} M_{l r}^{-1} \mathbb{P} M_{l r},  \tag{2.42}\\
W_{w w} & =-2 M_{w r} M_{l r}^{-1} \mathbb{P} C_{l w} \mathbb{P},  \tag{2.43}\\
W_{w z} & =-2 M_{w r} M_{l r}^{-1} \mathbb{P} C_{l z} \mathbb{P} . \tag{2.44}
\end{align*}
$$

In absence of twisted chiral fields, $\Omega_{ \pm}$reduces to $\Omega^{(+)}$, which yields the same relations as in eq. (2.24) and subsequent expressions.

We stress once more that while the introduction of the two-form $\Omega_{+}$will turn out to be most useful, it is not globally well defined as its precise form explicitly depends on the gauge choice for $b$.

### 2.2 Boundaries and $N=2$ superspace

We now introduce a boundary in $N=(2,2)$ superspace which breaks half of the supersymmetries, reducing $N=(2,2)$ to $N=2$. The boundary ${ }^{3}$ is defined by $\sigma=0$, $\theta^{\prime} \equiv\left(\theta^{+}-\theta^{-}\right) / 2=0$ and $\hat{\theta}^{\prime} \equiv\left(\hat{\theta}^{+}-\hat{\theta}^{-}\right) / 2=0$.

When passing to $N=2$ superspace, we get the following structure for the superfields:
Semi-chiral superfields: $l^{\tilde{\alpha}}, l^{\overline{\tilde{\alpha}}}, r^{\tilde{\mu}}, r^{\overline{\tilde{\mu}}}, \mathbb{D}^{\prime} l^{\tilde{\alpha}}, \overline{\mathbb{D}^{\prime}} l^{\bar{\alpha}}, \mathbb{D}^{\prime} r^{\tilde{\mu}}, \overline{\mathbb{D}^{\prime}} r^{\overline{\tilde{\mu}}}$ are unconstrained $N=2$ superfields. The remaining components are determined by

$$
\begin{equation*}
\overline{\mathbb{D}}^{\prime} l^{\tilde{\alpha}}=-\overline{\mathbb{D}} l^{\tilde{\alpha}}, \quad \mathbb{D}^{\prime} l^{\overline{\tilde{\alpha}}}=-\mathbb{D} l^{\overline{\tilde{\alpha}}}, \quad \overline{\mathbb{D}}^{\prime} r^{\tilde{\mu}}=+\overline{\mathbb{D}} r^{\tilde{\mu}}, \quad \mathbb{D}^{\prime} r^{\overline{\tilde{\mu}}}=+\mathbb{D} r^{\overline{\tilde{\mu}}} . \tag{2.45}
\end{equation*}
$$

Reducing the action to $N=1$ superspace, one finds that $\mathbb{D}^{\prime} l^{\tilde{\alpha}}, \overline{\mathbb{D}^{\prime}} l^{\bar{\alpha}}, \mathbb{D}^{\prime} r^{\tilde{\mu}}$ and $\overline{\mathbb{D}}^{\prime} r^{\bar{\mu}}$ are all auxiliary.

Twisted chiral superfields: $w^{\mu}, w^{\bar{\mu}}$ are unconstrained $N=2$ superfields. The other components are determined by,

$$
\begin{equation*}
\mathbb{D}^{\prime} w^{\mu}=+\mathbb{D} w^{\mu}, \quad \overline{\mathbb{D}}^{\prime} w^{\mu}=-\overline{\mathbb{D}} w^{\mu}, \quad \mathbb{D}^{\prime} w^{\bar{\mu}}=-\mathbb{D} w^{\bar{\mu}}, \quad \overline{\mathbb{D}^{\prime}} w^{\bar{\mu}}=+\overline{\mathbb{D}} w^{\bar{\mu}} . \tag{2.46}
\end{equation*}
$$

Chiral superfields: $z^{\alpha}, z^{\bar{\alpha}}, \mathbb{D}^{\prime} z^{\alpha}, \overline{\mathbb{D}}^{\prime} z^{\bar{\alpha}}$ are constrained $N=2$ superfields. They satisfy,

$$
\begin{align*}
& \overline{\mathbb{D}} z^{\alpha}=\mathbb{D} z^{\bar{\alpha}}=0, \\
& \overline{\mathbb{D} \mathbb{D}^{\prime} z^{\alpha}}=-2 i \partial_{\sigma} z^{\alpha}, \quad \mathbb{D} \overline{\mathbb{D}}^{\prime} z^{\bar{\alpha}}=-2 i \partial_{\sigma} z^{\bar{\alpha}} . \tag{2.47}
\end{align*}
$$

[^3]The other components are fixed by,

$$
\begin{equation*}
\overline{\mathbb{D}}^{\prime} z^{\alpha}=\mathbb{D}^{\prime} z^{\bar{\alpha}}=0 . \tag{2.48}
\end{equation*}
$$

Concluding: viewed from the boundary, both semi-chiral and twisted chiral superfields are very similar as they both give rise to unconstrained superfields. Chiral fields on the other hand remain constrained (chiral) on the boundary.

One verifies that the difference between the two measures $\int d^{2} \sigma D_{+} D_{-} \hat{D}_{+} \hat{D}_{-}$and $\int d^{2} \sigma D \hat{D} D^{\prime} \hat{D}^{\prime}$ is just a boundary term. So the most general $N=2$ invariant action which reduces to the usual action when boundaries are absent is,

$$
\begin{equation*}
\mathcal{S}=-\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime} V(X, \bar{X})+i \int d \tau d^{2} \theta W(X, \bar{X}), \tag{2.49}
\end{equation*}
$$

with $V(X, \bar{X})$ and $W(X, \bar{X})$ real functions of the semi-chiral, the twisted chiral and the chiral superfields. The generalized Kähler potential $V$ is arbitrary but the dependence of the boundary potential on the semi-chiral and twisted chiral fields will be determined by the boundary conditions as we will show later on. The action is still invariant under the generalized Kähler transformations eq. (2.10) provided the boundary potential $W$ transforms as well,

$$
\begin{equation*}
W \rightarrow W-i(F(l, w, z)-\bar{F}(\bar{l}, \bar{w}, \bar{z}))-i(G(\bar{r}, w, \bar{z})-\bar{G}(r, \bar{w}, z)) . \tag{2.50}
\end{equation*}
$$

This implies that $(V+i W)_{\bar{\mu}},(V+i W)_{\overline{\tilde{\alpha}}}$ and $(V+i W)_{\tilde{\mu}}$ (and their complex conjugates) are invariant expressions. Note that when dealing with the global definition of the geometry, eqs. (2.10) and (2.50) play an important role. Indeed when going from one coordinate system to another on the overlap of two neighbourhoods one finds that the generalized Kähler potential is invariant modulo a generalized Kähler transformation eq. (2.10). The requirement that the boundary potential should transform as in eq. (2.50) imposes then severe restrictions on the form of $W$. An explicit example of this can be found in [23].

Reducing the action, eq. (2.49) to $N=1$ boundary superspace yields,

$$
\begin{equation*}
\mathcal{S}=\mathcal{S}_{\text {bulk }}+i \int d \tau d \theta\left(B_{a}+\partial_{a} W\right) \hat{D} X^{a} \tag{2.51}
\end{equation*}
$$

where we denoted the superfields collectively by $X$. The locally defined one-form $B$ satisfies $2 \Omega_{+a b}=\partial_{a} B_{b}-\partial_{b} B_{a}$, where $\Omega_{+}$was given in eq. (2.33). Upon eliminating the auxiliary fields one finds for $\mathcal{S}_{\text {bulk }}$,

$$
\begin{equation*}
\mathcal{S}_{b u l k}=\int d^{2} \sigma d \theta D^{\prime}\left(2 D X^{a} D^{\prime} X^{b} g_{a b}-D X^{a} D X^{b} b_{a b}+D^{\prime} X^{a} D^{\prime} X^{b} b_{a b}\right) \tag{2.52}
\end{equation*}
$$

where $g$ and $b$ are given in eq. (2.32) and the gauge choice for $b$ is such that $\Omega_{+}$and $\Omega_{-}$ are given by eqs. (2.33) and (2.34). One verifies that the bulk action, eq. (2.52) is indeed equivalent to the expression given in eq. (B.1). Obviously a detailed comparison of the boundary term obtained in eq. (2.51) with the generic one in eq. (B.1) requires a careful analysis of the boundary conditions imposed on the superfields.

When varying the action eq. (2.49), one needs to take into account that the chiral fields are constrained, eq. (2.47). Introducing unconstrained fields $\Lambda^{\alpha}, \Lambda^{\bar{\alpha}}, M^{\alpha}$ and $M^{\bar{\alpha}}$ we can solve the constraints,

$$
\begin{align*}
z^{\alpha} & =\overline{\mathbb{D}} \Lambda^{\alpha}, & z^{\bar{\alpha}} & =\mathbb{D} \Lambda^{\bar{\alpha}}, \\
\mathbb{D}^{\prime} z^{\alpha} & =\overline{\mathbb{D}} M^{\alpha}-2 i \partial_{\sigma} \Lambda^{\alpha}, & \overline{\mathbb{D}^{\prime}} z^{\bar{\alpha}} & =\mathbb{D} M^{\bar{\alpha}}-2 i \partial_{\sigma} \Lambda^{\bar{\alpha}} . \tag{2.53}
\end{align*}
$$

Upon varying the action we get the bulk equations of motion and a boundary term,

$$
\begin{align*}
\left.\delta \mathcal{S}\right|_{\text {boundary }}=\int d \tau & d^{2} \theta\left\{\delta \Lambda^{\alpha}\left(\overline{\mathbb{D}}^{\prime} V_{\alpha}+i \overline{\mathbb{D}} W_{\alpha}\right)-\delta \Lambda^{\bar{\alpha}}\left(\mathbb{D}^{\prime} V_{\bar{\alpha}}-i \mathbb{D} W_{\bar{\alpha}}\right)\right. \\
& -\delta w^{\mu}\left(V_{\mu}-i W_{\mu}\right)+\delta w^{\bar{\mu}}\left(V_{\bar{\mu}}+i W_{\bar{\mu}}\right)-\delta l^{\tilde{\alpha}}\left(V_{\tilde{\alpha}}-i W_{\tilde{\alpha}}\right) \\
& +\delta l^{\tilde{\alpha}}\left(V_{\overline{\tilde{\alpha}}}+i W_{\overline{\tilde{\alpha}}}\right)+\delta r^{\tilde{\mu}}\left(V_{\tilde{\mu}}+i W_{\tilde{\mu}}\right)-\delta r^{\tilde{\mu}}\left(V_{\overline{\tilde{\mu}}}-i W_{\tilde{\mu}}\right\}, \tag{2.54}
\end{align*}
$$

which should vanish by imposing proper boundary conditions. The expression above can also be rewritten as,

$$
\begin{equation*}
\left.\delta \mathcal{S}\right|_{\text {boundary }}=i \int d \tau d^{2} \theta\left\{\delta \Lambda^{\alpha}\left(\overline{\mathbb{D}}^{\prime}-\overline{\mathbb{D}}\right) B_{\alpha}+\delta \Lambda^{\bar{\alpha}}\left(\mathbb{D}^{\prime}-\mathbb{D}\right) B_{\bar{\alpha}}+B_{a} \delta X^{a}+\delta W\right\}, \tag{2.55}
\end{equation*}
$$

where $X^{a}$ collectively denotes all superfields and $B_{a}$ is the locally defined one-form such that $2 \Omega_{+a b}=\partial_{a} B_{b}-\partial_{b} B_{a}$ where $\Omega_{+}$is defined in eq. (2.33).

Finally, when reducing the action eq. (2.49) to $N=1$ superspace, one finds that $\overline{\mathbb{D}}^{\prime} l^{\tilde{\alpha}}$, $\mathbb{D}^{\prime} l^{\bar{\alpha}}, \overline{\mathbb{D}^{\prime}} r^{\tilde{\mu}}$ and $\mathbb{D}^{\prime} r^{\overline{\tilde{\mu}}}$ are all auxiliary. It is interesting to note that upon their elimination one recovers a (matrix) structure which has a very different appearance, though it remains equivalent of course, from the one we get in the case without boundaries.

## 3 Boundary conditions

### 3.1 Unconstrained $N=2$ fields and lagrangian and coisotropic branes

### 3.1.1 Generalities

In this section we will study the case where all fields are a priori unconstrained from the $N=2$ boundary superspace point of view. Put differently: the bulk $N=(2,2)$ superfields consist of a number ( $n_{t}$, corresponding to $2 n_{t}$ real directions) of twisted chiral superfields and a number ( $n_{s}$, corresponding to $4 n_{s}$ real directions) of semi-chiral multiplets. No chiral $N=(2,2)$ superfields are present. We denote the unconstrained superfields collectively as $X^{a}, a \in\left\{1, \cdots, 2 n_{t}+4 n_{s}\right\}$. Having that $\operatorname{ker}\left(J_{+}-J_{-}\right)=\emptyset$ implies the existence of the non-degenerate two-form $\Omega^{(-)}=2 g\left(J_{+}-J_{-}\right)^{-1}$ introduced in eq. (2.20). We will use throughout section (3.1) the expression for $b$ given in eq. (2.23), i.e. $b=$ $-(1 / 2) \Omega^{(-)}\left(J_{+}+J_{-}\right)$.

Whenever $\operatorname{ker}\left(J_{+}-J_{-}\right)$is non-degenerate, one finds that imposing a Dirichlet boundary condition $Y(X)=0$ implies a Neumann boundary condition as well. Indeed, using the general relation,

$$
\begin{equation*}
\hat{D} X^{a}=\frac{1}{2}\left(J_{+}-J_{-}\right)^{a}{ }_{b} D^{\prime} X^{b}+\frac{1}{2}\left(J_{+}+J_{-}\right)^{a}{ }_{b} D X^{b}, \tag{3.1}
\end{equation*}
$$

we get from the Dirichlet boundary condition that,

$$
\begin{equation*}
0=\hat{D} Y=\partial_{a} Y\left(\left(J_{+}-J_{-}\right)^{a}{ }_{b} D^{\prime} X^{b}+\left(J_{+}+J_{-}\right)^{a}{ }_{b} D X^{b}\right), \tag{3.2}
\end{equation*}
$$

which is a Neumann boundary condition as it relates $D^{\prime} X$ to $D X$ (see eq. (B.8)). So the number of Dirichlet boundary conditions one can impose is bounded and can maximally be $n_{t}+2 n_{s}$.

As $\operatorname{ker}\left(J_{+}-J_{-}\right)=\emptyset$, we can rewrite eq. (3.1) as,

$$
\begin{equation*}
g_{a b} D^{\prime} X^{b}=\Omega_{a b}^{(-)} \hat{D} X^{b}+b_{a b} D X^{b}, \tag{3.3}
\end{equation*}
$$

where we used eq. (2.23). This is very reminiscent of the Neumann boundary conditions in eq. (B.8). The boundary conditions will allow for the identification of $\hat{D} X$ in terms of $D X$.

In the present case - only twisted chiral and semi-chiral superfields - the boundary term in the variation of the action eq. (2.55) reduces to,

$$
\begin{equation*}
\left.\delta \mathcal{S}\right|_{\text {boundary }}=i \int d \tau d^{2} \theta\left\{B_{a}(X) \delta X^{a}+\delta W(X)\right\}, \tag{3.4}
\end{equation*}
$$

where $B_{a}$ is a locally defined one-form whose external derivative is precisely the closed two-form $\Omega^{(-)}, 2 \Omega_{a b}^{(-)}=\partial_{a} B_{b}-\partial_{b} B_{a}$, introduced in eq. (2.20). The vanishing of eq. (3.4) requires appropriate boundary conditions. In what follows we will show that this gives rise to lagrangian and coisotropic D-branes which generalize lagrangian and coisotropic Abranes on Kähler manifolds to manifolds which are bihermitian but not necessarily Kähler. For the necessary background on lagrangian and coisotropic branes on symplectic manifolds, see appendix C.2.2.

### 3.1.2 Lagrangian branes

We first consider the case where we impose the maximal number of Dirichlet boundary conditions. We make a coordinate transformation such that the Dirichlet conditions are expressed by $Y^{\hat{A}}(X)=0$ for $\hat{A} \in\left\{1, \cdots, n_{t}+2 n_{s}\right\}, Y^{\hat{A}} \in \mathbb{R}$. The remainder of the coordinates - the world volume coordinates on the $\mathrm{D}\left(n_{t}+2 n_{s}\right)$-brane - are written as $\sigma^{A}(X) \in \mathbb{R}$ with $A \in\left\{1, \cdots, n_{t}+2 n_{s}\right\}$. The boundary term eq. (3.4) vanishes provided a boundary potential $W(\sigma)$ can be found which satisfies,

$$
\begin{equation*}
\frac{\partial W}{\partial \sigma^{A}}=-B_{b} \frac{\partial X^{b}}{\partial \sigma^{A}} . \tag{3.5}
\end{equation*}
$$

The integrability conditions for these equations state that the pullback of $\Omega^{(-)}$to the world volume of the brane vanishes. Put differently: we are dealing with a brane which is lagrangian with respect to the symplectic structure defined by $\Omega^{(-)}$.

The Neumann boundary conditions can be written as,

$$
\begin{equation*}
\frac{\partial X^{c}}{\partial \sigma^{A}} g_{c b} D^{\prime} X^{b}=\frac{\partial X^{c}}{\partial \sigma^{A}} b_{c d} \frac{\partial X^{d}}{\partial \sigma^{B}} D \sigma^{B} \tag{3.6}
\end{equation*}
$$

where we used eq. (3.3) and the fact that the pullback of $\Omega^{(-)}$to the world volume of the brane vanishes. Comparing this to the Neumann boundary conditions in eq. (B.8), one finds that the invariant field strength $\mathcal{F}$ is of the form,

$$
\begin{equation*}
\mathcal{F}_{a b}=b_{a b}=-\frac{1}{2} \Omega_{a c}^{(-)}\left(J_{+}+J_{-}\right)^{c}{ }_{b} . \tag{3.7}
\end{equation*}
$$

### 3.1.3 Maximally coisotropic branes

The other extremal case is when we have Neumann boundary conditions in all directions. The only way to achieve this is to constrain the fields such that they become chiral on the boundary,

$$
\begin{equation*}
\hat{D} X^{a}=K^{a}{ }_{b}(X) D X^{b} . \tag{3.8}
\end{equation*}
$$

From $\hat{D}^{2}=D^{2}=-i \partial / \partial \tau$ we obtain integrability conditions which tell us that $K$ is $\mathrm{a}(\mathrm{n}$ integrable) complex structure. Going to complex coordinates adapted to the complex structure $K$, one immediately finds that the boundary term in the action eq. (3.4) vanishes provided the one-form $B_{a}+\partial_{a} W$ is holomorphic with respect to $K$. This in its turn implies that $\Omega^{(-)}$is a closed holomorphic $(2,0)+(0,2)$ two-form with respect to $K$. As $\Omega^{(-)}$is non-degenerate, this requires that $n_{t} \in 2 \mathbb{N}$. So we end up with a space filling brane which is maximally coisotropic with respect to the symplectic structure $\Omega^{(-)}$.

The Neumann boundary conditions follow from eqs. (3.8) and (3.3) and are given by,

$$
\begin{equation*}
g_{a b} D^{\prime} X^{b}=\left(\Omega_{a c}^{(-)} K^{c}{ }_{b}+b_{a b}\right) D X^{b} \tag{3.9}
\end{equation*}
$$

where $b$ was given in eq. (2.23). Comparing this to eq. (B.8), we get that,

$$
\begin{equation*}
\mathcal{F}_{a b}=\Omega_{a c}^{(-)} K^{c}{ }_{b}+b_{a b} . \tag{3.10}
\end{equation*}
$$

As $\Omega^{(-)}$is a $(2,0)+(0,2)$ form with respect to the complex structure $K$, we get that,

$$
\begin{equation*}
\hat{\Omega}_{a b}=\Omega_{a c}^{(-)} K^{c}{ }_{b}, \tag{3.11}
\end{equation*}
$$

is a globally defined non-degenerate two-form. Furthermore, using the integrability of the complex structure $K$ (the vanishing of the Nijenhuis tensor), one shows that it is closed as well.

Following a strategy very similar to the the discussion around and following eq. (4.41) in [22], we rewrite the boundary term in the variation of the action eq. (3.4) as,

$$
\begin{equation*}
\left.\delta \mathcal{S}\right|_{\text {boundary }}=2 i \int d \tau d^{2} \theta \delta \Lambda^{a}\left\{\partial_{[a}\left(M_{|c|} K^{c}{ }_{b]}\right)-\partial_{[a} M_{c]} K^{c}{ }_{b}\right\} D X^{b}, \tag{3.12}
\end{equation*}
$$

where $\Lambda$ is an unconstrained anti-commuting superfield and $M_{a}=B_{a}+\partial_{a} W$. This vanishes provided,

$$
\begin{equation*}
\hat{\Omega}_{a b}=\partial_{a}\left(\frac{1}{2} M_{c} K_{b}^{c}\right)-\partial_{b}\left(\frac{1}{2} M_{c} K_{a}^{c}\right), \tag{3.13}
\end{equation*}
$$

holds. This leads us to the $\mathrm{U}(1)$ potential,

$$
\begin{equation*}
A_{a}=\frac{1}{2}\left(B_{b}+\partial_{b} W\right) K_{a}^{b}, \tag{3.14}
\end{equation*}
$$

which is fully consistent with eqs. (2.51), (3.8) and (B.3). From this it follows again that $d \mathcal{F}=H$, as required. Comparing eq. (3.10) to eq. (3.7), we conclude that we now have a $\mathrm{U}(1)$ bundle with fieldstrength $\hat{\Omega}_{a b}$ given in eq. (3.11) and potential $A_{a}$, eq. (3.14).

### 3.1.4 Coisotropic branes

Finally we consider the intermediate case. We use adapted coordinates $Y^{\hat{A}}(X), \sigma^{A}(X)$, $\sigma^{\alpha}(X)$ and $\sigma^{\bar{\alpha}}(X)$, with $\hat{A}, A \in\{1, \cdots, k\}$ and $\alpha, \bar{\alpha} \in\left\{1, \cdots, n_{t}+2 n_{s}-k\right\}$. We impose the Dirichlet boundary conditions,

$$
\begin{equation*}
Y^{\hat{A}}=0 \tag{3.15}
\end{equation*}
$$

and we require that the worldvolume coordinates $\sigma^{\alpha}$ are boundary chiral,

$$
\begin{equation*}
\hat{D} \sigma^{\alpha}=+i D \sigma^{\alpha}, \quad \hat{D} \sigma^{\bar{\alpha}}=-i D \sigma^{\bar{\alpha}} . \tag{3.16}
\end{equation*}
$$

The boundary term in the variation of the action - taking into account that we now have constrained fields on the boundary - vanishes provided,

$$
\begin{align*}
\frac{\partial W}{\partial \sigma^{A}} & =-B_{b} \frac{\partial X^{b}}{\partial \sigma^{A}} \\
\frac{\partial}{\partial \sigma^{\alpha}}\left(\frac{\partial X^{c}}{\partial \sigma^{\beta}} B_{c}+\frac{\partial W}{\partial \sigma^{\beta}}\right) & =\frac{\partial}{\partial \sigma^{\alpha}}\left(\frac{\partial X^{c}}{\partial \sigma^{\bar{\beta}}} B_{c}+\frac{\partial W}{\partial \sigma^{\bar{\beta}}}\right)=0, \\
\frac{\partial}{\partial \sigma^{A}}\left(\frac{\partial X^{c}}{\partial \sigma^{\beta}} B_{c}+\frac{\partial W}{\partial \sigma^{\beta}}\right) & =\frac{\partial}{\partial \sigma^{A}}\left(\frac{\partial X^{c}}{\partial \sigma^{\bar{\beta}}} B_{c}+\frac{\partial W}{\partial \sigma^{\bar{\beta}}}\right)=0 . \tag{3.17}
\end{align*}
$$

The integrability conditions which follow from this imply that all components of the pullback of $\Omega^{(-)}$to the D-brane world volume vanish except for $\Omega_{\alpha \beta}^{(-)}$and $\Omega_{\bar{\alpha} \bar{\beta}}^{(-)}$and we end up with a $\mathrm{D}\left(2 n_{t}+4 n_{s}-k\right)$-brane which is coisotropic ${ }^{4}$ with respect to the symplectic structure $\Omega^{(-)}$. Note that $n_{t}+2 n_{s}-k$ must be even. We distinguish three different sets of Neumann

[^4]boundary conditions,
\[

$$
\begin{align*}
& \frac{\partial X^{c}}{\partial \sigma^{A}} g_{c b}\left(\frac{\partial X^{b}}{\partial \sigma^{B}} D^{\prime} \sigma^{B}+\frac{\partial X^{b}}{\partial \sigma^{\beta}} D^{\prime} \sigma^{\beta}+\frac{\partial X^{b}}{\partial \sigma^{\bar{\beta}}} D^{\prime} \sigma^{\bar{\beta}}\right)= \\
& \frac{\partial X^{c}}{\partial \sigma^{A}} b_{c d}\left(\frac{\partial X^{d}}{\partial \sigma^{B}} D \sigma^{B}\right.\left.+\frac{\partial X^{d}}{\partial \sigma^{\beta}} D \sigma^{\beta}+\frac{\partial X^{d}}{\partial \sigma^{\bar{\beta}}} D \sigma^{\bar{\beta}}\right) \\
& \frac{\partial X^{c}}{\partial \sigma^{\alpha}} g_{c b}\left(\frac{\partial X^{b}}{\partial \sigma^{B}} D^{\prime} \sigma^{B}+\frac{\partial X^{b}}{\partial \sigma^{\beta}} D^{\prime} \sigma^{\beta}+\frac{\partial X^{b}}{\partial \sigma^{\bar{\beta}}} D^{\prime} \sigma^{\bar{\beta}}\right)=i \frac{\partial X^{c}}{\partial \sigma^{\alpha}} \Omega_{c d}^{(-)} \frac{\partial X^{d}}{\partial \sigma^{\beta}} D \sigma^{\beta} \\
&+\frac{\partial X^{c}}{\partial \sigma^{\alpha}} b_{c d}\left(\frac{\partial X^{d}}{\partial \sigma^{B}} D \sigma^{B}\right.\left.+\frac{\partial X^{d}}{\partial \sigma^{\beta}} D \sigma^{\beta}+\frac{\partial X^{d}}{\partial \sigma^{\bar{\beta}}} D \sigma^{\bar{\beta}}\right), \\
& \frac{\partial X^{c}}{\partial \sigma^{\bar{\alpha}}} g_{c b}\left(\frac{\partial X^{b}}{\partial \sigma^{B}} D^{\prime} \sigma^{B}+\frac{\partial X^{b}}{\partial \sigma^{\beta}} D^{\prime} \sigma^{\beta}+\frac{\partial X^{b}}{\partial \sigma^{\bar{\beta}}} D^{\prime} \sigma^{\bar{\beta}}\right)=-i \frac{\partial X^{c}}{\partial \sigma^{\bar{\alpha}}} \Omega_{c d}^{(-)} \frac{\partial X^{d}}{\partial \sigma^{\bar{\beta}}} D \sigma^{\bar{\beta}} \\
&+\frac{\partial X^{c}}{\partial \sigma^{\bar{\alpha}}} b_{c d}\left(\frac{\partial X^{d}}{\partial \sigma^{B}} D \sigma^{B}+\frac{\partial X^{d}}{\partial \sigma^{\beta}} D \sigma^{\beta}+\frac{\partial X^{d}}{\partial \sigma^{\bar{\beta}}} D \sigma^{\bar{\beta}}\right) \tag{3.18}
\end{align*}
$$
\]

Comparing these boundary conditions with eq. (B.8), we can read off the flux $\mathcal{F}$, which is generically of the form,

$$
\begin{equation*}
\mathcal{F}_{a b}=b_{a b}+F_{a b} \tag{3.19}
\end{equation*}
$$

where $b$ was given in eq. (2.23) and the only non-vanishing components of $F$ - the $\mathrm{U}(1)$ field strength - are given by,

$$
\begin{equation*}
F_{\alpha \beta}=i \Omega_{\alpha \beta}^{(-)}, \quad F_{\bar{\alpha} \bar{\beta}}=-i \Omega_{\bar{\alpha} \bar{\beta}}^{(-)} \tag{3.20}
\end{equation*}
$$

### 3.2 Chiral $N=2$ fields

We now turn to the case where only chiral fields, $z^{\alpha}, \alpha \in\left\{1, \cdots, n_{c}\right\}$, are present. The bulk geometry is Kähler. This case has been thoroughly studied in [22] where as a starting point the Dirichlet boundary conditions on the unconstrained superfields were taken (see eq. (2.54)). The result was that through a holomorphic coordinate transformation one can always find coordinates $z^{\tilde{\alpha}}, \tilde{\alpha} \in\{1, \cdots, k\}$ and $z^{\hat{\alpha}}, \hat{\alpha} \in\left\{k+1, \cdots, n_{c}\right\}$, such that the Dirichlet boundary conditions are simply the statement that $z^{\hat{\alpha}}$ s are constant. The worldvolume coordinates are then given by $z^{\tilde{\alpha}}$ and the worldvolume itself is also Kähler. Put differently, we obtain a type B D2k-brane wrapping around a holomorphic cycle of the target manifold.

In order that the boundary term in the variation eq. (2.54) vanishes, we need to impose $2 k$ Neumann boundary conditions as well,

$$
\begin{equation*}
V_{\tilde{\alpha} \bar{\beta}} \overline{\mathbb{D}}^{\prime} z^{\bar{\beta}}=-i W_{\tilde{\alpha} \overline{\tilde{\beta}}} \overline{\mathbb{D}} z^{\overline{\tilde{\beta}}} \tag{3.21}
\end{equation*}
$$

and complex conjugate. Comparing to eq. (B.8), we find a $U(1)$ field strength with as non-vanishing elements $\mathcal{F}_{\tilde{\alpha} \tilde{\tilde{\beta}}}=-i W_{\tilde{\alpha} \tilde{\tilde{\beta}}}$. Note that here - at least at the classical level we have no restrictions on the form of the boundary potential $W .{ }^{5}$

[^5]
### 3.3 The general case

We now turn to the most generic case where we have a model in terms of $n_{s}$ semi-chiral multiplets, $n_{t}$ twisted chiral superfields and $n_{c}$ chiral superfields. This generic case is an - at least in principle - combination of the two cases discussed below. Since expressions become more and more involved, we will restrict ourselves to some important remarks which capture the essence of the ideas involved. We can however already make some general remarks without going into more detail.

First of all, note that while the dependence of the boundary potential $W$ on the semichiral and twisted chiral coordinates is fixed by the boundary conditions, we are still free to add some function of the chiral fields to the potential. This reflects the freedom to switch on an arbitrary $\mathrm{U}(1)$ holomorphic bundle in the chiral directions.

Finally we still have that $W \simeq W+f+\bar{f}$ where $f$ is an arbitrary holomorphic function of all the boundary chiral fields. This freedom can e.g. be used to make certain isometries manifest in the boundary potential.

### 3.3.1 Generalized maximally coisotropic branes

Let us first assume that all twisted chiral and semi-chiral fields obey Neumann conditions. A first thing to realize is that one can do parts of the analysis in section 3.1 more generally. We again start from the generally valid eq. (3.1). In this subsection, we denote the collection of all twisted chiral and semi-chiral fields, and the chiral Neumann fields by $X^{a}$. The Neumann conditions then take the usual form

$$
\begin{equation*}
D^{\prime} X^{a}=g^{a b} \mathcal{F}_{b c} D X^{c} \tag{3.22}
\end{equation*}
$$

Plugging this into (3.1) yields

$$
\begin{equation*}
\hat{D} X^{a}=K^{a}{ }_{b} D X^{b}, \quad K^{a}{ }_{b}=\frac{1}{2}\left(J_{+}+J_{-}\right)^{a}{ }_{b}+\frac{1}{2}\left(J_{+}-J_{-}\right)^{a}{ }_{c} g^{c d} \mathcal{F}_{d b} . \tag{3.23}
\end{equation*}
$$

Note that when $X^{a}$ is a chiral field this simply reduces to the usual chirality condition. The other components of eq. (3.23) mix chiral and non-chiral fields. The integrability of these equations requires $K$ to be a complex structure. If $\operatorname{ker}\left(J_{+}-J_{-}\right)=0-$ i.e. in absence of chiral fields - we can solve for $\mathcal{F}$ as a function of $K$ and we recover eq. (3.10). When only chiral and twisted chiral fields are present, we recover the expression for the complex structure we presented in eq. (4.47) of [23].

The remainder of the analysis of the generic case is similar to the one in section 4.2.2 of $[23]\left(\pi_{+}=1\right.$ case). While $X^{a}$ still denotes any superfield (in the Neumann directions), we write $X^{\tilde{a}}$ for the chiral superfields and $X^{\hat{a}}$ for the semi-chiral and twisted chiral superfields. The vanishing of eq. (2.55) requires,

$$
\begin{equation*}
\partial_{\hat{a}}\left(M_{c} K_{b}^{c}\right)-\partial_{b}\left(M_{c} K_{\hat{a}}^{c}\right)=2 \Omega_{+\hat{a} c} K_{b}^{c}, \tag{3.24}
\end{equation*}
$$

to hold where $\Omega_{+}$was given in eq. (2.33). Using this we find that $\mathcal{F}_{a b}=b_{a b}+F_{a b}$ where $b$ is in the gauge where $\Omega_{+}$is a closed two-form and $F$ is the $\mathrm{U}(1)$ fieldstrength. The explicit ex-
pressions for the fieldstrength follow from combining eqs. (2.51) and (3.24) which results in,

$$
\begin{align*}
F_{\hat{a} \hat{b}} & =\left(\Omega_{+} K\right)_{\hat{a} \hat{b}} \\
F_{\hat{a} \tilde{b}} & =\left(\Omega_{+} K\right)_{\hat{a} \tilde{b}} \\
F_{\alpha \bar{\beta}} & =-i W_{\alpha \bar{\beta}}+\partial_{\alpha}\left(\frac{1}{2} M_{\hat{c}} K^{\hat{c}}{ }_{\bar{\beta}}\right)-\partial_{\bar{\beta}}\left(\frac{1}{2} M_{\hat{c}} K^{\hat{c}}{ }_{\alpha}\right), \\
F_{\alpha \beta} & =\partial_{[\alpha}\left(M_{|\hat{c}|} K^{\hat{c}}{ }_{\beta]}\right), \quad F_{\bar{\alpha} \bar{\beta}}=\partial_{[\bar{\alpha}}\left(M_{|\hat{c}|} K^{\hat{c}}{ }_{\bar{\beta}]}\right), \tag{3.25}
\end{align*}
$$

where we used the original (complex) notation for the chiral fields again. Note that the expressions significantly simplify when $K$ has no components which mix the chiral with the twisted and semi-chiral superfields.

Denoting the number of chiral fields for which we choose Neumann conditions by $\hat{n}_{c}$, the conditions of this subsection describe a $\left(2 \hat{n}_{c}+2 n_{t}+4 n_{s}\right)$-dimensional brane. Although the target space is here no longer symplectic, there is a very natural way in which such a brane still wraps a coisotropic submanifold, namely in the sense of Poisson geometry. This is explained in appendix C. 3 and further discussed in section 3.4. Hence the branes described above will be called generalized maximally coisotropic.

### 3.3.2 Generalized lagrangian branes

Let us now turn to the other extreme, namely impose the maximal number of Dirichlet conditions on twisted chiral and semi-chiral fields as possible. The discussion surrounding eq. (3.2) still holds, so that this means that there are an equal number of Dirichlet and Neumann conditions on these fields.

We denote the chiral fields (in the Neumann directions) by $z^{\alpha}$ and $z^{\bar{\alpha}}$ and we write the semi-chiral and twisted chiral superfields collectively as $X^{\hat{a}}$. Through a coordinate transformation we exchange $X^{\hat{a}}$ for adapted (real) coordinates $Y^{\hat{A}}(X, z)$ and $\sigma^{A}(X, z)$, $\hat{A}, A \in\left\{1, \cdots, n_{t}+2 n_{s}\right\}$. The Dirichlet boundary conditions are given by $Y^{\hat{A}}(X, z)=0$ and $\sigma^{A}, z^{\alpha}$ and $z^{\bar{\alpha}}$ are the worldvolume coordinates.

The vanishing of the boundary term in the variation of the action, eq. (2.55), requires the existence of a boundary potential $W(\sigma, z)$ such that,

$$
\begin{equation*}
\frac{\partial W}{\partial \sigma^{A}}=-B_{\hat{b}} \frac{\partial X^{\hat{b}}}{\partial \sigma^{A}}, \tag{3.26}
\end{equation*}
$$

holds. The integrability condition for this is given by,

$$
\begin{equation*}
\frac{\partial X^{\hat{c}}}{\partial \sigma^{A}} \Omega_{+\hat{c} \hat{d}} \frac{\partial X^{\hat{d}}}{\partial \sigma^{B}}=0 . \tag{3.27}
\end{equation*}
$$

The Neumann boundary conditions assume their standard form, eq. (B.8), with $\mathcal{F}=b+F$. The torsion potential $b$ is in the gauge where $\Omega_{+}=-(g-b) J_{+}$is a closed two-form. The $\mathrm{U}(1)$ fieldstrength follows from the gauge potentials,

$$
\begin{align*}
& A_{\alpha}=V_{\alpha}+i W_{\alpha}+i B_{\hat{b}} \frac{\partial X^{\hat{b}}}{\partial z^{\alpha}} \\
& A_{\bar{\alpha}}=V_{\bar{\alpha}}-i W_{\bar{\alpha}}-i B_{\hat{b}} \frac{\partial X^{\hat{b}}}{\partial z^{\bar{\alpha}}} \\
& A_{A}=0 . \tag{3.28}
\end{align*}
$$

Denoting the number of chiral fields for which we choose Neumann conditions again by $\hat{n}_{c}$, the conditions of this subsection describe a $\left(2 \hat{n}_{c}+n_{t}+2 n_{s}\right)$-dimensional brane. Such a brane wraps a minimally ${ }^{6}$ coisotropic submanifold - again in the sense of Poisson geometry - as will be explained in the next section. We therefore refer to it as a generalized lagrangian brane. Notice that it however need no longer be half-dimensional because of the chiral directions.

### 3.4 Embedding in generalized complex geometry

In flux compactification scenarios, the presence of non-trivial fluxes along cycles of the internal manifold forces the internal manifold to no longer be Calabi-Yau. A good language for capturing some essential features of the required internal geometry was proposed by Hitchin [28] and subsequently developed by Gualtieri [29]. Generalized complex geometry or GCG, as it is called, contains both complex and symplectic geometry as special cases. As such it turns out to be the right setting for the formulation of what the Calabi-Yau condition generalizes to in the presence of fluxes. Perhaps not surprisingly, this is called the (weak) generalized Calabi-Yau condition [28]. Since in this paper we are not yet concerned with conformal invariance on the worldsheet, we have no need to discuss all conditions that go into the generalized Calabi-Yau requirement. Demanding $N=(2,2)$ supersymmetry on the worldsheet nevertheless has a very nice interpretation in the language of GCG. Ever since the work of [4] we know that in the presence of NSNS-flux (but in the absence of RRflux and for constant dilaton) the relevant target space geometry is a bihermitian geometry. It was however shown in [29] that this is equivalent to what is called generalized Kähler geometry in the GCG approach. In appendix C some basic constructions in GCG - as well its limiting cases of complex and symplectic geometry - are discussed, with special emphasis on certain natural classes of submanifolds, i.e. generalized complex, complex and coisotropic submanifolds, respectively. In [29] (see also [30]) it was shown that both A branes (on symplectic manifolds) and B branes (on complex manifolds) can be understood as being generalized complex submanifolds. In this section and appendix C. 2 we rederive some of these results, flesh them out a bit and find more clues for the relevance of generalized complex submanifolds in describing D-branes on generic generalized Kähler manifolds by comparing our findings with the $\sigma$-model results of the previous section.

### 3.4.1 Generalized complex submanifols of bihermitian manifolds

In appendix C, eq. (C.7), we present the pair of commuting $H$-twisted generalized complex structures $\left(\mathcal{J}_{+}, \mathcal{J}_{-}\right)$comprising the generalized Kähler structure associated with the data $\left(g, H, J_{+}, J_{-}\right)$of a bihermitian geometry. As we discussed before, sending $J_{-}$to $-J_{-}$ interchanges chiral and twisted chiral fields in the local parameterization of the manifold. Since this also interchanges $\mathcal{J}_{+}$and $\mathcal{J}_{-}$it is sufficient to focus on one of them when analyzing the conditions for a generalized complex submanifold. In our conventions it turns out that the natural choice is $\mathcal{J}_{+}$which from now on we simply call $\mathcal{J}$.

[^6]Before we proceed, it will be useful to introduce some new notation. We combine the complex structures $J_{ \pm}$into the combinations ${ }^{7}$

$$
\begin{equation*}
J_{( \pm)}=\frac{1}{2}\left(J_{+} \pm J_{-}\right) \tag{3.29}
\end{equation*}
$$

From the non-degenerate two-forms, $\omega_{ \pm}=-g J_{ \pm}$, and more precisely their inverses $\omega_{ \pm}^{-1}=$ $J_{ \pm} g^{-1}$, we can then define two Poisson structures [31]

$$
\begin{equation*}
\Pi_{( \pm)}=J_{( \pm)} g^{-1}=\frac{1}{2}\left(\omega_{+}^{-1} \pm \omega_{-}^{-1}\right) \tag{3.30}
\end{equation*}
$$

For a brief discussion of some relevant facts about Poisson structures, see appendix C.3. When one of these Poisson bi-vectors is invertible, the inverse is a symplectic structure,

$$
\begin{equation*}
\Omega^{( \pm)} \equiv \Pi_{( \pm)}^{-1}=g J_{( \pm)}^{-1} \tag{3.31}
\end{equation*}
$$

As we mentioned before, from these symplectic structures we can define a symmetric 2covector and a 2 -form in a natural way,

$$
\begin{align*}
g^{( \pm)} & =\Omega^{( \pm)} J_{( \pm)}  \tag{3.32}\\
b^{( \pm)} & =-\Omega^{( \pm)} J_{(\mp)} \tag{3.33}
\end{align*}
$$

For backgrounds for which $\Pi_{( \pm)}$is invertible, $g^{( \pm)}$and $b^{( \pm)}$are precisely the metric and b-field of the bihermitian geometry respectively. Notice that using this notation, the additional complex structure $K$ in eq. (3.23) can also be written as, ${ }^{8}$

$$
\begin{equation*}
K=J_{(+)}+\Pi_{(-)} \mathcal{F}=\Pi_{(+)} g+\Pi_{(-)} \mathcal{F} \tag{3.34}
\end{equation*}
$$

Now consider a (generalized) submanifold $(\mathcal{N}, \mathcal{F})$ of a generalized Kähler manifold $\left(\mathcal{M}, \mathcal{J}_{ \pm}, H\right)$ in the sense discussed in appendix C , i.e in particular $d \mathcal{F}=\left.H\right|_{\mathcal{N}}$. Such a submanifold is called generalized complex if its generalized tangent bundle, $\tau_{\mathcal{N}}^{\mathcal{F}}$ defined in eq. (C.10), is stable under the following $H$-twisted generalized complex structure

$$
\mathcal{J}=\left(\begin{array}{cc}
J_{(+)} & \Pi_{(-)}  \tag{3.35}\\
g J_{(-)} & -J_{(+)}^{t}
\end{array}\right)
$$

which is simply a rewriting of $\mathcal{J}_{+}$in eq. (C.7). Requiring $\mathcal{J}$ to stabilize $\tau_{\mathcal{N}}^{\mathcal{F}}$, we get the following conditions,

$$
\begin{align*}
\Pi_{(-)}\left(\operatorname{Ann} T_{\mathcal{N}}\right) & \subset T_{\mathcal{N}}  \tag{3.36}\\
\left(J_{(+)}+\Pi_{(-)} \mathcal{F}\right)\left(T_{\mathcal{N}}\right) & \subset T_{\mathcal{N}}  \tag{3.37}\\
\left(g J_{(-)}-J_{(+)}^{t} \mathcal{F}-\mathcal{F} J_{(+)}-\mathcal{F} \Pi_{(-)} \mathcal{F}\right)\left(T_{\mathcal{N}}\right) & \subset \operatorname{Ann} T_{\mathcal{N}} \tag{3.38}
\end{align*}
$$

where $\operatorname{Ann} T_{\mathcal{N}}$ is defined in eq. (C.13). We now distinguish the following, gradually more complicated cases:

[^7]1. $J_{(-)}=0$

When $J_{(-)}=0-$ so that $J_{(+)}=J_{+}=J_{-}$gives rise to a Kähler structure condition (3.36) becomes empty, while the other two reduce to the conditions for a B brane in a Kähler manifold with complex structure $J_{+}$, as is reviewed in appendix C.
2. $\Pi_{(-)}$is invertible

As explained before, this implies that $\Pi_{(-)}^{-1}=\Omega^{(-)}$is symplectic. Condition (3.36) then reduces to the requirement that $\mathcal{N}$ be coisotropic with respect to $\Omega^{(-)}$. Indeed, in this case we have that $\Pi_{(-)}\left(\operatorname{Ann} T_{\mathcal{N}}\right)=T_{\mathcal{N}}^{\perp}$, the symplectic complement introduced in eq. (C.12).
Condition (3.37) is most straightforwardly analyzed by first introducing $F=\mathcal{F}$ -$b^{(-)}=\mathcal{F}+\Omega^{(-)} J_{(+)}$. In terms of $F$, the condition becomes $\Pi_{(-)}\left(\iota_{X} F\right)=\Pi_{(-)} F X \in$ $T_{\mathcal{N}}$. This condition was analyzed in subsection C.2.2 and the conclusion is that $F$ is zero on $T_{\mathcal{N}}^{\perp}$ and descends to a two-form on $T_{\mathcal{N}} / T_{\mathcal{N}}^{\perp}$. This implies that on $T_{\mathcal{N}}^{\perp}$, $\mathcal{F}=b^{(-)}$. In particular, on a lagrangian submanifold $\mathcal{F}=b^{(-)}$on the whole of $\mathcal{N}$, which agrees with (3.7).
Multiplying (3.38) by $\Pi_{(-)}$from the left and using simple identities like $J_{(+)}^{2}+J_{(-)}^{2}=$ -1 and $\Pi_{(-)} J_{(+)}^{t}=J_{(+)} \Pi_{(-)}$, we see that it implies

$$
\begin{equation*}
\left(J_{(+)}+\Pi_{(-)} \mathcal{F}\right)^{2}=-1 \quad \text { on } \quad T_{\mathcal{N}} / T_{\mathcal{N}}^{\perp} \tag{3.39}
\end{equation*}
$$

It follows that $K=J_{(+)}+\Pi_{(-)} \mathcal{F}$ is an almost complex structure on $T_{\mathcal{N}} / T_{\mathcal{N}}^{\perp}$. This is precisely the complex structure $K$ arising from the $\sigma$-model, as follows from eq. (3.10). Indeed, since $\Pi_{(-)}$is invertible, we can solve for $\mathcal{F}$,

$$
\begin{align*}
\mathcal{F} & =\Omega^{(-)}\left(K-J_{(+)}\right)  \tag{3.40}\\
& =\Omega^{(-)} K+b^{(-)}, \tag{3.41}
\end{align*}
$$

which is precisely eq. (3.10).
These results are actually nothing but the already known conditions for a coisotropic brane on a symplectic manifold with three-form flux $H=d b^{(-)}$, albeit stated more explicitly than is usually done. In fact, the above conclusions could have been obtained more straightforwardly by first performing a b-transform of (3.35) with $b=-b^{(-)}$. As discussed in appendix C , the resulting generalized complex structure $\mathcal{J}_{b}=e^{b} \mathcal{J} e^{-b}$ is untwisted since $H+d b=H-d b^{(-)}=0$. The resulting $\mathcal{J}_{b}$ actually turns out to be of canonical symplectic form, eq. (C.8) with $\Omega=\Omega^{(-)}$. All the above results then follow from the results for a canonical generalized complex structure for a symplectic manifold, reviewed in subsection C.2.2. For instance, the extra complex structure is $K=\Pi_{(-)} F=\Pi_{(-)}\left(\mathcal{F}-b^{(-)}\right)=J_{(+)}+\Pi_{(-)} \mathcal{F}$ as before.
3. No semi-chiral superfields

Even when $\Pi_{(-)}$is not invertible, condition eq. (3.36) is a coisotropy condition in the sense discussed in appendix C. 3 in the context of Poisson geometry. Indeed, while isotropic submanifolds have no natural generalization for (non-symplectic)

Poisson structures, coisotropic submanifolds do. While mathematicians would call such submanifolds coisotropic in the generic case, in order to make the distinction clear, we speak of generalized coisotropic once the Poisson structure in question is not invertible.

The simplest non-symplectic case is the one where no semi-chiral fields are present. Since in this case, we can compute things quite explicitly, let us try to get some intuition for the general case by first considering this one. We write the tangent space of $\mathcal{M}$ at some point $x$ as a sum of a chiral and a twisted chiral part, $T_{\mathcal{M}}=T_{\mathcal{C}} \oplus T_{\mathcal{T}}$. Denoting the canonical (diagonal) complex structure by $J$, and $\omega_{c, t}=-g_{c, t} J$, then we get the Poisson structures (we also use that the metric has a block diagonal form with blocks $g_{c}$ and $g_{t}$ )

$$
\Pi_{(+)}=\left(\begin{array}{cc}
\omega_{c}^{-1} & 0  \tag{3.42}\\
0 & 0
\end{array}\right), \quad \Pi_{(-)}=\left(\begin{array}{cc}
0 & 0 \\
0 & \omega_{t}^{-1}
\end{array}\right)
$$

This implies that a lot of the analysis splits up in conditions on $T_{\mathcal{C}}$ and $T_{\mathcal{T}}$ seperately. Using the language of symplectic foliations introduced in appendix C.3, a symplectic leave associated to $\Pi_{( \pm)}$is denoted by $S^{ \pm}$. At a point $x$, this implies that $S_{x}^{+}=T_{\mathcal{C}}$ and $S_{x}^{-}=T_{\mathcal{T}}$. Now according to eq. (C.20), $\Pi_{(-)}\left(\operatorname{Ann} T_{\mathcal{N}}\right)=T_{\mathcal{N}, \mathcal{T}}^{\perp}$, the symplectic complement of $T_{\mathcal{N}, \mathcal{T}} \equiv T_{\mathcal{N}} \cap S_{x}^{-}$in $S_{x}^{-}$, where the symplectic structure is the inverse of the restriction of $\Pi_{(-)}$to $S_{x}^{-}=T_{\mathcal{T}}$, namely $\omega_{t}$.
Eq. (3.36) then implies that $T_{\mathcal{N}, \mathcal{T}}^{\perp} \subset T_{\mathcal{N}}$. In fact, because of the block diagonal structure of $\Pi_{(-)}, T_{\mathcal{N}, \mathcal{T}}$ should be a coisotropic subspace of $T_{\mathcal{T}}$.

Note however that $\mathcal{F}$ can a priori still have mixed indices. Condition (3.37) on one hand says $J\left(T_{\mathcal{N}, \mathcal{C}}\right) \subset T_{\mathcal{N}, \mathcal{C}}$, where $T_{\mathcal{N}, \mathcal{C}}=T_{\mathcal{N}} \cap T_{\mathcal{C}}$, so that the chiral directions of $\mathcal{N}$ are 'holomorphic'. The term involving $\mathcal{F}$ however reduces to a condition on $T_{\mathcal{N}, \mathcal{T}}$. It implies that $\iota_{X} \mathcal{F}=0$ for $X \in T_{\mathcal{N}, \mathcal{T}}^{\perp}$, the symplectic complement of $T_{\mathcal{N}, \mathcal{T}}$ for $\omega_{t}$ restricted to $T_{\mathcal{T}}$. Note that, since this condition follows from restricting $\Pi_{(-)}$to $T_{\mathcal{T}}$, this says nothing about components of $\mathcal{F}$ with one leg in $T_{\mathcal{N}, \mathcal{T}}^{\perp}$ and one along $T_{\mathcal{N}, \mathcal{C}}$. Indeed such components were shown to be non-zero in [22].

Finally, eq. (3.38) requires more care. First of all, multiplying it by $\Pi_{(-)}$, we get as before that $K=J_{(+)}+\Pi_{(-)} \mathcal{F}$ is a complex structure on $T_{\mathcal{N}} / T_{\mathcal{N}, \mathcal{T}}^{\perp}$. This is indeed the object we called $\mathcal{K}$ in [22]. However, since $\Pi_{(-)}$is not invertible, multiplying eq. (3.38) by $\Pi_{(-)}$yields only part of the necessary conditions. The remaining conditions are obtained by multiplying eq. (3.38) by $\Pi_{(+)}$. This yields a $\Pi_{(+)}\left(A n n T_{\mathcal{N}}\right)$ on the right hand side of the inclusion. This equals $\left(T_{\mathcal{N}, \mathcal{C}}\right)^{\perp}$, where now $\omega_{c}$ on $T_{\mathcal{C}}$ has to be used. Since $T_{\mathcal{N}, \mathcal{C}}$ is a symplectic subspace of $T_{\mathcal{C}}$ (see appendix C.2), its symplectic complement is zero when all chiral fields are taken to be Neumann. Restricting to this case for simplicity (and using the fact that $J_{(+)} J_{(-)}=0$ in absence of semi-chiral fields), we find

$$
\begin{equation*}
J_{(+)} \Pi_{(+)} \mathcal{F}+\Pi_{(+)} \mathcal{F} J_{(+)}+\Pi_{(+)} \mathcal{F} \Pi_{(-)} \mathcal{F}=0 \quad \text { on } \quad T_{\mathcal{N}} . \tag{3.43}
\end{equation*}
$$

This equation generalizes the holomorphicity condition for the $U(1)$ flux on a $B$ brane, showing that for instance the field strengths along the chiral directions are generically no longer holomorphic. Indeed, letting $\alpha$ and $\beta$ run over chiral, and $\mu$ and $\nu$ over twisted chiral fields, one of the equations implied by eq. (3.43) is the following condition on $\mathcal{F}_{\alpha \beta}$,

$$
\begin{equation*}
2 \mathcal{F}_{\alpha \beta}+\mathcal{F}_{\alpha \mu} g^{\mu \bar{\nu}} \mathcal{F}_{\bar{\nu} \beta}-\mathcal{F}_{\alpha \bar{\mu}} g^{\bar{\mu} \nu} \mathcal{F}_{\nu \beta}=0 \tag{3.44}
\end{equation*}
$$

## 4. General case

Here again, we use the notation $S^{ \pm}$for the symplectic leaves associated to $\Pi_{( \pm)}$. Writing locally $T_{\mathcal{M}}=T_{\mathcal{C}} \oplus T_{\mathcal{T}} \oplus T_{\mathcal{S}}$ where the last term now adds the semi-chiral fields, we find that $S_{x}^{+}=T_{\mathcal{C}} \oplus T_{\mathcal{S}}$ and $S_{x}^{-}=T_{\mathcal{T}} \oplus T_{\mathcal{S}}$. Let us denote $S_{x}^{-} \cap T_{\mathcal{N}}$ by $S_{\mathcal{N}}^{-}$ in the following. Condition (3.36) then states that

$$
\begin{equation*}
\left(S_{\mathcal{N}}^{-}\right)^{\perp} \subset T_{\mathcal{N}} \tag{3.45}
\end{equation*}
$$

where the symplectic complement is with respect to the inverse of the restriction of $\Pi_{(-)}$to $S^{-}$. This is indeed essentially the structure that was found by analyzing boundary conditions in the $\sigma$-model. Of course much more remains to be analyzed, especially concerning the invariant field strength $\mathcal{F}$ on the brane. ${ }^{9}$ Let us simply note here that one can of course still multiply eq. (3.38) by $\Pi_{(-)}$from the right to obtain

$$
\begin{equation*}
K^{2}=-1 \quad \text { on } \quad T_{\mathcal{N}} /\left(S_{\mathcal{N}}^{-}\right)^{\perp} \tag{3.46}
\end{equation*}
$$

where $K$ is still of the form (3.34). This indeed agrees with eq. (3.23).

## 4 Duality transformations

In $N=(2,2)$ supersymmetric models there exists a variety of duality transformations which allows one to change the nature of the superfields. These duality transformations fall into two categories: those which need an isometry and those which do not. The former are what is usually understood as a T-duality transformation while the latter are a consequence of the constraints which are imposed on $N=(2,2)$ superfields. A complete catalogue of duality transformations in $N=(2,2)$ superspace was obtained in [34]. Here we generalize this to the situation where boundaries are present. The main subtlety consists in finding the proper boundary terms in the first order action which guarantee that the boundary conditions consistently pass through the duality transformation.

### 4.1 Dualities without an isometry

The basic idea of dualities without an isometry is to impose the constraints on the superfields through Lagrange multipliers (unconstrained superfields). In a first order formulation

[^8]one takes the original fields as unconstrained superfields. Integrating over the Lagrange multipliers brings us back to the original model. However, if we integrate over the original unconstrained fields we get the dual formulation. In this way one has the following dual combinations:

- Four dual semi-chiral formulations.
- Twisted chiral field $\leftrightarrow$ twisted complex linear superfield.
- Chiral field $\leftrightarrow$ complex linear superfield.

In the present paper we briefly introduce these duality transformations and postpone a detailed analysis of them - which requires a careful treatment of the boundary conditions - to a forthcoming paper.

### 4.1.1 The four dual semi-chiral formulations

The starting point is the first order action,

$$
\begin{align*}
\mathcal{S}= & -\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}\left(V(l, \bar{l}, r, \bar{r}, \cdots)-\Lambda^{+} \overline{\mathbb{D}}_{+} l-\bar{\Lambda}^{+} \mathbb{D}_{+} \bar{l}-\Lambda^{-} \overline{\mathbb{D}}_{-} r-\bar{\Lambda}^{-} \mathbb{D}_{-} \bar{r}\right) \\
& +i \int d \tau d^{2} \theta\left(W(l, \bar{l}, r, \bar{r}, \cdots)+i \Lambda^{+} \overline{\mathbb{D}}_{+} l-i \bar{\Lambda}^{+} \mathbb{D}_{+} \bar{l}-i \Lambda^{-} \overline{\mathbb{D}}_{-} r+i \bar{\Lambda}^{-} \mathbb{D}_{-} \bar{r}\right) \tag{4.1}
\end{align*}
$$

where $l, \bar{l}, r$ and $\bar{r}$ are unconstrained bosonic complex superfields and $\Lambda^{ \pm}$and $\bar{\Lambda}^{ \pm}$are unconstrained complex fermionic superfields. Integrating over the Lagrange multipliers constrains $l$ and $r$ to form a semi-chiral multiplet. Upon partial integration we can rewrite the action in three ways,

$$
\begin{align*}
\mathcal{S}= & -\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}\left(V(l, \bar{l}, r, \bar{r}, \cdots)-l l^{\prime}-\bar{l} \bar{l}^{\prime}-\Lambda^{-} \overline{\mathbb{D}}_{-} r-\bar{\Lambda}^{-} \mathbb{D}_{-} \bar{r}\right) \\
& +i \int d \tau d^{2} \theta\left(W(l, \bar{l}, r, \bar{r}, \cdots)+i l l^{\prime}-i \bar{l} \bar{l}^{\prime}-i \Lambda^{-} \overline{\mathbb{D}}_{-} r+i \bar{\Lambda}^{-} \mathbb{D}_{-} \bar{r}\right) \\
= & -\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}\left(V(l, \bar{l}, r, \bar{r}, \cdots)-\Lambda^{+} \overline{\mathbb{D}}_{+} l-\bar{\Lambda}^{+} \mathbb{D}_{+} \bar{l}-r r^{\prime}-\bar{r} \bar{r}^{\prime}\right) \\
& +i \int d \tau d^{2} \theta\left(W(l, \bar{l}, r, \bar{r}, \cdots)+i \Lambda^{+} \overline{\mathbb{D}}_{+} l-i \bar{\Lambda}^{+} \mathbb{D}_{+} \bar{l}-i r r^{\prime}+i \bar{r} \bar{r}^{\prime}\right) \\
= & -\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}\left(V(l, \bar{l}, r, \bar{r}, \cdots)-l l^{\prime}-\bar{l} \bar{l}^{\prime}-r r^{\prime}-\bar{r} \bar{r}^{\prime}\right) \\
& +i \int d \tau d^{2} \theta\left(W(l, \bar{l}, r, \bar{r}, \cdots)+i l l^{\prime}-i \bar{l} \bar{l}^{\prime}-i r r^{\prime}+i \bar{r} \bar{r}^{\prime}\right), \tag{4.2}
\end{align*}
$$

where we introduced the notation $l^{\prime}=\overline{\mathbb{D}}_{+} \Lambda^{+}, \bar{l}^{\prime}=\mathbb{D}_{+} \bar{\Lambda}^{+}, r^{\prime}=\overline{\mathbb{D}}_{-} \Lambda^{-}, \bar{r}^{\prime}=\mathbb{D}_{-} \bar{\Lambda}^{-}$. Integrating over the unconstrained fields $\left(l, \bar{l}, \Lambda^{-}, \bar{\Lambda}^{-}\right),\left(\Lambda^{+}, \bar{\Lambda}^{+}, r, \bar{r}\right)$ or $(l, \bar{l}, r, \bar{r})$ resp. yields three dual formulations of the model.

### 4.1.2 The duality between twisted chiral and twisted complex linear fields

This duality transformation is fully determined by the following two equivalent versions of the first order action,

$$
\begin{align*}
\mathcal{S}= & -\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}\left(V(w, \bar{w}, \cdots)-\Lambda^{+} \overline{\mathbb{D}}_{+} w-\bar{\Lambda}^{-} \mathbb{D}_{-} w-\bar{\Lambda}^{+} \mathbb{D}_{+} \bar{w}-\Lambda^{-} \overline{\mathbb{D}}-\bar{w}\right) \\
& +i \int d \tau d^{2} \theta\left(W(w, \bar{w}, \cdots)+i \Lambda^{+} \overline{\mathbb{D}}_{+} w+i \bar{\Lambda}^{-} \mathbb{D}_{-} w-i \bar{\Lambda}^{+} \mathbb{D}_{+} \bar{w}-i \Lambda^{-} \overline{\mathbb{D}}_{-} \bar{w}\right) \\
= & -\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}(V(w, \bar{w}, \cdots)-w x-\bar{w} \bar{x}) \\
& +i \int d \tau d^{2} \theta(W(w, \bar{w}, \cdots)+i w x-i \bar{w} \bar{x}), \tag{4.3}
\end{align*}
$$

where $\Lambda^{ \pm}$are unconstrained complex fermionic superfields and we wrote $x \equiv \overline{\mathbb{D}}_{+} \Lambda^{+}+\mathbb{D}_{-} \bar{\Lambda}^{-}$ and $\bar{x} \equiv \mathbb{D}_{+} \bar{\Lambda}^{+}+\overline{\mathbb{D}}_{-} \Lambda^{-}$. We identify $x$ as a twisted complex linear superfield defined by the constraints quadratic in the derivatives: $\overline{\mathbb{D}}_{+} \mathbb{D}_{-} x=\mathbb{D}_{+} \overline{\mathbb{D}}_{-} \bar{x}=0$ [35]. Integrating over $\Lambda^{ \pm}$and $\bar{\Lambda}^{ \pm}$constrains $w$ and $\bar{w}$ to be twisted chiral. If on the other hand we first integrate over the unconstrained fields $w$ and $\bar{w}$, we end up with the dual description where the dependence on a twisted chiral field was exchanged for one on a twisted complex linear superfield.

### 4.1.3 The duality between chiral and complex linear fields

Starting from the potentials $V(z, \bar{z}, \cdots)$ and $W(z, \bar{z}, \cdots)$, where $z$ is a chiral field, we write a first order action,

$$
\begin{align*}
\mathcal{S}= & -\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}\left(V(z, \bar{z}, \cdots)-\Lambda^{+} \overline{\mathbb{D}}_{+} z-\Lambda^{-} \overline{\mathbb{D}}_{-} z-\bar{\Lambda}^{+} \mathbb{D}_{+} \bar{z}-\bar{\Lambda}^{-} \mathbb{D}_{-} \bar{z}\right) \\
& +i \int d \tau d^{2} \theta\left(W(z, \bar{z}, \cdots)+i \Lambda^{+} \overline{\mathbb{D}}_{+} z-i \Lambda^{-} \overline{\mathbb{D}}_{-} z-i \bar{\Lambda}^{+} \mathbb{D}_{+} \bar{z}+i \bar{\Lambda}^{-} \mathbb{D}_{-} \bar{z}\right) \tag{4.4}
\end{align*}
$$

where we now take $z$ and $\bar{z}$ as unconstrained superfields and $\Lambda^{ \pm}$and $\bar{\Lambda}^{ \pm}$are (unconstrained) Lagrange multipliers. Varying the Lagrange multipliers gives the original model. Upon partial integration we can rewrite the first order action as,

$$
\begin{align*}
\mathcal{S}= & -\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}(V(z, \bar{z}, \cdots)-z x-\bar{z} \bar{x}) \\
& +i \int d \tau d^{2} \theta\left(W(z, \bar{z}, \cdots)+i z\left(\overline{\mathbb{D}}_{+} \Lambda^{+}-\overline{\mathbb{D}}_{-} \Lambda^{-}\right)-i \bar{z}\left(\mathbb{D}_{+} \bar{\Lambda}^{+}-\mathbb{D}_{-} \bar{\Lambda}^{-}\right)\right. \tag{4.5}
\end{align*}
$$

where $x \equiv \overline{\mathbb{D}}_{+} \Lambda^{+}+\overline{\mathbb{D}}_{-} \Lambda^{-}$is a complex linear superfield defined by the constraints $\overline{\mathbb{D}}_{+} \overline{\mathbb{D}}_{-} x=$ $\mathbb{D}_{+} \mathbb{D}_{-} \bar{x}=0[36,37]$. The treatment of the boundary term in the action and the boundary conditions requires special care. We postpone this discussion to a future paper.

### 4.2 Dualities with an isometry

The main idea here is to gauge the isometry and through Lagrange multipliers enforce the gauge fields to be pure gauge. Integrating over the Lagrange multipliers brings us back to the original model while integrating over the gauge fields results in the dual model. The treatment of the boundary conditions through the duality transformation requires special care.

### 4.2.1 The duality between a pair of chiral and twisted chiral fields and a semi-chiral multiplet

The starting point is a bulk potential of the form $V(z+\bar{z}, w+\bar{w}, i(z-\bar{z}-w+\bar{w}), \cdots)$ and a boundary potential $W(z+\bar{z}, w+\bar{w}, i(z-\bar{z}-w+\bar{w}), \cdots)$. This clearly exhibits the isometry $z \rightarrow z+i a, w \rightarrow w+i a$, with $a$ an arbitrary real constant. ${ }^{10}$ The first order action is,

$$
\begin{align*}
\mathcal{S}= & -\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}\left(V(Y, \tilde{Y}, \hat{Y}, \cdots)+\Lambda^{+} \overline{\mathbb{D}}_{+}(Y-\tilde{Y}-i \hat{Y})+\bar{\Lambda}^{+} \mathbb{D}_{+}(Y-\tilde{Y}+i \hat{Y})\right. \\
& \left.-\Lambda^{-} \overline{\mathbb{D}}_{-}(Y+\tilde{Y}-i \hat{Y})-\bar{\Lambda}^{-} \mathbb{D}_{-}(Y+\tilde{Y}+i \hat{Y})\right) \\
& +i \int d \tau d^{2} \theta\left(W(Y, \tilde{Y}, \hat{Y}, \cdots)-i \Lambda^{+} \overline{\mathbb{D}}_{+}(Y-\tilde{Y}-i \hat{Y})+i \bar{\Lambda}^{+} \mathbb{D}_{+}(Y-\tilde{Y}+i \hat{Y})\right. \\
& \left.-i \Lambda^{-} \overline{\mathbb{D}}_{-}(Y+\tilde{Y}-i \hat{Y})+i \bar{\Lambda}^{-} \mathbb{D}_{-}(Y+\tilde{Y}+i \hat{Y})\right) \tag{4.6}
\end{align*}
$$

where $\Lambda^{ \pm}$and $\bar{\Lambda}^{ \pm}$are unconstrained complex fermionic superfields and $Y, \tilde{Y}$ and $\hat{Y}$ are unconstrained real bosonic superfields. Integrating over the Lagrange multipliers $\Lambda^{ \pm}$and $\bar{\Lambda}^{ \pm}$returns us to the original model. Upon partial integration we rewrite the first order action as,

$$
\begin{align*}
\mathcal{S}= & -\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}(V(Y, \tilde{Y}, \hat{Y}, \cdots)+Y(l+\bar{l}-r-\bar{r})-\tilde{Y}(l+\bar{l}+r+\bar{r}) \\
& -i \hat{Y}(l-\bar{l}-r+\bar{r}))+i \int d \tau d^{2} \theta(W(Y, \tilde{Y}, \hat{Y}, \cdots)-i Y(l-\bar{l}+r-\bar{r}) \\
& +i \tilde{Y}(l-\bar{l}-r+\bar{r})-\hat{Y}(l+\bar{l}+r+\bar{r})) \tag{4.7}
\end{align*}
$$

where we introduced the semi-chiral multiplet $l=\overline{\mathbb{D}}_{+} \Lambda^{+}, \bar{l}=\mathbb{D}_{+} \bar{\Lambda}^{+}, r=\overline{\mathbb{D}}_{-} \Lambda^{-}$and $\bar{r}=\mathbb{D}_{-} \bar{\Lambda}^{-}$. Integrating over $Y, \tilde{Y}$ and $\hat{Y}$ yields the dual model.

Let us illustrate this with a simple example. Our starting point is a model on $T^{4}$ parameterized by a twisted chiral, $w$, and a chiral, $z$, superfield. We take for the generalized Kähler potential,

$$
\begin{equation*}
V=-\frac{1}{4}(z+\bar{z}-w-\bar{w})^{2}+\frac{1}{4}(z-\bar{z}-w+\bar{w})^{2}+(z+\bar{z})^{2} \tag{4.8}
\end{equation*}
$$

We consider a D3-brane whose location is fixed by the Dirichlet boundary condition,

$$
\begin{equation*}
i(z-\bar{z}-w+\bar{w})=i(1-a)(z-\bar{z}) \tag{4.9}
\end{equation*}
$$

where $a \in \mathbb{Q}$. Using the methods of section 3 one finds the boundary potential,

$$
\begin{equation*}
W=\frac{i}{2}(z-\bar{z}-w+\bar{w})(w+\bar{w}) \tag{4.10}
\end{equation*}
$$

to which we could have added an arbitrary real function of $z$ and $\bar{z}$. When dualizing this to a semi-chiral model, we have to distinguish two cases: $a=1$ and $a \neq 1$.

[^9]Consider the case where $a=1$. In that case eq. (4.9) implies a Dirichlet boundary condition for the gauge fields: $\hat{Y}=0$ and the boundary potential $W$ vanishes. The first order action eq. (4.7) becomes,

$$
\begin{align*}
\mathcal{S}= & -\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}\left(-\frac{1}{4}(Y-\tilde{Y})^{2}-\frac{1}{4} \hat{Y}^{2}+Y^{2}+Y(l+\bar{l}-r-\bar{r})-\tilde{Y}(l+\bar{l}+r+\bar{r})\right. \\
& -i \hat{Y}(l-\bar{l}-r+\bar{r}))+i \int d \tau d^{2} \theta(-i Y(l-\bar{l}+r-\bar{r})+i \tilde{Y}(l-\bar{l}-r+\bar{r})) \tag{4.11}
\end{align*}
$$

From the bulk equations of motion we get,

$$
\begin{align*}
& Y=r+\bar{r} \\
& \tilde{Y}=-2(l+\bar{l})-(r+\bar{r}) \\
& \hat{Y}=-2 i(l-\bar{l}-r+\bar{r}) \tag{4.12}
\end{align*}
$$

Note that we already had a Dirichlet boundary condition $\hat{Y}=0$ which is reproduced by varying $\tilde{Y}$ in the boundary term in the first order action eq. (4.11). Varying $Y$ in the boundary term yields a second Dirichlet boundary condition which together with the first one imply,

$$
\begin{equation*}
l=\bar{l}, \quad r=\bar{r} \tag{4.13}
\end{equation*}
$$

So in the dual model we obtain a generalized lagrangian D2-brane whose location is specified by eq. (4.13), the boundary potential vanishes and the bulk potential is given by,

$$
\begin{equation*}
V_{\text {dual }}=(l+\bar{l}+r+\bar{r})^{2}-(l-\bar{l}-r+\bar{r})^{2}-(r+\bar{r})^{2} \tag{4.14}
\end{equation*}
$$

We now consider the case $a \neq 0$ where for simplicity we choose $a=0$. Eq. (4.9) results in the boundary conditions,

$$
\begin{equation*}
\overline{\mathbb{D}}(\hat{Y}+i Y)=\mathbb{D}(\hat{Y}-i Y)=0 \tag{4.15}
\end{equation*}
$$

which implies that,

$$
\begin{equation*}
Z^{1} \equiv \hat{Y}+i Y=-2 i l+2 i \bar{l}+3 i r-i \bar{r} \tag{4.16}
\end{equation*}
$$

is a boundary chiral field! With this, the first order action eq. (4.7) becomes,

$$
\begin{align*}
\mathcal{S}= & -\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}\left(-\frac{1}{4}(Y-\tilde{Y})^{2}-\frac{1}{4} \hat{Y}^{2}+Y^{2}+Y(l+\bar{l}-r-\bar{r})-\tilde{Y}(l+\bar{l}+r+\bar{r})\right. \\
& -i \hat{Y}(l-\bar{l}-r+\bar{r}))+i \int d \tau d^{2} \theta\left(\frac{1}{4}\left(Z^{1}+\bar{Z}^{\overline{1}}\right) \tilde{Y}+i \tilde{Y}(l-\bar{l}-r+\bar{r})\right. \\
& \left.-Z^{1}(l+r)-\bar{Z}^{\overline{1}}(\bar{l}+\bar{r})\right) \tag{4.17}
\end{align*}
$$

Obviously the bulk equations of motion are again given by eq. (4.12). Varying $\tilde{Y}$ in the boundary term of the first order action eq. (4.17) gives an expression compatible with the
bulk equations of motion eq. (4.12). Varying $Z^{1}$ and $\bar{Z}^{\overline{1}}$ - taking into account that they are constrained boundary superfields - gives,

$$
\begin{equation*}
\overline{\mathbb{D}}\left(\frac{1}{4} \tilde{Y}-l-r\right)=\mathbb{D}\left(\frac{1}{4} \tilde{Y}-\bar{l}-\bar{r}\right)=0 \tag{4.18}
\end{equation*}
$$

implying the existence of a second boundary chiral field $Z^{2}$,

$$
\begin{equation*}
Z^{2} \equiv \frac{1}{4} \tilde{Y}-l-r=-\frac{3}{2} l-\frac{1}{2} \bar{l}-\frac{5}{4} r-\frac{1}{4} \bar{r} . \tag{4.19}
\end{equation*}
$$

So we end up with a maximally coisotropic brane on $T^{4}$. Labelling rows and columns as $(l, \bar{l}, r, \bar{r})$, we get for the complex structure $K$,

$$
K=\frac{1}{4}\left(\begin{array}{cccc}
6 i & -2 i & -i & 3 i  \tag{4.20}\\
2 i & -6 i & -3 i & i \\
-2 i & 6 i & 6 i & -2 i \\
-6 i & 2 i & 2 i & -6 i
\end{array}\right)
$$

The bulk potential is given by eq. (4.14) and the boundary potential is,

$$
\begin{equation*}
W_{\text {dual }}=-i(l-\bar{l}-r+\bar{r})(2(l+\bar{l})+(r+\bar{r})) \tag{4.21}
\end{equation*}
$$

In terms of the boundary chiral fields this becomes,

$$
\begin{equation*}
W_{\text {dual }}=-\frac{1}{4}\left(Z^{1}+\bar{Z}^{\overline{1}}\right)\left(Z^{2}+\bar{Z}^{\overline{2}}-\frac{i}{4}\left(Z^{1}-\bar{Z}^{\overline{1}}\right)\right)=-\frac{1}{4}\left(Z^{1} \bar{Z}^{\overline{2}}+\bar{Z}^{\overline{1}} Z^{2}\right) \tag{4.22}
\end{equation*}
$$

where in the last step we discarded total derivative terms.
We now focus on the inverse transformation. Starting point is a bulk potential of the form $V(l+\bar{l}, r+\bar{r}, i(l-\bar{l}-r+\bar{r}), \cdots)$ and a boundary potential $W(l+\bar{l}, r+\bar{r}, i(l-\bar{l}-r+\bar{r}), \cdots)$. The basic relation is given by,

$$
\begin{align*}
\mathcal{S}= & -\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}\left(V(Y, \tilde{Y}, \hat{Y}, \cdots)+i u \overline{\mathbb{D}}_{+} \overline{\mathbb{D}}-(Y-\tilde{Y}-i \hat{Y})\right. \\
& \left.+i \bar{u} \mathbb{D}_{+} \mathbb{D}_{-}(Y-\tilde{Y}+i \hat{Y})-i v \overline{\mathbb{D}}_{+} \mathbb{D}_{-}(Y+\tilde{Y}-i \hat{Y})-i \bar{v} \mathbb{D}_{+} \overline{\mathbb{D}}_{-}(Y+\tilde{Y}+i \hat{Y})\right) \\
& +i \int d \tau d^{2} \theta\left(W(Y, \tilde{Y}, \hat{Y}, \cdots)-\frac{1}{2} \overline{\mathbb{D}}^{\prime} u \overline{\mathbb{D}}^{\prime}(Y-\tilde{Y}-i \hat{Y})+\frac{1}{2} \mathbb{D}^{\prime} \bar{u}_{\mathbb{D}^{\prime}}(Y-\tilde{Y}+i \hat{Y})\right. \\
& \left.-v \overline{\mathbb{D}}_{+} \mathbb{D}_{-}(Y+\tilde{Y}-i \hat{Y})+\bar{v} \mathbb{D}_{+} \overline{\mathbb{D}}_{-}(Y+\tilde{Y}+i \hat{Y})\right) \\
= & -\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}(V(Y, \tilde{Y}, \hat{Y}, \cdots)+Y(z+\bar{z}-w-\bar{w})-\tilde{Y}(z+\bar{z}+w+\bar{w}) \\
& -i \hat{Y}(z-\bar{z}-w+\bar{w}))+i \int d \tau d^{2} \theta(W(Y, \tilde{Y}, \hat{Y}, \cdots) \\
& +i(Y+\tilde{Y})(w-\bar{w})+\hat{Y}(w+\bar{w})) \tag{4.23}
\end{align*}
$$

where $u, v \in \mathbb{C}$ and $Y, \tilde{Y}, \hat{Y} \in \mathbb{R}$ are unconstrained superfields and where we defined $z=i \overline{\mathbb{D}}_{+} \overline{\mathbb{D}}_{-} u, \bar{z}=i \mathbb{D}_{+} \mathbb{D}_{-} \bar{u}, w=i \overline{\mathbb{D}}_{+} \mathbb{D}_{-} v$ and $\bar{w}=i \mathbb{D}_{+} \overline{D_{-}} \bar{v}$. When using this, special attention must be given to the boundary terms proportional to $\overline{\mathbb{D}}^{\prime} u$ and $\mathbb{D}^{\prime} \bar{u}$.

Again we will illustrate this with a simple example. Indeed we will dualize the lagrangian D2- and the coisotropic D4-brane obtained above back to a D3-brane in terms of a twisted chiral and a chiral field. The bulk potential we start from is given by eq. (4.14). For the D2-brane we consider the Dirichlet boundary conditions eq. (4.13) and a vanishing boundary potential. The Dirichlet boundary condition imply $\hat{Y}=0$ on the boundary. Using the first part of relation eq. (4.23), we find the first order action to be,

$$
\begin{align*}
\mathcal{S}= & -\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}\left((Y+\tilde{Y})^{2}+\hat{Y}^{2}-\tilde{Y}^{2}+i u \overline{\mathbb{D}}_{+} \overline{\mathbb{D}}_{-}(Y-\tilde{Y}-i \hat{Y})\right. \\
& \left.+i \bar{u} \mathbb{D}_{+} \mathbb{D}_{-}(Y-\tilde{Y}+i \hat{Y})-i v \overline{\mathbb{D}}_{+} \mathbb{D}_{-}(Y+\tilde{Y}-i \hat{Y})-i \bar{v}_{+} \overline{\mathbb{D}}_{-}(Y+\tilde{Y}+i \hat{Y})\right) \\
& +i \int d \tau d^{2} \theta\left(-v \overline{\mathbb{D}}_{+} \mathbb{D}_{-}(Y+\tilde{Y}-i \hat{Y})+\bar{v} \mathbb{D}_{+} \overline{\mathbb{D}}_{-}(Y+\tilde{Y}+i \hat{Y})\right. \\
& \left.-\frac{1}{2} \overline{\mathbb{D}}^{\prime} u\left(\overline{\mathbb{D}}^{\prime}(Y-\tilde{Y}-i \hat{Y})+\overline{\mathbb{D}}(Y+\tilde{Y})\right)+\frac{1}{2} \mathbb{D}^{\prime} \bar{u}\left(\mathbb{D}^{\prime}(Y-\tilde{Y}+i \hat{Y})+\mathbb{D}(Y+\tilde{Y})\right)\right), \tag{4.24}
\end{align*}
$$

where we added two extra terms to the boundary term proportional to $\overline{\mathbb{D}}^{\prime} u$ and $\mathbb{D}^{\prime} \bar{u}$ such that the variation of $\overline{\mathbb{D}}^{\prime} u$ and $\mathbb{D}^{\prime} \bar{u}$ yields expressions compatible with the boundary conditions and the constraints eq. (2.47). Integrating this action by parts yields,

$$
\begin{align*}
\mathcal{S}= & -\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}\left((Y+\tilde{Y})^{2}+\hat{Y}^{2}-\tilde{Y}^{2}+Y(z+\bar{z}-w-\bar{w})\right. \\
& -\tilde{Y}(z+\bar{z}+w+\bar{w})-i \hat{Y}(z-\bar{z}-w+\bar{w})) \\
+ & i \int d \tau d^{2} \theta(+i(Y+\tilde{Y})(w-\bar{w}-z+\bar{z})) \tag{4.25}
\end{align*}
$$

where the boundary term containing the chiral field $z, \bar{z}$ results from the additional terms added in the first order action we started from. We used the boundary condition $\hat{Y}=0$ as well.

The bulk equations of motion give,

$$
\begin{align*}
Y & =\frac{1}{2}(z+\bar{z}+w+\bar{w}) \\
\tilde{Y} & =-(z+\bar{z}) \\
\hat{Y} & =\frac{i}{2}(z-\bar{z}-w+\bar{w}) \tag{4.26}
\end{align*}
$$

Inserting these equations of motion back into the bulk part of the action eq. (4.25) reproduces the generalized Kähler potential eq. (4.8). The Dirichlet boundary condition $\hat{Y}=0$ implies - using eq. (4.26) - the Dirichlet boundary condition in eq. (4.9) with $a=1$. So we do recover the D3-brane discussed previously. Varying either $Y$ or $\tilde{Y}$ in eq. (4.25) yields an expression which vanishes by virtue of the Dirichlet boundary condition. As a consequence the boundary term in the dual action vanishes as expected.

Next, we consider the coisotropic D4-brane constructed above, given by the Neumann boundary conditions,

$$
\begin{align*}
\overline{\mathbb{D}}(-2 i l+2 i \bar{l}+3 i r-i \bar{r}) & =0, & \mathbb{D}(-2 i l+2 i \bar{l}+i r-3 i \bar{r}) & =0  \tag{4.27}\\
\overline{\mathbb{D}}(-6 l-2 \bar{l}-5 r-\bar{r}) & =0, & \mathbb{D}(-2 l-6 \bar{l}-r-5 \bar{r}) & =0 \tag{4.28}
\end{align*}
$$

and the boundary potential eq. (4.21). The Neumann boundary conditions eq. (4.27) imply that $\tilde{Y}$ and $\hat{Y}$ together form a chiral boundary field,

$$
\begin{equation*}
\overline{\mathbb{D}}\left(\hat{Y}-\frac{i}{2} \tilde{Y}\right)=\mathbb{D}\left(\hat{Y}+\frac{i}{2} \tilde{Y}\right)=0 \tag{4.29}
\end{equation*}
$$

The first order action reads,

$$
\begin{align*}
\mathcal{S}=-\int & d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}\left((Y+\tilde{Y})^{2}+\hat{Y}^{2}-\tilde{Y}^{2}+i u \overline{\mathbb{D}}_{+} \overline{\mathbb{D}}_{-}(Y-\tilde{Y}-i \hat{Y})\right. \\
& \left.+i \bar{u}_{\mathbb{D}}^{+} \mathbb{D}_{-}(Y-\tilde{Y}+i \hat{Y})-i v \overline{\mathbb{D}}_{+} \mathbb{D}_{-}(Y+\tilde{Y}-i \hat{Y})-i \bar{v} \mathbb{D}_{+} \overline{\mathbb{D}}_{-}(Y+\tilde{Y}+i \hat{Y})\right) \\
& +i \int d \tau d^{2} \theta\left(-\hat{Y}(2 Y+\tilde{Y})-\frac{1}{2} \overline{\mathbb{D}}^{\prime} u\left(\overline{\mathbb{D}}^{\prime}(Y-\tilde{Y}-i \hat{Y})-\overline{\mathbb{D}}(Y+\tilde{Y}+i \hat{Y})\right)\right. \\
& +\frac{1}{2} \mathbb{D}^{\prime} \bar{u}\left(\mathbb{D}^{\prime}(Y-\tilde{Y}+i \hat{Y})-\mathbb{D}(Y+\tilde{Y}-i \hat{Y})\right)-v \overline{\mathbb{D}}_{+} \mathbb{D}_{-}(Y+\tilde{Y}-i \hat{Y}) \\
& \left.+\bar{v} \mathbb{D}_{+} \overline{\mathbb{D}}_{-}(Y+\tilde{Y}+i \hat{Y})\right), \tag{4.30}
\end{align*}
$$

where once more we inserted two additional terms in the boundary term such that the variation of $\overline{\mathbb{D}}^{\prime} u$ and $\mathbb{D}^{\prime} \bar{u}$ gives expressions consistent with the Neumann boundary conditions and the constraints eq. (2.47). After integrating this action by parts, we find the following action,

$$
\begin{align*}
\mathcal{S}= & -\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}\left((Y+\tilde{Y})^{2}+\hat{Y}^{2}-\tilde{Y}^{2}+Y(z+\bar{z}-w-\bar{w})\right. \\
& -\tilde{Y}(z+\bar{z}+w+\bar{w})-i \hat{Y}(z-\bar{z}-w+\bar{w})) \\
& +i \int d \tau d^{2} \theta(-\hat{Y}(2 Y+\tilde{Y})+i(Y+\tilde{Y})(w-\bar{w}+z-\bar{z})+\hat{Y}(w+\bar{w}-z-\bar{z})) . \tag{4.31}
\end{align*}
$$

The bulk analysis is similar to the previous case, with equations of motion given in eqs. (4.26). Varying the gauge field Y in the boundary term and imposing the equation of motion for $\hat{Y}$ yields the Dirichlet boundary condition,

$$
\begin{equation*}
i(w-\bar{w})=0, \tag{4.32}
\end{equation*}
$$

which is indeed the boundary condition eq. (4.9) for $a=0$. When varying $\tilde{Y}$ and $\hat{Y}$ in the boundary term, one should take into account that they are constrained at the boundary (see eq. (4.29)). Doing so correctly, one recovers again the Dirichlet boundary condition eq. (4.32).

### 4.2.2 The duality between a chiral and a twisted chiral field

Starting from a potential of the form $V(z+\bar{z}, \cdots)$ and $W(z+\bar{z}, \cdots)$, we write the first order action,

$$
\begin{align*}
\mathcal{S}=-\int & d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}\left(V(Y, \cdots)-i u \overline{\mathbb{D}}_{+} \mathbb{D}_{-} Y-i \bar{u} \mathbb{D}_{+} \overline{\mathbb{D}}_{-} Y\right) \\
& +i \int d \tau d^{2} \theta\left(W(Y, \cdots)-u \overline{\mathbb{D}}_{+} \mathbb{D}_{-} Y+\bar{u} \mathbb{D}_{+} \overline{\mathbb{D}}_{-} Y\right) . \tag{4.33}
\end{align*}
$$

Integrating over the complex unconstrained Lagrange multipliers $u$ and $\bar{u}$ brings us back to the original model. Upon integrating by parts one gets,

$$
\begin{align*}
\mathcal{S}=-\int & d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}(V(Y, \cdots)-Y(w+\bar{w})) \\
& +i \int d \tau d^{2} \theta(W(Y, \cdots)+i Y(w-\bar{w})), \tag{4.34}
\end{align*}
$$

where we introduced the twisted chiral fields $w=i \overline{\mathbb{D}}_{+} \mathbb{D}_{-} u$ and $\bar{w}=i \mathbb{D}_{+} \overline{\mathbb{D}}-\bar{u}$. Integrating over the unconstrained gauge field $Y$ gives us the dual model in terms of a twisted chiral field $w$.

We illustrate this with a simple example, a two-torus parameterized by a chiral field with Kähler potential $V=(z+\bar{z})^{2} / 2$. Either D0- or D2-brane configurations are allowed.

Let us start with a D0-brane. We take the Dirichlet boundary condition $z=(a+i b) / 2$ with $a, b \in \mathbb{R}$ and constant. The boundary potential vanishes. The first order action is given in eq. (4.33) where the gauge field $Y$ satisfies the boundary condition $Y=a$. Dualizing the model using eq. (4.34) we obtain the bulk equation of motion $Y=w+\bar{w}$ which - using the boundary condition for $Y$ - gives us the boundary condition for the twisted chiral field: $w+\bar{w}=a$. Performing the duality transformation gives the potentials,

$$
\begin{equation*}
V_{\text {dual }}=-\frac{1}{2}(w+\bar{w})^{2}, \quad W_{\text {dual }}=i a(w-\bar{w}) . \tag{4.35}
\end{equation*}
$$

So we end up with a lagrangian D1-brane whose position is determined by $w+\bar{w}=a$.
We now turn to the D2-brane. We still have the bulk potential $V=(z+\bar{z})^{2} / 2$ but we can now allow for a boundary potential as well, which for simplicity we choose as $F(z+\bar{z})^{2} / 2$ with $F \in \mathbb{R}$ and constant. The boundary conditions are fully Neumann and explicitly given by,

$$
\begin{equation*}
\mathbb{D}^{\prime} z=i F \mathbb{D} z, \quad \overline{\mathbb{D}}^{\prime} \bar{z}=-i F \overline{\mathbb{D}} \bar{z} \tag{4.36}
\end{equation*}
$$

Once more our starting point is the first order action eq. (4.33) where the gauge field $Y$ satisfies the boundary conditions $\mathbb{D}^{\prime} Y=i F \mathbb{D} Y$ and $\overline{\mathbb{D}}^{\prime} Y=-i F \overline{\mathbb{D}} Y$. Using eq. (4.34) we obtain the dual model. The bulk equation of motion gives $Y=w+\bar{w}$ which combined with the boundary conditions for $Y$ results in the boundary conditions $\mathbb{D}(-i(w-\bar{w})-$ $F(w+\bar{w}))=\overline{\mathbb{D}}(-i(w-\bar{w})-F(w+\bar{w}))=0$ where we used eq. (2.46). These equations are equivalent to a single Dirichlet boundary condition,

$$
\begin{equation*}
-i(w-\bar{w})=F(w+\bar{w}) . \tag{4.37}
\end{equation*}
$$

The potentials for the dual model are given by,

$$
\begin{equation*}
V_{\text {dual }}=-\frac{1}{2}(w+\bar{w})^{2}, \quad W_{\text {dual }}=-\frac{1}{2} F(w+\bar{w})^{2} . \tag{4.38}
\end{equation*}
$$

As was to be expected we find a lagrangian D1-brane whose position is determined by eq. (4.37).

The inverse transformation starts from potentials of the form $V(w+\bar{w}, \cdots)$ and $W(w+$ $\bar{w}, \cdots)$. One has

$$
\begin{align*}
& -\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}\left(V(\tilde{Y}, \cdots)-i u \overline{\mathbb{D}}_{+} \overline{\mathbb{D}}_{-} \tilde{Y}-i \bar{u} \mathbb{D}_{+} \mathbb{D}_{-} \tilde{Y}\right) \\
& +i \int d \tau d^{2} \theta\left(W(\tilde{Y}, \cdots)+\frac{1}{2} \overline{\mathbb{D}}^{\prime} u \overline{\mathbb{D}}^{\prime} \tilde{Y}-\frac{1}{2} \mathbb{D}^{\prime} \bar{u} \mathbb{D}^{\prime} \tilde{Y}\right) \\
& \quad=-\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}(V(\tilde{Y}, \cdots)-\tilde{Y}(z+\bar{z}))+i \int d \tau d^{2} \theta W(\tilde{Y}, \cdots), \tag{4.39}
\end{align*}
$$

where we have put $z=i \overline{\mathbb{D}}_{+} \overline{\mathbb{D}}_{-} u$ and $\bar{z}=i \mathbb{D}_{+} \mathbb{D}_{-} \bar{u}$.
Here more care is required with the treatment of the boundary term as we will illustrate with a simple example. Starting point is a lagrangian D1-brane with Kähler potential $V=-(w+\bar{w})^{2} / 2$ and whose position is determined by the Dirichlet boundary condition $-i(w-\bar{w})=m(w+\bar{w})$ with $m \in \mathbb{Z}$. As a consequence we find a boundary potential $W=-m(w+\bar{w})^{2} / 2$. From the boundary condition on the twisted chiral field we get the boundary conditions for the gauge field $\tilde{Y}: \mathbb{D}^{\prime} \tilde{Y}=i m \mathbb{D} \tilde{Y}$ and $\overline{\mathbb{D}}^{\prime} \tilde{Y}=-i m \overline{\mathbb{D}} \tilde{Y}$. We modify the expression in eq. (4.39) to,

$$
\begin{align*}
\mathcal{S}= & -\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}\left(-\frac{1}{2} \tilde{Y}^{2}-i u \overline{\mathbb{D}}_{+} \overline{\mathbb{D}}_{-} \tilde{Y}-i \bar{u} \mathbb{D}_{+} \mathbb{D}_{-} \tilde{Y}\right) \\
& +i \int d \tau d^{2} \theta\left(-\frac{m}{2} \tilde{Y}^{2}+\frac{1}{2} \overline{\mathbb{D}}^{\prime} u\left(\overline{\mathbb{D}}^{\prime} \tilde{Y}+i m \overline{\mathbb{D}} \tilde{Y}\right)-\frac{1}{2} \mathbb{D}^{\prime} \bar{u}\left(\mathbb{D}^{\prime} \tilde{Y}-i m \mathbb{D} \tilde{Y}\right)\right), \tag{4.40}
\end{align*}
$$

such that the variation of $\overline{\mathbb{D}}^{\prime} u$ and $\mathbb{D}^{\prime} \bar{u}$ in the boundary term precisely reproduces the boundary conditions for $\tilde{Y}$. Upon partial integration, this becomes,

$$
\begin{align*}
\mathcal{S}= & -\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}\left(-\frac{1}{2} \tilde{Y}^{2}-\tilde{Y}(z+\bar{z})\right) \\
& +i \int d \tau d^{2} \theta\left(-\frac{m}{2} \tilde{Y}^{2}-m \tilde{Y}(z+\bar{z})\right) \tag{4.41}
\end{align*}
$$

where we used $\overline{\mathbb{D}}_{+} \overline{\mathbb{D}}_{-}=-\overline{\mathbb{D}}^{\mathbb{D}^{\prime}} / 2$. Both the bulk and the boundary variation of $\tilde{Y}$ yields $\tilde{Y}=-(z+\bar{z})$ which results in the dual potentials,

$$
\begin{equation*}
V_{\text {dual }}=\frac{1}{2}(z+\bar{z})^{2}, \quad W_{\text {dual }}=\frac{m}{2}(z+\bar{z})^{2} \tag{4.42}
\end{equation*}
$$

Combining the boundary condition for $\tilde{Y}$ with the bulk equation of motion results in the Neumann boundary conditions for the chiral field: $\mathbb{D}^{\prime} z=i m \mathbb{D} z$ and $\overline{\mathbb{D}}^{\prime} \bar{z}=-i m \overline{\mathbb{D}} \bar{z}$ so that we end up with a D2-brane.

One can also dualize a lagrangian D1-brane on a two-torus parameterized by a twisted chiral superfield to a D0-brane. Let us start from the Kähler potential $V=-\frac{1}{2}(w+\bar{w})^{2}$ and the Dirichlet boundary condition $w+\bar{w}=-i n(w-\bar{w})$, with $n \in \mathbb{Z}$, describing the position of the D1-brane. For this model we can consider two different possible dualizations, depending on the value of $n$. If $n \neq 0$ we can dualize the D1-brane to a D2-brane with a worldvolume flux characterized by the integer $n$, analogous to the situation described
above. However, if $n=0$ the D1-brane is dualized to a D0-brane. The boundary potential vanishes in that case and the first order action we start from reads,

$$
\begin{align*}
\mathcal{S}= & -\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}\left(-\frac{1}{2} \tilde{Y}^{2}-i u \overline{\mathbb{D}}_{+} \overline{\mathbb{D}}_{-} \tilde{Y}-i \bar{u} \mathbb{D}_{+} \mathbb{D} \mathcal{D}_{-} \tilde{Y}\right) \\
& +i \int d \tau d^{2} \theta\left(+\frac{1}{2} \overline{\mathbb{D}}^{\prime} u \overline{\mathbb{D}}^{\prime} \tilde{Y}-\frac{1}{2} \mathbb{D}^{\prime} \bar{u} \mathbb{D}^{\prime} \tilde{Y}\right), \tag{4.43}
\end{align*}
$$

and $\tilde{Y}$ satisfies the boundary condition $\tilde{Y}=0$. When varying the Lagrange multipliers $u$ and $\bar{u}$ we recover the original model parameterized by a twisted chiral superfield. It is however crucial to notice that the fermionic derivatives of the Lagrange multipliers $\overline{\mathbb{D}}^{\prime} u$ and $\mathbb{D}^{\prime} \bar{u}$ should satisfy a Dirichlet boundary condition in order to reproduce the D1-brane with $n=0$. Upon integration by parts we find,

$$
\begin{equation*}
\mathcal{S}=-\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}\left(-\frac{1}{2} \tilde{Y}^{2}-\tilde{Y}(z+\bar{z})\right) . \tag{4.44}
\end{equation*}
$$

The bulk equation of motion reads $\tilde{Y}=-(z+\bar{z})$, while the boundary term vanishes completely. The dual potentials are therefore given by,

$$
\begin{equation*}
V_{\text {dual }}=\frac{1}{2}(z+\bar{z})^{2}, \quad W_{\text {dual }}=0 . \tag{4.45}
\end{equation*}
$$

Since the gauge field $\tilde{Y}$ satisfies the Dirichlet boundary condition $\tilde{Y}=0$, we conclude that the chiral field $z$ and its complex conjugate $\bar{z}$ also satisfy a Dirichlet boundary condition,

$$
\begin{equation*}
z=i b, \quad \bar{z}=-i b . \tag{4.46}
\end{equation*}
$$

Moreover, these Dirichlet boundary conditions are fully consistent with the Dirichlet boundary conditions for the Lagrange mulitpliers we had to impose in the original model. We thus find a D0-brane localized in the point $\operatorname{Re}(z)=0$ and $\operatorname{Im}(z)=b$, where $b$ is a free parameter.

## 5 Examples

### 5.1 The WZW model on $S^{3} \times S^{1}$ and its dual formulation

We will use the Hopf surface $S^{3} \times S^{1}$ - better known as the WZW-model on $\mathrm{SU}(2) \times \mathrm{U}(1)$ - as a non-trivial example of various issues discussed in the preceding two sections. We parameterize the Hopf surface with coordinates $z$ and $w$ where $z, w \in\left(\mathbb{C}^{2} \backslash 0\right) / \Gamma$ where $\Gamma$ is generated by $(z, w) \rightarrow\left(e^{2 \pi} z, e^{2 \pi} w\right)$. The connection with the group manifold $\mathrm{SU}(2) \times \mathrm{U}(1)$ is made explicit when parameterizing a group element as,

$$
\mathcal{G}=\frac{e^{-i \ln \sqrt{z \bar{z}+w \bar{w}}}}{\sqrt{z \bar{z}+w \bar{w}}}\left(\begin{array}{cc}
w & \bar{z}  \tag{5.1}\\
-z & \bar{w}
\end{array}\right) .
$$

A very useful parameterization is in terms of Hopf coordinates $\phi_{1}, \phi_{2}, \rho \in \mathbb{R} \bmod 2 \pi$ and $\psi \in[0, \pi / 2]$ where we put,

$$
\begin{equation*}
z=\cos \psi e^{\rho+i \phi_{1}}, \quad w=\sin \psi e^{\rho+i \phi_{2}} . \tag{5.2}
\end{equation*}
$$

In [42] it was shown that any WZW-model which has an even-dimensional target manifold has $N \geq(2,2)$. In [43] an explicit formulation of the $\mathrm{SU}(2) \times \mathrm{U}(1)$ model was given in terms of a chiral and a twisted chiral superfield. ${ }^{11}$ The chiral superfield $z$ and the twisted chiral superfield $w$ are precisely identified with the coordinates $z$ and $w$ introduced above. The generalized Kähler potential was found to be,

$$
\begin{equation*}
V(z, \bar{z}, w, \bar{w})=+\int^{z \bar{z} / w \bar{w}} \frac{d q}{q} \ln (1+q)-\frac{1}{2}(\ln w \bar{w})^{2} \tag{5.3}
\end{equation*}
$$

which is everywhere well defined except when $w=0$. However - as noted in [23] — we can rewrite the generalized Kähler potential as,

$$
\begin{equation*}
V(z, \bar{z}, w, \bar{w})=-\int^{w \bar{w} / z \bar{z}} \frac{d q}{q} \ln (1+q)+\frac{1}{2}(\ln z \bar{z})^{2}-\ln (z \bar{z}) \ln (w \bar{w}) \tag{5.4}
\end{equation*}
$$

where the last term can be removed by a generalized Kähler transformation resulting in an expression for the potential well defined in $w=0$ (but not in $z=0$ ). The non-vanishing components of the metric are in these coordinates,

$$
\begin{equation*}
g_{z \bar{z}}=g_{w \bar{w}}=\frac{1}{z \bar{z}+w \bar{w}} \tag{5.5}
\end{equation*}
$$

and we get for the torsion 3 -form,

$$
\begin{equation*}
H_{z \bar{z} w}=-\frac{1}{2} \frac{\bar{w}}{(z \bar{z}+w \bar{w})^{2}}, \quad H_{z w \bar{w}}=-\frac{1}{2} \frac{\bar{z}}{(z \bar{z}+w \bar{w})^{2}} \tag{5.6}
\end{equation*}
$$

and complex conjugates. In [23], D1- and D3-branes on $S^{3} \times S^{1}$ were explicitely constructed using the above formulation. Below we will show that D2- and D4 branes exist as well on $S^{3} \times S^{1}$, although they require a semi-chiral parameterization of the Hopf surface.

By making a different choice for the complex structures on $S^{3} \times S^{1}$ an alternative parameterization in terms of a semi-chiral multiplet was found in [10]. The generalized Kähler potential is now,

$$
\begin{equation*}
V(l, \bar{l}, r, \bar{r})=\ln \frac{l}{\bar{r}} \ln \frac{\bar{l}}{r}-\int^{r \bar{r}} \frac{d q}{q} \ln (1+q) \tag{5.7}
\end{equation*}
$$

Using this we calculate the metric,

$$
\begin{equation*}
g_{l \bar{l}}=\frac{1}{l \bar{l}}, \quad g_{r \bar{r}}=\frac{1}{r \bar{r}} \frac{1}{1+r \bar{r}}, \quad g_{l r}=-\frac{1}{l r} \frac{1}{1+r \bar{r}}, \quad g_{\bar{l} \bar{r}}=-\frac{1}{\bar{l} \bar{r}} \frac{1}{1+r \bar{r}} \tag{5.8}
\end{equation*}
$$

and the torsion 3 -form,

$$
\begin{equation*}
H_{l r \bar{r}}=-\frac{1}{l} \frac{1}{(1+r \bar{r})^{2}}, \quad H_{\bar{l} \bar{r}}=+\frac{1}{\bar{l}} \frac{1}{(1+r \bar{r})^{2}} \tag{5.9}
\end{equation*}
$$

Geometrically the two parametrizations are related by the coordinate transformation,

$$
\begin{equation*}
l=w, \quad \bar{l}=\bar{w}, \quad r=\frac{\bar{w}}{z}, \quad \bar{r}=\frac{w}{\bar{z}} . \tag{5.10}
\end{equation*}
$$

[^10]One easily verifies that the expressions for the metric and torsion are indeed equivalent in both coordinate systems. The complex structures in both formulations are obviously different. In the chiral/twisted chiral formulation we find that $J_{+}$and $J_{-}$are diagonal where $J_{+}$has eigenvalue $+i$ on $d z$ and $d w$ while for $J_{-}$one finds eigenvalue $+i$ on $d z$ and eigenvalue $-i$ on $d w$. In the semi-chiral parameterization we find for $J_{+}$and $J_{-}$,

$$
\begin{align*}
& J_{+}=\left(\begin{array}{cccc}
+i & 0 & 0 & 0 \\
0 & -i & 0 & 0 \\
0 & -2 i \frac{r}{l}+i & 0 \\
+2 i \frac{\bar{r}}{l} & 0 & 0 & -i
\end{array}\right), \\
& J_{-}=\left(\begin{array}{cccc}
i & 0 & 0 & -2 i \frac{l}{\bar{r}} \frac{1}{1+r \bar{r}} \\
0 & -i+2 i \frac{\bar{l}}{r} \frac{1}{1+r \bar{r}} & 0 \\
0 & 0 & +i & 0 \\
0 & 0 & 0 & -i
\end{array}\right) . \tag{5.11}
\end{align*}
$$

where we labelled the rows and columns in the order $l \bar{l} r \bar{r}$.
In [23] D1- and D3-branes were constructed on $S^{3} \times S^{1}$ in the chiral/twisted chiral parameterization. In this section we will study lagrangian D 2 -branes and maximally coisotropic D4-branes on $S^{3} \times S^{1}$ in its semi-chiral parameterization. As the direct construction of such branes is rather non-trivial we will make use of a duality transformation. Indeed the semi-chiral model on $S^{3} \times S^{1}$ is dual to a model on $T^{2} \times D$ where $T^{2}$ is parameterized by a twisted chiral and $D$ (the disk) by a chiral field. In the dual model it is very easy to construct general D1- and D3-brane configurations which when dualizing back to $S^{3} \times S^{1}$ will give rise to the desired D2- and D4-branes.

We make a coordinate transformation in eq. (5.7) by replacing $l$ by $e^{l}$ and $r$ by $e^{-r}$ which gives,

$$
\begin{align*}
V(l, \bar{l}, r, \bar{r}) & =(l+\bar{r})(\bar{l}+r)+\int^{r+\bar{r}} d q \ln \left(1+e^{-q}\right) \\
& =\frac{1}{4}(l+\bar{l}+r+\bar{r})^{2}-\frac{1}{4}(l-\bar{l}-r+\bar{r})^{2}+\int^{r+\bar{r}} d q \ln \left(1+e^{-q}\right) \tag{5.12}
\end{align*}
$$

In these coordinates we get that the two-form $\Omega^{(-)}$defined in eq. (2.20) is explicitly given by,

$$
\begin{equation*}
\Omega_{l \bar{l}}^{(-)}=\Omega_{l r}^{(-)}=\Omega_{\bar{r} \bar{l}}^{(-)}=-i, \quad \Omega_{l \bar{r}}^{(-)}=\Omega_{\bar{l} r}^{(-)}=0, \quad \Omega_{r \bar{r}}^{(-)}=\frac{i}{1+e^{-r-\bar{r}}} . \tag{5.13}
\end{equation*}
$$

The potential eq. (5.12) is readily dualized to,

$$
\begin{align*}
V_{\text {dual }} & =-(z+\bar{z}-w-\bar{w})^{2}+(z-\bar{z}-w+\bar{w})^{2}-2 \int^{z+\bar{z}} d q \ln \left(e^{-2 q}-1\right) \\
& =-4(z-w)(\bar{z}-\bar{w})-2 \int^{z+\bar{z}} d q \ln \left(e^{-2 q}-1\right) \tag{5.14}
\end{align*}
$$

Modulo a generalized Kähler transformation, one finds that the dual potential factorizes in a part which describes a disk, $\operatorname{Re} z \leq 0$ and a part which describes a two torus,
$w \simeq w+\pi\left(n_{1}+i n_{2}\right)$ with $n_{1}, n_{2} \in \mathbb{Z} .{ }^{12}$ Here it is rather straightforward (see [23]) to construct globally well defined D-brane configurations. We have two cases.

1. A D1-brane

The position of the D1-brane is given by the three Dirichlet boundary conditions,

$$
\begin{align*}
-i(w-\bar{w}) & =\frac{m}{n}(w+\bar{w}), \\
z & =\frac{1}{2}(a+i b), \quad \bar{z}=\frac{1}{2}(a-i b), \tag{5.15}
\end{align*}
$$

where $m, n \in \mathbb{Z}, a, b \in \mathbb{R}$ and constant and $a \leq 0$. In order to be consistent we need - besides the bulk potential in eq. (5.14) - a boundary potential given by,

$$
\begin{equation*}
W_{\text {dual }}=2\left(\frac{m}{n} a-b\right)(w+\bar{w}) \tag{5.16}
\end{equation*}
$$

2. A D3-brane

The position of the D3-brane is fixed by the Dirichlet boundary condition,

$$
\begin{equation*}
-i(w-\bar{w})=\frac{m}{n}(w+\bar{w})+\alpha z+\bar{\alpha} \bar{z} \tag{5.17}
\end{equation*}
$$

where $m, n \in \mathbb{Z}$ and $\alpha \in \mathbb{C}$. Consistency requires the presence of a boundary potential,

$$
\begin{equation*}
W_{\text {dual }}=2\left(\alpha z+\bar{\alpha} \bar{z}+i(z-\bar{z})+\frac{m}{n}(z+\bar{z})\right)(w+\bar{w})+g(z+\bar{z}) \tag{5.18}
\end{equation*}
$$

where $g$ is an arbitrary real function of $z+\bar{z}$.
We have now all ingredients which will allow us to dualize this to lagrangian D2-branes and maximally coisotropic D4-branes on the Hopf surface $S^{3} \times S^{1}$.
5.2 From D1-branes on $T^{2} \times D$ to D2-branes on $S^{3} \times S^{1}$

The Dirichlet boundary conditions given in eq. (5.15) imply the following Dirichlet boundary conditions on the gauge fields,

$$
\begin{align*}
Y & =a \\
\hat{Y} & =-b+\frac{m}{n} \tilde{Y} \tag{5.19}
\end{align*}
$$

Using this, the first order action eq. (4.7) becomes,

$$
\begin{align*}
\mathcal{S}= & -\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}\left(V(Y, \tilde{Y}, \hat{Y})_{\mathrm{dual}}+Y(l+\bar{l}-r-\bar{r})-\tilde{Y}(l+\bar{l}+r+\bar{r})\right. \\
& -i \hat{Y}(l-\bar{l}-r+\bar{r}))+i \int d \tau d^{2} \theta\left(\left(2\left(\frac{m}{n} a-b\right)+i(l-\bar{l}-r+\bar{r})\right.\right. \\
& \left.\left.-\frac{m}{n}(l+\bar{l}+r+\bar{r})\right) \tilde{Y}+b(l+\bar{l}+r+\bar{r})-i a(l-\bar{l}+r-\bar{r})\right) \tag{5.20}
\end{align*}
$$

[^11]Varying $\tilde{Y}$ in the boundary term gives a Dirichlet boundary condition which is compatible with a combination of the boundary conditions for the gauge fields and the bulk equations of motion of the gauge fields. Integrating over the gauge fields gives in this way a D2-brane on $S^{3} \times S^{1}$ whose position is given by,

$$
\begin{align*}
r+\bar{r} & =-\ln \left(e^{-2 a}-1\right) \\
r-\bar{r} & =l-\bar{l}+i \frac{m}{n}(l+\bar{l})+i\left(2 b-\frac{m}{n} \ln \left(1-e^{2 a}\right)\right) \tag{5.21}
\end{align*}
$$

The bulk potential is given in eq. (5.12) and the boundary potential is now,

$$
\begin{equation*}
W=\left(b+\frac{m}{n} a\right)(l+\bar{l})-2 i a(l-\bar{l}) \tag{5.22}
\end{equation*}
$$

One checks that the Dirichlet boundary conditions in terms of Hopf coordinates are rephrased as,

$$
\begin{align*}
\psi & =\arcsin \sqrt{1-e^{2 a}} \in\left[0, \frac{\pi}{2}\right] \\
\phi_{1} & =\frac{m}{n} \rho+b \tag{5.23}
\end{align*}
$$

where we used $a \neq 0$. This is indeed a lagrangian brane with respect to the symplectic form given in eq. (5.13). It is gratifying to notice - see eq. (5.23) - that also globally everything works out perfectly.

### 5.3 From D3-branes on $T^{2} \times D$ to D2-branes on $S^{3} \times S^{1}$

Taking $\operatorname{Im} \alpha=-1$ allows us to translate the Dirichlet boundary condition in eq. (5.17) into a Dirichlet boundary condition for the gauge fields,

$$
\begin{equation*}
\hat{Y}=a Y+\frac{m}{n} \tilde{Y} \tag{5.24}
\end{equation*}
$$

where $a \equiv \operatorname{Re} \alpha$. Using this we rewrite the first order action eq. (4.7) as,

$$
\begin{align*}
\mathcal{S}= & -\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}\left(V(Y, \tilde{Y}, \hat{Y})_{\mathrm{dual}}+Y(l+\bar{l}-r-\bar{r})-\tilde{Y}(l+\bar{l}+r+\bar{r})\right. \\
& -i \hat{Y}(l-\bar{l}-r+\bar{r}))+i \int d \tau d^{2} \theta\left(2\left(a+\frac{m}{n}\right) Y \tilde{Y}+g(Y)\right. \\
& -Y((a+i) l+(a-i) \bar{l}+(a+i) r+(a-i) \bar{r})- \\
& \left.\tilde{Y}\left(\left(\frac{m}{n}-i\right) l+\left(\frac{m}{n}+i\right) \bar{l}+\left(\frac{m}{n}+i\right) r+\left(\frac{m}{n}-i\right) \bar{r}\right)\right) \tag{5.25}
\end{align*}
$$

Varying $\tilde{Y}$ in the boundary term in eq. (5.25) gives a Dirichlet boundary condition which upon using the bulk equations of motion is equivalent to eq. (5.24). Varying $Y$ in the boundary term in eq. (5.25) gives a second Dirichlet boundary condition so that we end
up with a D2-brane on $S^{3} \times S^{1}$. Explicitly the Dirichlet boundary conditions are,

$$
\begin{align*}
-i(l-\bar{l})= & a(l+\bar{l}+r+\bar{r})-\frac{1}{2} g^{\prime}\left(-\frac{1}{2} \ln \left(1+e^{-(r+\bar{r})}\right)\right) \\
-i(r-\bar{r})= & \left(a+\frac{m}{n}\right)\left(l+\bar{l}+r+\bar{r}+\ln \left(1+e^{-(r+\bar{r})}\right)\right) \\
& -\frac{1}{2} g^{\prime}\left(-\frac{1}{2} \ln \left(1+e^{-(r+\bar{r})}\right)\right) \tag{5.26}
\end{align*}
$$

In Hopf coordinates this gives,

$$
\begin{align*}
& \phi_{1}=\frac{m}{n} \rho-a \ln (\cos \psi) \\
& \phi_{2}=a \rho+a \ln (\cos \psi)-\frac{1}{4} g^{\prime}(\ln (\cos \psi)) \tag{5.27}
\end{align*}
$$

Using the Dirichlet boundary conditions and the equations of motion we can write the dual boundary potential as,

$$
\begin{align*}
W_{\text {dual }}= & \frac{1}{2} \ln \left(1+e^{-(r+\bar{r})}\right)((a+i) l+(a-i) \bar{l}+(a+i) r+(a-i) \bar{r}) \\
& +g\left(-\frac{1}{2} \ln \left(1+e^{-(r+\bar{r})}\right)\right) . \tag{5.28}
\end{align*}
$$

Neglecting the function $g^{\prime}(\ln (\cos \psi))$ (by interpreting it as a manner to describe fluctuations of the D2-branes) one can easily check that the pullback of the two-form in eq. (5.13) w.r.t. the D 2 -brane vanishes. Also this D 2 -brane is a lagrangian brane w.r.t. the symplectic form in eq. (5.13).

### 5.4 From D3-branes on $T^{2} \times D$ to D4-branes on $S^{3} \times S^{1}$

For generic values of $\alpha$ we find that the Dirichlet boundary condition eq. (5.17) implies,

$$
\begin{align*}
\overline{\mathbb{D}}\left(\hat{Y}+(i-\bar{\alpha}) Y-\frac{m}{n} \tilde{Y}\right) & =0 \\
\mathbb{D}\left(\hat{Y}+(-i-\alpha) Y-\frac{m}{n} \tilde{Y}\right) & =0, \tag{5.29}
\end{align*}
$$

which implies that $Z^{1} \equiv\left(\hat{Y}+(i-\bar{\alpha}) Y-\frac{m}{n} \tilde{Y}\right)$ is a boundary chiral field. Note that if $\operatorname{Im} \alpha=-1$, the boundary chiral field is real and as a consequence is a constant which is precisely the case previously studied. For simplicity we take here $\alpha=0$ and we find that

$$
\begin{equation*}
Z^{1}=\hat{Y}+i Y-\frac{m}{n} \tilde{Y} \tag{5.30}
\end{equation*}
$$

is a boundary chiral field. Using this we write the first order action eq. (4.7) as,

$$
\begin{align*}
\mathcal{S}= & -\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime}\left(V(Y, \tilde{Y}, \hat{Y})_{\text {dual }}+Y(l+\bar{l}-r-\bar{r})-\tilde{Y}(l+\bar{l}+r+\bar{r})\right. \\
& -i \hat{Y}(l-\bar{l}-r+\bar{r}))+i \int d \tau d^{2} \theta\left(\left(Z^{1}+\bar{Z}^{\overline{1}}\right) \tilde{Y}-i \frac{m}{n}\left(Z^{1}-\bar{Z}^{\overline{1}}\right) \tilde{Y}\right. \\
& +g\left(-\frac{i}{2}\left(Z^{1}-\bar{Z}^{\overline{1}}\right)\right)-\frac{1}{2}\left(Z^{1}-\bar{Z}^{\overline{1}}\right)(l-\bar{l}+r-\bar{r})+i \tilde{Y}(l-\bar{l}-r+\bar{r}) \\
& \left.-\frac{m}{n} \tilde{Y}(l+\bar{l}+r+\bar{r})-\frac{1}{2}\left(Z^{1}+\bar{Z}^{\overline{1}}\right)(l+\bar{l}+r+\bar{r})\right) . \tag{5.31}
\end{align*}
$$

Varying the unconstrained field $\tilde{Y}$ in the boundary term yields an equation fully compatible with the bulk equations of motion. When varying $Z^{1}$ and $\bar{Z}^{\overline{1}}$ in the boundary term one needs to take into account that they are constrained fields. This variation implies the existence of a second boundary chiral field $Z^{2}$,

$$
\begin{equation*}
Z^{2}=\tilde{Y}-\frac{1}{2}(l+\bar{l}+r+\bar{r})-\frac{1}{2}(l-\bar{l}+r-\bar{r})-i\left(\frac{1}{2} g^{\prime}(Y)+\frac{m}{n} \tilde{Y}\right), \tag{5.32}
\end{equation*}
$$

where a prime denotes a derivative. The variation of $Z^{1}$ and $\bar{Z}^{\overline{1}}$ in the boundary term gives $\overline{\mathbb{D}} Z^{2}=\mathbb{D} \bar{Z}^{\overline{2}}=0$. Hence, we constructed a (space-filling) coisotropic D4-brane with the complex structure $K$ w.r.t. the basis $\{l, \bar{l}, r, \bar{r}\}$ given by,
$K=\frac{i}{2 n}\left(\begin{array}{cccc}2 n+(n+i m) e^{r+\bar{r}} & -(n-i m) e^{r+\bar{r}} & -(n-i m) \frac{e^{2 r+2 \bar{r}}}{1+e^{2+\bar{r}}} & \frac{2 n+(n+i m) e^{r+\bar{r}}}{1+e^{-(r+\bar{r}}} \\ (n+i m) e^{r+\bar{r}} & -2 n-(n-i m) e^{r+\bar{r}} & -\frac{2 n+(n-i m)}{\left.1+e^{-(r+r}\right)} \\ -(n+i m) e^{r+\bar{r}} & (n-i m)\left(2+e^{r+\bar{r}}\right) & 2 n+(n-i m) e^{r+\bar{r}} & -(n+i m) \frac{e^{2 r+2 \bar{r}}}{1+e^{r+\bar{r}}} \\ -(n+i m)\left(2+e^{r+\bar{r}}\right) & (n-i m) e^{+\bar{r}} & (n-i m) e^{r+\bar{r}} & -2 n-(n+i m) e^{r+\bar{r}}\end{array}\right)$.
The dual boundary potential reads,

$$
\begin{align*}
W_{\text {dual }}= & \frac{1}{2}(l+\bar{l}+r+\bar{r})\left[i(l-\bar{l}-r-\bar{r})-\frac{m}{n}(l+\bar{l}+r+\bar{r})\right] \\
& +\frac{1}{2} \ln \left(1+e^{-(r+\bar{r})}\right)\left[i(l-\bar{l}+r-\bar{r})-\frac{m}{n}(l+\bar{l}+r+\bar{r})\right] \\
& +g\left(-\frac{1}{2} \ln \left(1+e^{-(r+\bar{r})}\right)\right) \tag{5.33}
\end{align*}
$$

which can also be written in terms of the boundary chiral fields as follows, when ignoring total derivative terms,

$$
\begin{align*}
W_{\text {dual }}= & -\frac{1}{4}\left(1-i \frac{m}{n}\right) Z^{1} \bar{Z}^{\overline{2}}-\frac{1}{4}\left(1+i \frac{m}{n}\right) \bar{Z}^{\overline{1}} Z^{2}-\frac{m}{2 n} Z^{1} \bar{Z}^{\overline{1}} \\
& +\frac{i}{2}\left(Z^{1}-\bar{Z}^{\overline{1}}\right) g^{\prime}\left(-\frac{i}{2}\left(Z^{1}-\bar{Z}^{\overline{1}}\right)\right)+g\left(-\frac{i}{2}\left(Z^{1}-\bar{Z}^{\overline{1}}\right)\right) . \tag{5.34}
\end{align*}
$$

So we arrive at the conclusion that $S^{3} \times S^{1}$ (or the WZW model on $\left.\mathrm{SU}(2) \times \mathrm{U}(1)\right)$ allows for D1, D3, D2 and D4 supersymmetric brane configurations. We need the description of $S^{3} \times S^{1}$ in terms of a twisted chiral and a chiral field if we have D1- or D3-branes [23]. Lagrangian D2-branes or maximally coisotropic D4-branes require the semi-chiral description. From the above it should be clear that duality transformations provide for a powerful method to construct highly non-trivial supersymmetric D-brane configurations.

## 6 Conclusions and discussion

The off-shell description of a general $d=2, N=(2,2)$ supersymmetric non-linear $\sigma$-model requires semi-chiral, twisted chiral and chiral superfields. In the present paper we identified the allowed boundary conditions for these fields. The cleanest case is where only semi-chiral and twisted chiral fields are involved. These fields share the property that they are a priori
unconstrained on the boundary. For these fields two classes of boundary conditions are possible: either we impose a Dirichlet boundary condition - which in its turn implies a Neumann boundary condition as well - or we require them to be chiral on the boundary. The result is a straightforward generalization of A-branes on Kähler manifolds: the allowed D-brane configurations are either lagrangian or coisotropic with respect to the symplectic structure $\Omega^{(-)}=2 g\left(J_{+}-J_{-}\right)^{-1}$. When no semi-chiral superfields are present, $\Omega^{(-)}$reduces to the Kähler two-form and we recover the usual lagrangian and coisotropic A-branes on Kähler manifolds. Once semi-chiral superfields are present as well, non-Kähler geometries become possible, but the notion of lagrangian and coisotropic branes carries over. An example of this are the lagrangian D2-branes and the maximally coisotropic D4-branes on $S^{3} \times S^{1}$ (which is certainly not a Kähler manifold).

The picture gets murkier once chiral fields get involved. Chiral fields remain chiral i.e. constrained - on the boundary. When only chiral fields are present, the situation is still quite simple. The branes wrap around holomorphic cycles of Kähler manifold. These are nothing but the standard B-branes on Kähler manifolds.

Once all three types of superfields are present we get into a situation interpolating between the two cases mentioned above. In general the target manifold is not symplectic anymore, however any bihermitian manifold is still a Poisson manifold. This allows us to view the resulting D-brane configurations as generalized coisotropic submanifolds defined through a foliation of the Poisson manifold by symplectic leaves.

While the precise form of the torsion potential $b$ is gauge dependent, we found that there is a particular gauge such that $\Omega_{+}=-(g-b) J_{+}$is a closed two-form. As - at least with this definition - this two-form is not globally defined, it does not define a symplectic structure. However, when it is globally defined it allows for an alternative classification of the allowed supersymmetric D-brane configurations. Consider e.g. the four-dimensional case. When described in terms of two chiral fields, we can have D0-, D2- or D4-branes which are all symplectic submanifolds with respect to $\Omega_{+}$. Having one chiral and one twisted chiral superfield gives a D1-brane which is isotropic and a D3-brane which is coisotropic. Finally a semi-chiral multiplet or two twisted chiral fields gives a lagrangian D2-brane or a maximally coisotropic D4-brane. The latter case is indeed always lagrangian or coisotropic as $\Omega_{+}$coincides with the symplectic structure $\Omega^{(-)}$.

An unexpected ${ }^{13}$ result of the present analysis is the fact that supersymmetric D0and D1-branes are rather "rare". Indeed, the only way to get a D0-brane is by imposing Dirichlet boundary conditions in all directions. This is only possible if the model is formulated in terms of chiral superfields only. So supersymmetric D0-branes are always B-branes on Kähler manifolds! Similarly, in order to obtain D1-branes, we need a single twisted chiral and an arbitrary number of chiral fields. The fact that D0- and D1-branes behave differently from the other D-branes is somewhat puzzling (note however that such an unusual behaviour of D0- and D1-branes viz. other Dp-branes was - though in a very different context - already seen before [49]).

The superspace formulation of these models allows for the study of T-duality trans-

[^12]formations while keeping the $N=2$ supersymmetry manifest. As usual, the possibility of making a T-duality transformation requires the existence of an isometry in the target manifold geometry. Having an isometry which acts on chiral or twisted chiral fields only results in a T-duality transformation which exchanges chiral and twisted chiral fields. An isometry which mixes chiral and twisted chiral fields non trivially yields a T-duality transformation which exchanges a pair consisting of a twisted chiral and a chiral field for a semi-chiral multiplet. The inverse transformation exists as well. A consequence of this is that these duality transformations often simplify the construction of D-branes. e.g. coisotropic branes require the existence of an additional complex structure on (a subspace of) the worldvolume. As we illustrate in this paper, such branes can often be obtained through a T-duality transformation from much simpler brane configurations.

Looking at the case relevant to compactified string theory, we arrive at the following possible parametrizations of a six dimensional target manifold. We denote chiral fields by $z$, twisted chiral fields by $w$ and semi-chiral fields by $l$ and $r$.
$z_{1}, z_{2}, z_{3}$ : The geometry is necessarily Kähler and one can have D0-, D2-, D4- and D6branes wrapping holomorphic cycles.
$z_{1}, z_{2}, w_{3}$ : A non-trivial $H$-flux can be present. One can have D1-, D3- or D5-branes where the branes wrap holomorphic cycles in the chiral directions and a lagrangian submanifold in the twisted chiral direction.
$z_{1}, w_{2}, w_{3}$ : Once more a non-trivial $H$-flux might be present. There are D2- or D4-brane configurations which wrap a holomorphic cycle in the chiral direction and which are lagrangian in the twisted chiral directions. Also D4- and D6-branes can be possible where the branes are now maximally coisotropic in the twisted chiral directions.
$w_{1}, w_{2}, w_{3}$ : The geometry is again Kähler. One either has a lagrangian D3-brane or a coisotropic D5-brane.
$l, r, z$ : A non-trivial $H$-flux can be present. When the branes wrap a lagrangian submanifold in the semi-chiral directions we can have D2- or D4-branes. When the brane is maximally coisotropic in the semi-chiral directions we have D4- or D6-branes.
$l, r, w$ : Once more a non-trivial $H$-flux can be present. We either have a lagrangian D3-brane or a coisotropic D5-brane.

Presently an analysis of supersymmetric branes on various tori described by any of the superfield combinations given above is being investigated with applications along the lines of [44] in mind.

The whole analysis in this paper was performed at the classical level. In order to make contact with the ( $\alpha^{\prime}$ corrected) supergravity equations of motion and their solutions, one needs to study the superconformal invariance of these models at the quantum level. Having no boundaries, the one loop $\beta$-function for a general $N=(2,2)$ non-linear $\sigma$-model was calculated and analysed in [45] and recently shown to be consistent with supergravity results [46]. The results in this paper are perfectly tailored for a systematic study of
the one-loop $\beta$-functions in the presence of D-branes. As argued in [27], the superspace treatment automatically yields the stability conditions for the supersymmetric D-branes which would allow to extend and reinterpret the results of [47] in a more physical context. Work in this direction is now in progress. We would also like to stress that an economic formulation of $\sigma$-models with the dilaton in $N=(2,2)$ or $N=2$ superspace would be most useful for numerous applications.

Finally a study of D- and F-terms in $N=2$ boundary superspace using the technology developed in the present paper might be very interesting. Indeed, supersymmetric Dbranes sometimes cease to remain supersymmetric when a small closed string perturbation is switched on. Another interesting event is when a D-brane decays into a superposition of D-branes when crossing a line of marginal stability (for both phenomena see e.g. [50]). A manifest supersymmetric formulation might reveal the systematics of this.

## Acknowledgments

We thank Matthias Gaberdiel, Jim Gates, Chris Hull, Paul Koerber, Ulf Lindström, Martin Roček and Maxim Zabzine for useful discussions and suggestions. AS and WS are supported in part by the Belgian Federal Science Policy Office through the Interuniversity Attraction Pole P6/11, and in part by the "FWO-Vlaanderen" through project G.0428.06. AW is supported in part by grant 070034022 from the Icelandic Research Fund.

## A Conventions, notations and identities

The conventions used in the present paper are essentially the same as those in [23] and [22]. However we did modify some of the notations. The torsion which was previously called $T$ is now more conventionally renamed to $H$. Semi-chiral fields were previously labelled by $r, \bar{r}, s$ and $\bar{s}$ and are now called $l, \bar{l}, r$ and $\bar{r}$.

We denote the worldsheet coordinates by $\tau \in \mathbb{R}$ and $\sigma \in \mathbb{R}, \sigma \geq 0$, and the worldsheet light-cone coordinates are defined by,

$$
\begin{equation*}
\sigma^{\neq}=\tau+\sigma, \quad \sigma^{=}=\tau-\sigma \tag{A.1}
\end{equation*}
$$

The $N=(1,1)$ (real) fermionic coordinates are denoted by $\theta^{+}$and $\theta^{-}$and the corresponding derivatives satisfy,

$$
\begin{equation*}
D_{+}^{2}=-\frac{i}{2} \partial_{\neq}, \quad D_{-}^{2}=-\frac{i}{2} \partial_{=}, \quad\left\{D_{+}, D_{-}\right\}=0 \tag{A.2}
\end{equation*}
$$

The $N=(1,1)$ integration measure is explicitely given by,

$$
\begin{equation*}
\int d^{2} \sigma d^{2} \theta=\int d^{2} \sigma D_{+} D_{-} \tag{A.3}
\end{equation*}
$$

Passing from $N=(1,1)$ to $N=(2,2)$ superspace requires the introduction of two more real fermionic coordinates $\hat{\theta}^{+}$and $\hat{\theta}^{-}$where the corresponding fermionic derivatives satisfy,

$$
\begin{equation*}
\hat{D}_{+}^{2}=-\frac{i}{2} \partial_{\neq}, \quad \hat{D}_{-}^{2}=-\frac{i}{2} \partial_{=} \tag{A.4}
\end{equation*}
$$

and again all other - except for (A.2) - (anti-)commutators do vanish. The $N=(2,2)$ integration measure is,

$$
\begin{equation*}
\int d^{2} \sigma d^{2} \theta d^{2} \hat{\theta}=\int d^{2} \sigma D_{+} D_{-} \hat{D}_{+} \hat{D}_{-} . \tag{A.5}
\end{equation*}
$$

Quite often a complex basis is used,

$$
\begin{equation*}
\mathbb{D}_{ \pm} \equiv \hat{D}_{ \pm}+i D_{ \pm}, \quad \overline{\mathbb{D}}_{ \pm} \equiv \hat{D}_{ \pm}-i D_{ \pm}, \tag{A.6}
\end{equation*}
$$

which satisfy,

$$
\begin{equation*}
\left\{\mathbb{D}_{+}, \overline{\mathbb{D}}_{+}\right\}=-2 i \partial_{\neq}, \quad\left\{\mathbb{D}_{-},, \overline{\mathbb{D}}_{-}\right\}=-2 i \partial_{=}, \tag{A.7}
\end{equation*}
$$

and all other anti-commutators do vanish.
When dealing with boundaries in $N=(2,2)$ superspace, we introduce various derivatives as linear combinations of the previous ones. We summarize their definitions together with the non-vanishing anti-commutation relations. We have,

$$
\begin{align*}
& D \equiv D_{+}+D_{-}, \quad \hat{D} \equiv \hat{D}_{+}+\hat{D}_{-}, \\
& D^{\prime} \equiv D_{+}-D_{-}, \quad \hat{D}^{\prime} \equiv \hat{D}_{+}-\hat{D}_{-}, \tag{A.8}
\end{align*}
$$

with,

$$
\begin{align*}
D^{2} & =\hat{D}^{2}=D^{\prime 2}=\hat{D}^{\prime 2}=-\frac{i}{2} \partial_{\tau}, \\
\left\{D, D^{\prime}\right\} & =\left\{\hat{D}, \hat{D}^{\prime}\right\}=-i \partial_{\sigma} . \tag{A.9}
\end{align*}
$$

In addition we also use,

$$
\begin{array}{ll}
\mathbb{D} \equiv \mathbb{D}_{+}+\mathbb{D}_{-}=\hat{D}+i D, & \mathbb{D}^{\prime} \equiv \mathbb{D}_{+}-\mathbb{D}_{-}=\hat{D}^{\prime}+i D^{\prime}, \\
\overline{\mathbb{D}} \equiv \overline{\mathbb{D}}_{+}+\overline{\mathbb{D}}_{-}=\hat{D}-i D, & \overline{\mathbb{D}}^{\prime} \equiv \overline{\mathbb{D}}_{+}-\overline{\mathbb{D}}_{-}=\hat{D}^{\prime}-i D^{\prime} . \tag{A.10}
\end{array}
$$

They satisfy,

$$
\begin{align*}
\{\mathbb{D}, \overline{\mathbb{D}}\} & =\left\{\mathbb{D}^{\prime},, \overline{\mathbb{D}}^{\prime}\right\}=-2 i \partial_{\tau}, \\
\left\{\mathbb{D}, \overline{\mathbb{D}}^{\prime}\right\} & =\left\{\mathbb{D}^{\prime}, \overline{\mathbb{D}}\right\}=-2 i \partial_{\sigma} . \tag{A.11}
\end{align*}
$$

The integration measure we use when boundaries are present is defined by,

$$
\begin{equation*}
\int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime} \equiv \int d^{2} \sigma D \hat{D} D^{\prime} \hat{D}^{\prime} \tag{A.12}
\end{equation*}
$$

and on the boundary we take,

$$
\begin{equation*}
\int d \tau d^{2} \theta \equiv \int d \tau D \hat{D} . \tag{A.13}
\end{equation*}
$$

When integrating by parts one finds that the following relations are most useful,

$$
\begin{align*}
& \int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime} \mathbb{D}_{ \pm}=\mp \int d \tau d^{2} \theta \mathbb{D}_{ \pm}=-\frac{1}{2} \int d \tau d^{2} \theta \mathbb{D}^{\prime} \\
& \int d^{2} \sigma d^{2} \theta d^{2} \theta^{\prime} \overline{\mathbb{D}}_{ \pm}= \pm \int d \tau d^{2} \theta \overline{\mathbb{D}}_{ \pm}=+\frac{1}{2} \int d \tau d^{2} \theta \overline{\mathbb{D}}^{\prime} \tag{A.14}
\end{align*}
$$

## B $\quad N=1$ non-linear $\sigma$-models

While a comprehensive review of the $N=1$ non-linear $\sigma$-model in the presence of boundaries can be found in [22], we summarize here - in order to be self contained - its most relevant properties.

In the absence of boundaries a non-linear $\sigma$-model (with $N \leq(1,1)$ ) on some $d$ dimensional target manifold $\mathcal{M}$ is characterized by a metric $g_{a b}(X)$ and a closed 3 -form $H_{a b c}(X)$ where $X^{a}$ are local coordinates on $\mathcal{M}$ and $a, b, c, \ldots \in\{1, \cdots, d\}$, we also use a locally defined 2-form potential $b_{a b}(X)=-b_{b a}(X)$ for the torsion: $H_{a b c}=-(3 / 2) \partial_{[a} b_{b c}$. We introduce a boundary at $\sigma=0(\sigma \geq 0)$ and $\theta^{+}=\theta^{-}$which breaks the invariance under translations in both the $\sigma$ and the $\theta^{\prime} \equiv \theta^{+}-\theta^{-}$direction thus reducing the $N=(1,1)$ supersymmetry to an $N=1$ supersymmetry. The action,

$$
\begin{equation*}
\mathcal{S}=-4 \int d^{2} \sigma d \theta D^{\prime}\left(D_{+} X^{a} D_{-} X^{b}\left(g_{a b}+b_{a b}\right)\right)+2 i \int d \tau d \theta A_{a}(X) D X^{a}, \tag{B.1}
\end{equation*}
$$

is manifestly invariant under the $N=1$ supersymmetry and differs from the usual action in the absence of boundary terms by a total derivative term [20,21]. We can drop the boundary term provided we replace $b$ in the bulk term by $\mathcal{F}$,

$$
\begin{equation*}
b_{a b} \rightarrow \mathcal{F}_{a b}=b_{a b}+F_{a b}, \tag{B.2}
\end{equation*}
$$

with,

$$
\begin{equation*}
F_{a b}=\partial_{a} A_{b}-\partial_{b} A_{a} . \tag{B.3}
\end{equation*}
$$

Dimensionally, one could as well add a non-standard boundary term to the action,

$$
\begin{equation*}
\mathcal{S}_{\hat{b}}=2 i \int d \tau d \theta \hat{A}_{a}(X) D^{\prime} X^{a} \tag{B.4}
\end{equation*}
$$

A priori such a term is problematic, however through appropriate Neumann boundary conditions it can be reduced to the standard boundary term. This is precisely the situation we encounter when dealing with twisted chiral and semi-chiral superfields.

Varying the action eq. (B.1) yields a boundary term,

$$
\begin{equation*}
\left.\delta \mathcal{S}\right|_{\text {boundary }}=-2 i \int d \tau d \theta \delta X^{a}\left(g_{a b} D^{\prime} X^{b}-\mathcal{F}_{a b} D X^{b}\right) \tag{B.5}
\end{equation*}
$$

which will only vanish upon imposing suitable boundary conditions. In order to do so we start by imposing a set of Dirichlet boundary conditions,

$$
\begin{equation*}
Y^{\hat{A}}(X)=0, \quad \hat{A} \in\{1, \cdots, d-p\} . \tag{B.6}
\end{equation*}
$$

We denote the remainder of the coordinates - the world volume coordinates of the brane - by,

$$
\begin{equation*}
\sigma^{A}(X), \quad A \in\{1, \cdots, p\} . \tag{B.7}
\end{equation*}
$$

In order to make the boundary term in the variation vanish, we need to impose in addition to the Dirichlet boundary conditions eq. (B.6), $p$ Neumann boundary conditions,

$$
\begin{equation*}
\frac{\partial X^{c}}{\partial \sigma^{A}} g_{c b} D^{\prime} X^{b}=\frac{\partial X^{c}}{\partial \sigma^{A}} \mathcal{F}_{c d} \frac{\partial X^{d}}{\partial \sigma^{B}} D \sigma^{B} \tag{B.8}
\end{equation*}
$$

We end up with a $\mathrm{D} p$-brane whose position is determined by eq. (B.6), with a possibly non-trivial $\mathrm{U}(1)$ bundle with field strength $\mathcal{F}$ on it.

## C Some geometry

## C. 1 Generalized complex geometry

In this section, we review some aspects of generalized complex geometry (GCG) that are useful for understanding some discussions in the main text, section 3.4 in particular. For a much more detailed discussion, see [29].

To get started, let us recall some better known structures. An almost complex structure on a manifold $\mathcal{M}$ is a linear map $J: T \rightarrow T$ (where $T$ is the tangent bundle of $\mathcal{M}$ ), ${ }^{14}$ which satisfies $J^{2}=-1$. For our purposes this should be contrasted with the notion of a presymplectic structure on $\mathcal{M}$, which is simply a non-degenerate two-form $\Omega$ on $\mathcal{M}$. More abstractly, this means that a pre-symplectic structure is an isomorphism $\Omega: T \rightarrow T^{*}$ (where $T^{*}$ is the dual of $T$, the cotangent bundle of $\mathcal{M}$ ), satisfying $\Omega^{*}=-\Omega$.

Both notions can be naturally combined once we look at structures on the direct sum $T \oplus T^{*}$, leading to the notion of a generalized complex structure (GCS). As usual, it is useful to have a bilinear form at one's disposal. The natural symmetric pairing on $T \oplus T^{*}$ is given by,

$$
\begin{equation*}
\langle X+\xi, Y+\eta\rangle=\frac{1}{2}(\eta(X)+\xi(Y)), \quad X+\xi, Y+\eta \in T \oplus T^{*} . \tag{C.1}
\end{equation*}
$$

Using this bilinear form, an almost GCS is a linear map $\mathcal{J}: T \oplus T^{*} \rightarrow T \oplus T^{*}$, satisfying $\mathcal{J}^{2}=-1$, which preserves the natural pairing, $\langle\mathcal{J} W, \mathcal{J} Z\rangle=\langle W, Z\rangle$ for all $W, Z \in T \oplus T^{*}$. Using the defining relation for the dual map $\langle W, \mathcal{J} Z\rangle=\langle\mathcal{J} * W, Z\rangle$, the latter condition is nothing but $\mathcal{J}^{*}=-\mathcal{J}$.

The next step is to introduce an appropriate notion of integrability. To this end one defines the Courant bracket,

$$
\begin{equation*}
[X+\xi, Y+\eta]=[X, Y]+\mathcal{L}_{X} \eta-\mathcal{L}_{Y} \xi-\frac{1}{2} d(\eta(X)-\xi(Y)) . \tag{C.2}
\end{equation*}
$$

Here the first term is the usual Lie bracket on $T$ and $\mathcal{L}_{X}$ is the Lie derivative corresponding to $X$. This clearly reduces to the Lie bracket when projecting to $T$. One of the main useful properties of the Courant bracket is its covariance with respect to b-transforms. A btransform is a symmetry of the natural pairing eq. (C.1),

$$
e^{b}\binom{X}{\xi} \equiv\left(\begin{array}{ll}
1 & 0  \tag{C.3}\\
b & 1
\end{array}\right)\binom{X}{\xi}=\binom{X}{\xi+\iota_{X} b},
$$

[^13]where $b$ is a locally defined two-form and $\iota_{X} b$ is the inner product, $\iota_{X} b(Y)=b(X, Y)$ for all vector fields $Y$. It is then not hard to show that,
\[

$$
\begin{equation*}
\left[e^{b}(W), e^{b}(Z)\right]=e^{b}[W, Z], \quad \text { if } d b=0 \tag{C.4}
\end{equation*}
$$

\]

Analogously to the case of an almost complex structure, given an almost GCS $\mathcal{J}$ we can consider its $+i$-eigenbundle $L$, namely $\mathcal{J} W=+i W$, for all $W \in L$. A GCS is then an almost GCS for which its $+i$-eigenbundle $L$ is involutive with respect to the Courant bracket. Symbolically we will write this as $[L, L] \subset L$. In this case we say that the almost GCS is integrable. Note that eq. (C.4) implies that if $\mathcal{J}$ is integrable with $+i$-eigenbundle $L$, then $e^{b} \mathcal{J} e^{-b}$ is integrable with $+i$-eigenbundle $e^{b} L$ as long as $d b=0$.

In the presence of a non-zero three-form $H$ one can twist the Courant bracket by $H$,

$$
\begin{equation*}
[X+\xi, Y+\eta]_{H}=[X+\xi, Y+\eta]+\iota_{X} \iota_{Y} H, \tag{C.5}
\end{equation*}
$$

where $\iota_{X} \iota_{Y} H(Z)=H(Y, X, Z)$. With this definition, eq. (C.4) becomes,

$$
\begin{equation*}
\left[e^{b}(W), e^{b}(Z)\right]_{H}=e^{b}[W, Z]_{H-d b} . \tag{C.6}
\end{equation*}
$$

This shows that this is still only a symmetry of the twisted bracket if $d b=0$. On the other hand it shows that performing a b-transform with $d b \neq 0$ changes the twisting. An almost GCS which is integrable with respect to an $H$-twisted Courant bracket will be called an $H$-twisted GCS. If $L \subset T \oplus T^{*}$ is involutive with respect to $[,]_{H}$ then $e^{b} L$ is involutive with respect to $[,]_{H+d b}$. In other words, if $\mathcal{J}$ is $H$-twisted, then $e^{b} \mathcal{J} e^{-b}$ is $(H+d b)$-twisted.

A pair $\left(\mathcal{J}_{1}, \mathcal{J}_{2}\right)$ of commuting GCSs, such that $\mathcal{G}=-\mathcal{J}_{1} \mathcal{J}_{2}$ defines a positive definite metric on $T \oplus T^{*}$, is called a generalized Kähler structure (GKS). When both $\mathcal{J}_{1}$ and $\mathcal{J}_{2}$ are $H$-twisted, the resulting GKS is also called $H$-twisted. As was shown in [29], a twisted GKS is equivalent to a bihermitian structure. Given the bihermitian data ( $g, H, J_{+}, J_{-}$), the corresponding $H$-twisted GKS $\left(\mathcal{J}_{+}, \mathcal{J}_{-}\right)$is, up to a b-transform,

$$
\mathcal{J}_{ \pm}=\frac{1}{2}\left(\begin{array}{cc}
J_{+} \pm J_{-} & \omega_{+}^{-1} \mp \omega_{-}^{-1}  \tag{C.7}\\
-\left(\omega_{+} \mp \omega_{-}\right) & -\left(J_{+}^{t} \pm J_{-}^{t}\right)
\end{array}\right),
$$

where $\omega_{ \pm}=-g J_{ \pm}$are two-forms, ${ }^{15}$ because $g$ is hermitian with respect to both $J_{ \pm}$.

## C.1.1 Example: Kähler structure

As an illustration of the definition of a GKS and in preparation of the discussion in the next section, let us look at the simplest example of a GKS - a Kähler structure. A Kähler structure $(g, J, \Omega)$ is a Riemannian metric $g$, a complex structure $J$ and a symplectic structure $\Omega$ (i.e. a pre-symplectic structure satisfying $d \Omega=0$ ), with the compatibility condition $\Omega=-g J$. This last condition is usually phrased as $g$ being hermitian with

[^14]respect to $J$. Now, a complex structure $J$ and a symplectic structure $\Omega$ correspond to the GCSs $\mathcal{J}_{J}$ and $\mathcal{J}_{\Omega}$, respectively, where
\[

\mathcal{J}_{J}=\left($$
\begin{array}{cc}
J & 0  \tag{C.8}\\
0 & -J^{t}
\end{array}
$$\right), \quad \mathcal{J}_{\Omega}=\left($$
\begin{array}{cc}
0 & \Omega^{-1} \\
-\Omega & 0
\end{array}
$$\right) .
\]

Courant integrability of $\mathcal{J}_{J}$ is equivalent with the integrability of the complex structure $J$, while Courant integrability of $\mathcal{J}_{\Omega}$ can be written as $d \Omega=0$, indeed the integrability condition required for a symplectic structure. For a Kähler manifold - so given a Riemannian metric expressible as $g=\Omega J$ - it is easily seen that $\mathcal{J}_{J}$ and $\mathcal{J}_{\Omega}$ commute and their product leads to a positive metric on $T \oplus T^{*}$,

$$
\mathcal{G}=-\mathcal{J}_{J} \mathcal{J}_{\Omega}=-\mathcal{J}_{\Omega} \mathcal{J}_{J}=\left(\begin{array}{cc}
0 & g^{-1}  \tag{C.9}\\
g & 0
\end{array}\right) .
$$

In other words a Kähler manifold is an example of a generalized Kähler manifold. Note that taking $J_{+}=J_{-}=J$ in (C.7) results in the Kähler structure $\left(\mathcal{J}_{+}, \mathcal{J}_{-}\right)=\left(\mathcal{J}_{J}, \mathcal{J}_{\Omega}\right)$. In our conventions this corresponds to a local description entirely in terms of chiral fields. The mirror description in terms of only twisted chiral fields by sending $J_{-} \rightarrow-J_{-}$results in the Kähler structure $\left(\mathcal{J}_{+}, \mathcal{J}_{-}\right)=\left(\mathcal{J}_{\Omega}, \mathcal{J}_{J}\right)$ where indeed complex and symplectic structure data are interchanged. More generally, on defines mirror symmetry to act locally by interchanging $\mathcal{J}_{+}$and $\mathcal{J}_{-}$.

## C. 2 Generalized complex submanifolds

We now want to define the appropriate notion of generalized submanifold of a generalized complex manifold. Again a more in-depth discussion can be found in [29]. Consider a manifold $\mathcal{M}$ and a closed three-form $H$ living on it. With the application to D-branes in mind, one defines a generalized submanifold $(\mathcal{N}, \mathcal{F})$ of the manifold $(\mathcal{M}, H)$ as a submanifold $\mathcal{N}$ of $\mathcal{M}$ along with a two-form $\mathcal{F}$ living on $\mathcal{N}$ such that $d \mathcal{F}=\left.H\right|_{\mathcal{N}} \cdot{ }^{16}$ One then defines the generalized tangent bundle of $\mathcal{N}$ to be,

$$
\begin{equation*}
\tau_{\mathcal{N}}^{\mathcal{F}}=\left\{X+\left.\xi \in T_{\mathcal{N}} \oplus T_{\mathcal{M}}^{*}\right|_{\mathcal{N}}:\left.\xi\right|_{\mathcal{N}}=i_{X} \mathcal{F}\right\}, \tag{C.10}
\end{equation*}
$$

where from now on we denote the tangent bundle of a manifold $\mathcal{M}$ by $T_{\mathcal{M}}$ to avoid confusion between the tangent bundle of the total space and that of the submanifold. We use the notation $\left.T_{\mathcal{M}}^{*}\right|_{\mathcal{N}}$ to denote the restriction of the cotangent bundle of $\mathcal{M}$ to the submanifold $\mathcal{N}$, i.e of all vector fields tangent to $\mathcal{M}$, only those that "start at" a point in $\mathcal{N}$ are sections of this restricted bundle. Finally, a generalized complex submanifold of a generalized complex manifold $(\mathcal{M}, \mathcal{J}, H)$, where $\mathcal{J}$ is an $H$-twisted GCS, is a submanifold $(\mathcal{N}, \mathcal{F})$ of $(\mathcal{M}, H)$ which is stable under $\mathcal{J}$,

$$
\begin{equation*}
\mathcal{J}\left(\tau_{\mathcal{N}}^{\mathcal{N}}\right) \subset \tau_{\mathcal{N}}^{\mathcal{N}} \tag{C.11}
\end{equation*}
$$

[^15]This mimics (and generalizes) the definition of a holomorphic submanifold $\mathcal{N}$ of a complex manifold $\mathcal{M}$ with complex structure $J$, where $T_{\mathcal{N}}$ is required to be stable under $J$. Notice that this definition of a generalized submanifold and tangent bundle is consistent with changing of the twisting. Indeed, since $e^{b}(\mathcal{N}, \mathcal{F})=\left(\mathcal{M}, \mathcal{F}^{\prime}=\mathcal{F}+b\right)$, we find $d \mathcal{F}^{\prime}=H+d b$ on $\mathcal{N}$. On the other hand, $e^{b} \mathcal{J} e^{-b}$ is $(H+d b)$-twisted, so that it is indeed $H+d b$, and not just $H$, which enters the definition eq. (C.10) of the generalized tangent bundle.

Let us get a feeling for this definition and its usefulness by examining the two limiting cases. The more general case is developed to some extend in section 3.4.

## C.2.1 Example 1: complex manifolds

Consider a complex manifold $(\mathcal{M}, J)$. We can examine what it means for a submanifold to be a generalized complex submanifold with respect to $\mathcal{J}_{J}$. Eq. (C.11) implies

- $J\left(T_{\mathcal{N}}\right) \subset T_{\mathcal{N}}$, i.e. $\mathcal{N}$ is a complex submanifold of $\mathcal{M}$.
- $J^{t} \mathcal{F}+\mathcal{F} J=0$ on $\mathcal{N}$, i.e. $\mathcal{F}$ is of type $(1,1)$ on $\mathcal{N}$.

Note that this conclusion works for any complex manifold and arbitrary $H$. In the case of a Kähler manifold (which also implies that $H=0$ ), this however shows that a B brane $(\mathcal{N}, F)$ is a generalized complex submanifold with respect to $\mathcal{J}_{J}$ of the Kähler manifold $\mathcal{M}$.

## C.2.2 Example 2: symplectic manifolds

Since some aspects of symplectic geometry might be less familiar, we start by reviewing these briefly. As stated before, a symplectic form $\Omega$ is a closed, non-degenerate two-form. A manifold endowed with a symplectic form is called a symplectic manifold. A symplectic manifold $\mathcal{M}$ has several types of submanifolds. A submanifold $\mathcal{N}$ is called symplectic, isotropic, coisotropic or lagrangian resp. if its tangent space $T_{\mathcal{N}}$ is a symplectic, isotropic, coisotropic or lagrangian subspace resp. of the tangent space $T_{\mathcal{M}}$ of the manifold $\mathcal{M}$.

Given a symplectic vector space $M$, i.e. an even dimensional $(d=2 k, k \in \mathbb{N})$ vector space equipped with a non-degenerate, skew-symmetric, bilinear form $\Omega$. Consider a subspace $N$ of $M$ and define its symplectic complement $N^{\perp}$ by,

$$
\begin{equation*}
N^{\perp}=\{m \in M \mid \Omega(m, n)=0, \forall n \in N\} . \tag{C.12}
\end{equation*}
$$

We distinguish four cases:
Symplectic subspace: $N$ is a symplectic subspace of $M$ if $N^{\perp} \cap N=\emptyset$. Note that e.g. for a holomorphic submanifold $\mathcal{N}$ of a Kähler manifold $\mathcal{M}, T_{\mathcal{N}}$ is a symplectic subspace of $T_{\mathcal{M}}$.

Isotropic subspace: $N$ is an isotropic subspace of $M$ if $N \subseteq N^{\perp}$. This is true if and only if $\Omega$ restricts to zero on $N$ and we get $\operatorname{dim}(N) \leq k$. Every one-dimensional subspace is isotropic.

Coisotropic subspace: $N$ is a coisotropic subspace of $M$ if $N^{\perp} \subseteq N$. In other words, $N$ is coisotropic if and only if $N^{\perp}$ is isotropic. Equivalently, $N$ is coisotropic if and
only if $\Omega$ descends to a non-degenerate form on the quotient space $N / N^{\perp}$. We get $\operatorname{dim}(N) \geq k$ and any codimension one subspace is always coisotropic.

Lagrangian subspace: $N$ is a lagrangian subspace of $M$ if it is simultaneously isotropic and coisotropic, i.e. if $N^{\perp}=N$. This implies that, because of the non-degeneracy of $\Omega$, a lagrangian subspace is $k$-dimensional. Obviously $\Omega$ vanishes on a lagrangian subspace.

We are now ready to analyze the conditions for a generalized complex submanifold of a symplectic manifold $\mathcal{M}$. For this we consider the stability of the generalized tangent bundle under $\mathcal{J}_{\Omega}$, as in eq. (C.11). This results in the following conditions:

- $\Omega^{-1}\left(\operatorname{Ann} T_{\mathcal{N}}\right) \subset T_{\mathcal{N}}$, where

$$
\begin{equation*}
\operatorname{Ann} T_{\mathcal{N}}=\left\{\xi \in T_{\mathcal{M}}^{*} \mid \xi(X)=0, \forall X \in T_{\mathcal{N}}\right\} \tag{C.13}
\end{equation*}
$$

It is easily shown that $\Omega^{-1}\left(\operatorname{Ann} T_{\mathcal{N}}\right)=T_{\mathcal{N}}^{\perp}$, so that this is equivalent to $T_{\mathcal{N}}^{\perp} \subset T_{\mathcal{N}}$, i.e. $\mathcal{N}$ is a coisotropic submanifold of $\mathcal{M}$. In other words $\Omega$ is non-degenerate on $T_{\mathcal{N}} / T_{\mathcal{N}}^{\perp}$.

- $\Omega^{-1}\left(\iota_{X} \mathcal{F}\right)=X_{T} \in T_{\mathcal{N}}$ for all $X \in T_{\mathcal{N}}$. This implies that $\mathcal{F}(X, Y)=\Omega\left(X_{T}, Y\right)$, for all $X, Y \in T_{\mathcal{N}}$. This in turn implies that $\iota_{Y} \mathcal{F}=0$ for all $Y \in T_{\mathcal{N}}^{\perp}$. In other words, $\mathcal{F}$ descends to a form on $T_{\mathcal{N}} / T_{\mathcal{N}}^{\perp}$.
- $\left(\Omega+\mathcal{F} \Omega^{-1} \mathcal{F}\right)\left(T_{\mathcal{N}}\right) \subset \operatorname{Ann} T_{\mathcal{N}}$, or $\left(1+K^{2}\right)\left(T_{\mathcal{N}}\right) \subset T_{\mathcal{N}}^{\perp}$, where $K=\Omega^{-1} \mathcal{F}$, so that $K$ is a complex structure on $T_{\mathcal{N}} / T_{\mathcal{N}}^{\perp}$. This in turn implies that $\mathcal{F}$ is non-degenerate on $T_{\mathcal{N}} / T_{\mathcal{N}}^{\perp}$ and both $\Omega$ and $\mathcal{F}$ are (2,0)+(0,2) forms with respect to $K$.

When $T_{\mathcal{N}}^{\perp}=T_{\mathcal{N}}$, the submanifold is lagrangian and $\mathcal{F}=0$ on $\mathcal{N}$. These conditions are precisely those for a A branes on symplectic manifolds. In particular, they coincide with the conditions for coisotropic branes first proposed in [26]. The fact that coisotropic branes on symplectic manifolds are generalized complex submanifolds with respect to the symplectic structure was first established in [29].

Summarizing, a brane $(\mathcal{N}, \mathcal{F})$ is coisotropic if $\mathcal{N}$ is a coisotropic submanifold and $\mathcal{F}$ is zero on $T_{\mathcal{N}}^{\perp}$ but non-degenerate on $T_{\mathcal{N}} / T_{\mathcal{N}}^{\perp}$ so that $\Omega^{-1} \mathcal{F}$ is a complex structure on $T_{\mathcal{N}} / T_{\mathcal{N}}^{\perp}$.

## C. 3 Poisson structures

A Poisson manifold $(\mathcal{M}, \Pi)$ is a manifold $\mathcal{M}$ endowed with a Poisson structure $\Pi$. A Poisson structure is an antisymmetric bivector $\Pi$ such that the associated Poisson bracket

$$
\begin{equation*}
\{f, g\} \equiv \Pi(d f, d g)=\Pi^{a b} \partial_{a} f \partial_{b} g, \tag{C.14}
\end{equation*}
$$

for smooth functions $f$ and $g$ on $\mathcal{M}$ obeys the Poisson algebra, i.e. it is a Lie algebra that acts as a derivation on the algebra of smooth functions on $\mathcal{M}$,

$$
\begin{equation*}
\{f, g h\}=\{f, g\} h+g\{f, h\} . \tag{C.15}
\end{equation*}
$$

All required conditions follow automatically from the definition (C.14), except for the Jacobi identity. The latter is equivalent to the set of conditions,

$$
\begin{equation*}
\Pi^{d[a} \partial_{d} \Pi^{b c]}=0 \tag{C.16}
\end{equation*}
$$

on the antisymmetric bivector $\Pi$. So in short, a Poisson structure is an antisymmetric bivector which satisfies (C.16). See [48] for more details. When $\Pi$ is invertible, this condition translates to $d \Omega=0$, for $\Omega=\Pi^{-1}$. This implies that an invertible Poisson structure yields a symplectic structure.

An interesting property of Poisson manifolds is that they are foliated by symplectic leaves. The construction is very roughly as follows. A Hamiltonian vector field is a vector field $X_{f}$ associated with some function $f$ for which

$$
\begin{equation*}
X_{f}(g)=\{f, g\}, \quad \text { for any function } g . \tag{C.17}
\end{equation*}
$$

In components, this implies

$$
\begin{equation*}
X_{f}^{a}=\Pi^{b a} \partial_{b} f \tag{C.18}
\end{equation*}
$$

We call $S_{x}$ the subspace of $T_{\mathcal{M}}$ spanned by these Hamiltonian vector fields at a point $x$ of $\mathcal{M}$. If we regard $\Pi$ as a map from $T_{\mathcal{M}}^{*}$ to $T_{\mathcal{M}}$, i.e. $\Pi(d f)=X_{f}$, we see that the dimension of $S_{x}$ is the rank of the map $\Pi$. A point $x$ is called regular when the rank of $\Pi$ is constant in a neighborhood of $x$. We implicitly only consider regular points in this text. Now, one can show [48] that the subspaces $S_{x}$ define a (generalized) integrable distribution, and the Poisson structure induces a symplectic structure on the leaves $S$. This symplectic structure is essentially the inverse of the restriction of $\Pi$ to $S$.

The notion of a coisotropic submanifold carries over to Poisson manifolds in the following way. A submanifold $\mathcal{N}$ of a Poisson manifold $(\mathcal{M}, \Pi)$ is called coisotropic if

$$
\begin{equation*}
\Pi\left(\operatorname{Ann} T_{\mathcal{N}}\right) \subset T_{\mathcal{N}} \tag{C.19}
\end{equation*}
$$

where the annihilator $\operatorname{Ann} T_{\mathcal{N}}$ was defined in eq. (C.13). Equivalently, for any two functions $f$ and $g$ which vanish on a coisotropic submanifold $\mathcal{N}$, their Poisson bracket $\{f, g\}$ also vanishes on $\mathcal{N}$ [48]. It is clear from eq. (3.35) that all generalised complex submanifolds of generalized Kähler manifolds are coisotropic in this general sense.

If $\Pi$ is invertible eq. (C.19) reduces to the coisotropy condition on a symplectic manifold of the previous section since $\Omega^{-1}\left(\operatorname{Ann} T_{\mathcal{N}}\right)=T_{\mathcal{N}}^{\perp}$, where $T_{\mathcal{N}}^{\perp}$ denotes the symplectic complement with respect to $\Omega$ as before.

This characterization of a coisotropic submanifold by the symplectic complement of the tangent space has a natural generalization to the Poisson case [48]. Indeed, it is not hard to see that in general $\Pi\left(\operatorname{Ann} T_{\mathcal{N}}\right)$ for some submanifold $\mathcal{N}$ is the symplectic complement of $T_{\mathcal{N}} \cap S_{x}$ in $S_{x}$ with respect to the induced symplectic structure on $S$. Eq. (C.19) thus becomes

$$
\begin{equation*}
\left(T_{\mathcal{N}} \cap S_{x}\right)^{\perp} \subset T_{\mathcal{N}} \tag{C.20}
\end{equation*}
$$

This obviously reduces to the standard definition on symplectic manifolds, where the foliation comprises only one leaf, namely $S=\mathcal{M}$.

## D Auxiliary fields and boundary conditions

As noted in section 2.2 the fields $\mathbb{D}^{\prime} l^{\tilde{\alpha}}, \overline{\mathbb{D}^{\prime}} l^{\bar{\alpha}}, \mathbb{D}^{\prime} r^{\tilde{\mu}}$ and $\overline{\mathbb{D}}^{\prime} r^{\overline{\tilde{\mu}}}$ should be treated as auxiliary fields. In an $N=1$ superspace formulation these auxiliary fields are essential for the extended supersymmetry-algebra to close off-shell in the directions along which the two complex structures $J_{+}$and $J_{-}$do not commute. The expressions for the auxiliary fields in terms of the $N=2$ superfields can be found by working out the $\mathbb{D}^{\prime}$ and $\overline{\mathbb{D}}^{\prime}$ derivatives in the action eq. (2.49) and varying the resulting action with respect to $\mathbb{D}^{\prime} l^{\tilde{\alpha}}, \overline{\mathbb{D}^{\prime}} l^{\bar{\alpha}}, \mathbb{D}^{\prime} r^{\tilde{\mu}}$ and $\overline{\mathbb{D}}^{\prime} r^{\bar{\mu}}$. Performing this set of manipulations yields the following relations,

$$
\begin{align*}
& \mathcal{N} \overline{\mathbb{D}}^{\prime} \overline{\mathbb{X}}=-\mathcal{M}_{1} \overline{\mathbb{D} X}-\mathcal{M}_{2} \overline{\mathbb{D}} \overline{\mathbb{X}}-\mathcal{M}_{3} \overline{\mathbb{D}}^{\prime} \overline{\mathbb{Y}} \\
& -\mathcal{M}_{4} \overline{\mathbb{D}} \overline{\mathbb{Y}}-\mathcal{M}_{5} \overline{\bar{D}^{\prime} \mathbb{Y}}-\mathcal{M}_{6} \mathbb{D} \mathbb{Y}, \tag{D.1}
\end{align*}
$$

and,

$$
\begin{align*}
\mathbb{D}^{\prime} \mathbb{X}^{T} \mathcal{N}^{\dagger}= & -\mathbb{D} \overline{\mathbb{X}}^{T} \mathcal{M}_{1}^{\dagger}-\mathbb{D} \mathbb{X}^{T} \mathcal{M}_{2}^{\dagger}-\mathbb{D}^{\prime} \mathbb{Y}^{T} \mathcal{M}_{3}^{\dagger} \\
& -\mathbb{D} \mathbb{Y}^{T} \mathcal{M}_{4}^{\dagger}-\mathbb{D}^{\prime} \overline{\mathbb{Y}}^{T} \mathcal{M}_{5}^{\dagger}-\mathbb{D}^{T} \mathcal{Y}_{6}^{\dagger}, \tag{D.2}
\end{align*}
$$

where we introduced $\mathbb{X}^{T} \equiv\left(l^{\tilde{\beta}}, r^{\tilde{\nu}}\right)$ and $\mathbb{Y}^{T} \equiv\left(z^{\beta}, w^{\nu}\right)$ and

$$
\begin{align*}
& \mathcal{N} \equiv\binom{V_{\tilde{\alpha} \bar{\beta}} V_{\tilde{\alpha} \bar{\nu}}}{V_{\tilde{\mu} \overline{\tilde{\beta}}} V_{\tilde{\mu} \bar{\nu}}}, \quad \mathcal{M}_{1} \equiv\left(\begin{array}{cc}
0 & 2 V_{\tilde{\alpha} \tilde{\nu}} \\
-2 V_{\tilde{\mu} \tilde{\beta}} & 0
\end{array}\right), \quad \mathcal{M}_{2} \equiv\left(\begin{array}{cc}
V_{\tilde{\alpha} \tilde{\beta}} & V_{\tilde{\alpha} \tilde{\nu}} \\
-V_{\tilde{\mu} \tilde{\bar{\beta}}}-V_{\tilde{\mu} \tilde{\nu}}
\end{array}\right), \quad \mathcal{M}_{3} \equiv\left(\begin{array}{cc}
V_{\tilde{\alpha} \bar{\beta}} V_{\tilde{\alpha} \bar{\nu}} \\
V_{\tilde{\mu} \bar{\beta}} & 0
\end{array}\right), \\
& \mathcal{M}_{4} \equiv\left(\begin{array}{cc}
V_{\tilde{\alpha} \bar{\beta}} & V_{\tilde{\alpha} \bar{\nu}} \\
-V_{\tilde{\mu} \bar{\beta}} & 0
\end{array}\right), \quad \mathcal{M}_{5} \equiv\left(\begin{array}{cc}
V_{\tilde{\alpha} \beta} & 0 \\
V_{\tilde{\mu} \beta} & V_{\tilde{\mu} \nu}
\end{array}\right), \quad \mathcal{M}_{6} \equiv\left(\begin{array}{cc}
V_{\tilde{\alpha} \beta} & 0 \\
-V_{\tilde{\mu} \beta} & -V_{\tilde{\mu} \nu}
\end{array}\right) . \tag{D.3}
\end{align*}
$$

Using the $N=2$ superfield constraints eqs. (2.45), (2.46) and (2.47) these relations can be written more elegantly as,

$$
\begin{align*}
& \overline{\mathbb{D}}^{\prime} V_{\tilde{\alpha}}=-\overline{\mathbb{D}} V_{\tilde{\alpha}}, \\
& \overline{\mathbb{D}}^{\prime} V_{\tilde{\mu}}=+\overline{\mathbb{D}} V_{\tilde{\mu}}, \tag{D.4}
\end{align*}
$$

and,

$$
\begin{align*}
& \mathbb{D}^{\prime} V_{\overline{\tilde{\alpha}}}=-\mathbb{D} V_{\overline{\tilde{\alpha}}} \\
& \mathbb{D}^{\prime} V_{\tilde{\tilde{\mu}}}=+\mathbb{D} V_{\overline{\tilde{\mu}}} \tag{D.5}
\end{align*}
$$

In the second part of this section we will discuss how the relations for the auxiliary fields eqs. (D.4) and (D.5) arise, when a chiral/twisted chiral pair is dualized to a semi-chiral multiplet. While the Dirichlet boundary conditions in the original model are dualized to the Dirichlet or/and Neumann boundary conditions in the dual model, the Neumann boundary conditions from the original model result in the expressions for the auxiliary fields after dualization. This connection between the original Neumann boundary conditions and the expressions for the auxiliary fields in the dual model thus forms an additional consistency check for the dualization. Let us clarify these statements with the examples constructed in section 5 .

Starting with the Dirichlet boundary conditions eq. (5.15) for the D1-brane, we can deduce from the associated Neumann boundary condition for the twisted chiral superfield that the gauge field $\tilde{Y}$ should satisfy the relations,

$$
\begin{equation*}
\mathbb{D}^{\prime} \tilde{Y}=i \frac{m}{n} \mathbb{D} \tilde{Y}, \quad \overline{\mathbb{D}}^{\prime} \tilde{Y}=-i \frac{m}{n} \overline{\mathbb{D}} \tilde{Y} . \tag{D.6}
\end{equation*}
$$

Using the equations of motion,

$$
\begin{align*}
\hat{Y} & =-\frac{i}{2}(l-\bar{l}-r+\bar{r}), \\
\tilde{Y} & =Y-\frac{1}{2}(l+\bar{l}+r+\bar{r}), \\
Y & =-\frac{1}{2} \ln \left(e^{-(r+\bar{r})}+1\right), \tag{D.7}
\end{align*}
$$

and imposing the Dirichlet boundary conditions of the dual D2-brane eqs. (5.21) enables us to write eqs. (D.6) as,

$$
\begin{align*}
\mathbb{D}^{\prime}\left(l+\bar{l}+r+\bar{r}+\ln \left(1+e^{-r-\bar{r}}\right)\right) & =-\mathbb{D}(l-\bar{l}-r-\bar{r}), \\
\overline{\mathbb{D}}^{\prime}\left(l+\bar{l}+r+\bar{r}+\ln \left(1+e^{-r-\bar{r}}\right)\right) & =+\overline{\mathbb{D}}(l-\bar{l}-r-\bar{r}) . \tag{D.8}
\end{align*}
$$

These relations can also be obtained from eqs. (D.5) and (D.4) respectively, after taking a linear combination and imposing the dual Dirichlet boundary conditions.

When dualizing the D 3 -brane given in eq. (5.17) we need to distinguish between two different cases: $\alpha=a-i$ and $\alpha \neq a-i$. In the first case the D 3 -brane is dualized to a D2-brane, in the latter case to a D4-brane. Focusing first on the lagrangian D2-brane, we can deduce from the associated Neumann boundary condition for eq. (5.17) that the gauge fields $\tilde{Y}$ and $Y$ should satisfy the following expressions at the boundary,

$$
\begin{align*}
& \mathbb{D}^{\prime} \tilde{Y}=+i \frac{m}{n} \mathbb{D} \tilde{Y}+i a \mathbb{D} Y+\mathbb{D} Y, \\
& \overline{\mathbb{D}}^{\prime} \tilde{Y}=-i \frac{m}{n} \overline{\mathbb{D}} \tilde{Y}-i a \overline{\mathbb{D}} Y+\overline{\mathbb{D}} Y . \tag{D.9}
\end{align*}
$$

Imposing the Dirichlet boundary condition eq. (5.24) and implementing the equations of motion eq. (D.7), we find the following relations,

$$
\begin{align*}
& \mathbb{D}^{\prime}\left(l+\bar{l}+r+\bar{r}+\ln \left(1+e^{-r-\bar{r}}\right)\right)=-\mathbb{D}\left(l-\bar{l}-r+\bar{r}-\ln \left(1+e^{-r-\bar{r}}\right)\right), \\
& \overline{\mathbb{D}}^{\prime}\left(l+\bar{l}+r+\bar{r}+\ln \left(1+e^{-r-\bar{r}}\right)\right)=+\overline{\mathbb{D}}\left(l-\bar{l}-r+\bar{r}-\ln \left(1+e^{-r-\bar{r}}\right)\right), \tag{D.10}
\end{align*}
$$

which are just linear combinations of the expressions in eqs. (D.5) and (D.4) respectively. The Neumann boundary conditions for the chiral superfield on the other hand can be properly dualized to the first expression in eqs. (D.4) and (D.5).

If we choose $\alpha=0$, the D 3 -brane is dualized to a coisotropic D 4 -brane, and the associated Neumann boundary condition for eq. (5.17) then yields the same relations for $\tilde{Y}$ as in eq. (D.6). However, we need to impose the relations in eq. (5.29) for this situation, after which we implement the equations of motion eq. (D.7). These manipulations lead to the same expressions as in eq. (D.10), and thus reproduce the expressions for the auxiliary fields. One can also properly dualize the Neumann boundary conditions for the chiral superfield to the first expression given in eqs. (D.4) and (D.5) respectively.

## References

[1] S. Kachru, R. Kallosh, A. Linde and S.P. Trivedi, de Sitter vacua in string theory, Phys. Rev. D 68 (2003) 046005 [hep-th/0301240] [SPIRES].
[2] N. Berkovits, Super-Poincaré covariant quantization of the superstring, JHEP 04 (2000) 018 [hep-th/0001035] [SPIRES].
[3] L. Álvarez-Gaumé and D.Z. Freedman, Geometrical Structure and Ultraviolet Finiteness in the Supersymmetric $\sigma$-model, Commun. Math. Phys. 80 (1981) 443 [SPIRES].
[4] J. Gates, S. J., C.M. Hull and M. Roček, Twisted Multiplets and New Supersymmetric Nonlinear $\sigma$-models, Nucl. Phys. B 248 (1984) 157 [SPIRES].
[5] T.L. Curtright and C.K. Zachos, Geometry, Topology and Supersymmetry in Nonlinear Models, Phys. Rev. Lett. 53 (1984) 1799 [SPIRES].
[6] P.S. Howe and G. Sierra, Two-dimensional supersymmetric nonlinear $\sigma$-models with torsion, Phys. Lett. B 148 (1984) 451 [SPIRES].
[7] U. Lindström, M. Roček, R. von Unge and M. Zabzine, Generalized Kähler manifolds and off-shell supersymmetry, Commun. Math. Phys. 269 (2007) 833 [hep-th/0512164] [SPIRES].
[8] T. Buscher, U. Lindström and M. Roček, New supersymmetric $\sigma$-models with Wess-Zumino terms, Phys. Lett. B 202 (1988) 94 [SPIRES].
[9] I.T. Ivanov, B.-b. Kim and M. Roček, Complex structures, duality and WZW models in extended superspace, Phys. Lett. B 343 (1995) 133 [hep-th/9406063] [SPIRES].
[10] A. Sevrin and J. Troost, Off-shell formulation of $N=2$ non-linear $\sigma$-models, Nucl. Phys. B 492 (1997) 623 [hep-th/9610102] [SPIRES].
[11] J. Bogaerts, A. Sevrin, S. van der Loo and S. Van Gils, Properties of semi-chiral superfields, Nucl. Phys. B 562 (1999) 277 [hep-th/9905141] [SPIRES].
[12] J. Maes and A. Sevrin, A note on $N=(2,2)$ superfields in two dimensions, Phys. Lett. B 642 (2006) 535 [hep-th/0607119] [SPIRES].
[13] H. Ooguri, Y. Oz and Z. Yin, D-branes on Calabi-Yau spaces and their mirrors, Nucl. Phys. B 477 (1996) 407 [hep-th/9606112] [SPIRES].
[14] A. Hanany and K. Hori, Branes and $N=2$ theories in two dimensions, Nucl. Phys. B 513 (1998) 119 [hep-th/9707192] [SPIRES].
[15] K. Hori, A. Iqbal and C. Vafa, D-branes and mirror symmetry, hep-th/0005247 [SPIRES].
[16] K. Hori, Linear models of supersymmetric D-branes, hep-th/0012179 [SPIRES].
[17] C. Albertsson, U. Lindström and M. Zabzine, $N=1$ supersymmetric $\sigma$-model with boundaries. I, Commun. Math. Phys. 233 (2003) 403 [hep-th/0111161] [SPIRES].
[18] C. Albertsson, U. Lindström and M. Zabzine, $N=1$ supersymmetric $\sigma$-model with boundaries. II, Nucl. Phys. B 678 (2004) 295 [hep-th/0202069] [SPIRES].
[19] U. Lindström and M. Zabzine, $N=2$ boundary conditions for non-linear $\sigma$-models and Landau-Ginzburg models, JHEP 02 (2003) 006 [hep-th/0209098] [SPIRES].
[20] U. Lindström, M. Roček and P. van Nieuwenhuizen, Consistent boundary conditions for open strings, Nucl. Phys. B 662 (2003) 147 [hep-th/0211266] [SPIRES].
[21] P. Koerber, S. Nevens and A. Sevrin, Supersymmetric non-linear $\sigma$-models with boundaries revisited, JHEP 11 (2003) 066 [hep-th/0309229] [SPIRES].
[22] A. Sevrin, W. Staessens and A. Wijns, The world-sheet description of $A$ and $B$ branes revisited, JHEP 11 (2007) 061 [arXiv:0709.3733] [SPIRES].
[23] A. Sevrin, W. Staessens and A. Wijns, An $N=2$ worldsheet approach to D-branes in bihermitian geometries: I. Chiral and twisted chiral fields, JHEP 10 (2008) 108 [arXiv:0809.3659] [SPIRES].
[24] A. Sevrin, W. Staessens and A. Wijns, $N=2$ world-sheet approach to D-branes on generalized Kähler geometries: I. General formalism, Fortsch. Phys. 57 (2009) 684 [arXiv:0810.5355] [SPIRES].
[25] C.M. Hull, U. Lindström, M. Roček, R. von Unge and M. Zabzine, Generalized Kähler geometry and gerbes, arXiv:0811.3615 [SPIRES].
[26] A. Kapustin and D. Orlov, Remarks on A-branes, mirror symmetry and the Fukaya category, J. Geom. Phys. 48 (2003) 84 [hep-th/0109098] [SPIRES].
[27] S. Nevens, A. Sevrin, W. Troost and A. Wijns, Derivative corrections to the Born-Infeld action through $\beta$-function calculations in $N=2$ boundary superspace, JHEP 08 (2006) 086 [hep-th/0606255] [SPIRES].
[28] N. Hitchin, Generalized Calabi-Yau manifolds, Quart. J. Math. Oxford Ser. 54 (2003) 281 [math/0209099].
[29] M. Gualtieri, Generalized complex geometry, Ph.D Thesis, Oxford University (2003) [math/0401221]; Generalized complex geometry, math/0703298.
[30] M. Zabzine, Geometry of $D$-branes for general $N=(2,2) \sigma$-models, Lett. Math. Phys. 70 (2004) 211 [hep-th/0405240] [SPIRES].
[31] S. Lyakhovich and M. Zabzine, Poisson geometry of $\sigma$-models with extended supersymmetry, Phys. Lett. B 548 (2002) 243 [hep-th/0210043] [SPIRES].
[32] M. Gualtieri, Branes on Poisson varieties, arXiv:0710.2719.
[33] A. Kapustin, A-branes and noncommutative geometry, hep-th/0502212 [SPIRES].
[34] M.T. Grisaru, M. Massar, A. Sevrin and J. Troost, Some aspects of $N=(2,2), D=2$ supersymmetry, Fortsch. Phys. 47 (1999) 301 [hep-th/9801080] [SPIRES].
[35] J. Gates, S. J., M.T. Grisaru and M.E. Wehlau, A Study of General 2D, N = 2 Matter Coupled to Supergravity in Superspace, Nucl. Phys. B 460 (1996) 579 [hep-th/9509021] [SPIRES].
[36] S.J. Gates Jr. and W. Siegel, Variant superfield representations, Nucl. Phys. B 187 (1981) 389 [SPIRES].
[37] B.B. Deo and S.J. Gates, Comments on nonminimal $N=1$ scalar multiplets, Nucl. Phys. B 254 (1985) 187 [SPIRES].
[38] U. Lindström, M. Roček, I. Ryb, R. von Unge and M. Zabzine, New $N=(2,2)$ vector multiplets, JHEP 08 (2007) 008 [arXiv:0705.3201] [SPIRES].
[39] S.J. Gates Jr. and W. Merrell, $D=2 N=(2,2)$ Semi Chiral Vector Multiplet, JHEP 10 (2007) 035 [arXiv:0705.3207] [SPIRES].
[40] U. Lindström, M. Roček, I. Ryb, R. von Unge and M. Zabzine, T-duality and Generalized Kähler Geometry, JHEP 02 (2008) 056 [arXiv:0707.1696] [SPIRES].
[41] W. Merrell and D. Vaman, T-duality, quotients and generalized Kähler geometry, Phys. Lett. B 665 (2008) 401 [arXiv:0707.1697] [SPIRES].
[42] P. Spindel, A. Sevrin, W. Troost and A. Van Proeyen, Extended Supersymmetric $\sigma$-models on Group Manifolds. 1. The Complex Structures, Nucl. Phys. B 308 (1988) 662 [SPIRES].
[43] M. Roček, K. Schoutens and A. Sevrin, Off-shell WZW models in extended superspace, Phys. Lett. B 265 (1991) 303 [SPIRES];
M. Roček, C.H. Ahn, K. Schoutens and A. Sevrin, Superspace WZW models and black holes, hep-th/9110035 [SPIRES].
[44] A. Font, L.E. Ibáñez and F. Marchesano, Coisotropic D8-branes and model-building, JHEP 09 (2006) 080 [hep-th/0607219] [SPIRES].
[45] M.T. Grisaru, M. Massar, A. Sevrin and J. Troost, The quantum geometry of $N=(2,2)$ non-linear $\sigma$-models, Phys. Lett. B 412 (1997) 53 [hep-th/9706218] [SPIRES].
[46] N. Halmagyi and A. Tomasiello, Generalized Kähler Potentials from Supergravity, Commun. Math. Phys. 291 (2009) 1 [arXiv:0708.1032] [SPIRES].
[47] A. Kapustin and Y. Li, Stability conditions for topological D-branes: A worldsheet approach, hep-th/0311101 [SPIRES].
[48] I. Vaisman, Lectures on the Geometry of Poisson Manifolds, Birkhäuser Verlag, Basel (1994).
[49] B. Craps, O. Evnin and S. Nakamura, Local recoil of extended solitons: A string theory example, JHEP 01 (2007) 050 [hep-th/0608123] [SPIRES].
[50] I. Brunner, M.R. Gaberdiel, S. Hohenegger and C.A. Keller, Obstructions and lines of marginal stability from the world-sheet, arXiv:0902.3177 [SPIRES].


[^0]:    ${ }^{1}$ Aspirant FWO.

[^1]:    ${ }^{1}$ Out of two $(1,1)$ tensors $R^{a}{ }_{b}$ and $S^{a}{ }_{b}$, one constructs a $(1,2)$ tensor $\mathcal{N}[R, S]^{a}{ }_{b c}$, the Nijenhuis tensor, as $\mathcal{N}[R, S]^{a}{ }_{b c}=R^{a}{ }_{d} S^{d}{ }_{[b, c]}+R^{d}{ }_{[b} S^{a}{ }_{c], d}+R \leftrightarrow S$. In the present context, the integrability of $J_{+}$and $J_{-}$is equivalent to $\mathcal{N}\left[J_{+}, J_{+}\right]=\mathcal{N}\left[J_{-}, J_{-}\right]=0$.

[^2]:    ${ }^{2}$ We refer to the appendix for our conventions. We make a distinction between letters from the beginning $(\alpha, \beta, \gamma, \ldots)$ and letters from the middle of the Greek alphabet $(\mu, \nu, \rho, \ldots)$

[^3]:    ${ }^{3}$ This is a so called B-type boundary. Alternatively we could have introduced an A-type boundary defined by $\sigma=0, \theta^{\prime} \equiv\left(\theta^{+}-\theta^{-}\right) / 2=0$ and $\hat{\theta}^{\prime} \equiv\left(\hat{\theta}^{+}+\hat{\theta}^{-}\right) / 2=0$. Throughout this paper we will always use B-type boundary conditions as switching to A-type boundary conditions amounts to performing the local version of the mirror transform as defined in eq. (2.19) [22].

[^4]:    ${ }^{4}$ When no semi-chiral fields are present, this reduces to coisotropic A-branes on Kähler manifolds whose existence was discovered in [26].

[^5]:    ${ }^{5}$ Superconformal invariance at the quantum level does give additional conditions, see e.g. [27].

[^6]:    ${ }^{6}$ Here we mean minimal in the non-chiral directions. Any number of chiral fields can be chosen to obey Neumann boundary conditions without affecting the minimality we refer to here.

[^7]:    ${ }^{7}$ In this section, it is more appropriate to use a slightly more abstract notation, as is explained in footnote 15 of appendix C.
    ${ }^{8}$ To be precise, the objects in this equation should be pulled back in the proper way to the world-volume, as will be discussed below.

[^8]:    ${ }^{9}$ As far as the authors are aware, the most general analysis has so far not appeared in the literature in the amount of detail required for comparison with $\sigma$-model results. An equation similar and related to eq. (3.38) has been studied in $[32,33]$ for slightly different, but ultimately related reasons.

[^9]:    ${ }^{10}$ While this duality transformation was already found in [34], the elucidation of the underlying gauge structure is rather recent [38]-[41].

[^10]:    ${ }^{11}$ In fact it was also shown that this is the only WZW-model which can be described without the use of semi-chiral superfields.

[^11]:    ${ }^{12}$ In [43] the $S^{3} \times S^{1}$ model in terms of a chiral and twisted chiral field was shown to be dual to the model on $D \times T^{2}$ in terms of chiral fields with the same singular metric on $D$ as here. Note that superconformal invariance at the quantum level requires a non-trivial dilaton as well [43].

[^12]:    ${ }^{13}$ Note however that the present analysis holds only for models with a constant dilaton and no RR-fluxes.

[^13]:    ${ }^{14}$ In order to be correct, we should be speaking of smooth sections $\mathcal{C}^{\infty}(T)$ of $T$. We will however be a bit sloppy here and use the same notation for a bundle and the space of its sections.

[^14]:    ${ }^{15}$ In this section we use a more abstract notation, viewing tensors as maps between the appropriate sets. For instance $g J_{ \pm}$corresponds to $g_{a c} J_{ \pm b}^{c}$ in the rest of the text (apart from section 3.4). A good check for the validity of expressions is thus that lower indices should always be contracted with upper indices when recovering the index structure.

[^15]:    ${ }^{16}$ In the absence of $H$, this reduces to the existence of a closed two-form on $\mathcal{N}$, which is the magnetic field strength.

